# On the Relationship between Higher-Order Recursion Schemes and Higher-Order Fixpoint Logic 

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#### Abstract

We study the relationship between two kinds of higher-order extensions of model checking: HORS model checking, where models are extended to higher-order recursion schemes, and HFL model checking, where the logic is extended to higher-order modal fixpoint logic. These extensions have been independently studied until recently, and the former has been applied to higher-order program verification, while the latter has been applied to assume-guarantee reasoning and process equivalence checking. We show that there exist (arguably) natural reductions between the two problems. To prove the correctness of the translation from HORS to HFL model checking, we establish a type-based characterization of HFL model checking, which should be of independent interest. The results reveal a close relationship between the two problems, enabling cross-fertilization of the two research threads.


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## 1. Introduction

Inspired by the great success of finite state model checking [4], two kinds of its higher-order extensions have been studied recently. One is model checking of higher-order recursion schemes (HORS model checking, for short) [8, 12, 24], which asks, given a higher-order recursion scheme $\mathcal{G}$ (which is a kind of a tree grammar) and a formula $\varphi$ of the modal $\mu$-calculus (or equivalently, an alternating parity tree automaton), whether the tree generated by $\mathcal{G}$ satisfies $\varphi$. The other is higher-order modal fixpoint logic model checking of finite state systems (HFL model checking, for short) [33], which asks, given a finite state system $\mathcal{L}$ and a formula $\varphi$ of the higher-order modal fixpoint logic (which is a higher-order extension of the modal $\mu$-calculus), whether $\mathcal{L}$ satisfies $\varphi$. Thus, in HORS model checking, systems to be verified are higher-order, whereas in HFL model checking, properties to be checked are higher-order. HORS model checking has recently been successfully applied to verification of higher-order programs [9, 16-18, 22, 25, 32, 34]. HFL model checking has been applied to assume-guarantee reasoning [33] and process equivalence checking [19]. In general, HORS model checking is useful for pre-
cisely modeling and verifying certain infinite state systems, whereas HFL model checking is useful for checking non-regular properties of systems that cannot be expressed in ordinary modal logics such as LTL, CTL, and modal $\mu$-calculus.

Unfortunately, the two problems (i.e., HORS/HFL model checking) have been studied independently by different research communities, and little has been known on their relationship. Interestingly, both problems are $k$-EXPTIME complete, where $k$ is the largest type-theoretic order of functions used in HORS or HFL formulas. Thus, there should exist translations between order- $k$ HORS model checking problems and order- $k$ HFL model checking, but no direct (i.e., without going via Turing machines) translations were known.

In the present paper, we present direct, mutual translations between the HORS and HFL model checking problems. Interestingly, the roles of systems and properties are switched by the translations; in the HORS-to-HFL translation, a HORS (which is a description of a system to be verified) is translated to an HFL formula, and an automaton (which is a description of a property to be checked) is translated to a transition system, whereas in the converse translation, an HFL formula is translated to a HORS and a transition system is translated to an automaton. The translations are non-trivial. For the HORS-to-HFL translation, we have to replace the parity acceptance condition on the tree generated by HORS with proper alternation of least and greatest fixpoint operators of HFL. For the converse translation, we have to emulate the calculation of least and greatest fixpoint operators by HORS, which requires a tricky encoding of numbers.

The correctness of the HORS-to-HFL translation is also nontrivial. ${ }^{1}$ To this end, we provide a type-based characterization of HFL model checking, so that an HFL formula is typable in the type system parameterized by a finite transition system if and only if the transition system satisfies the formula. We then prove that a HORS is typable in (a variation of) Kobayashi and Ong's type system for characterizing the HORS model checking if and only if the corresponding HFL formula is typable in the aforementioned type system. Thus, the correctness of the HORS-to-HFL formula follows from that of Kobayashi and Ong's type system.

The type-based characterization of HFL model checking mentioned above should be of independent interest. A type-based characterization of HORS model checking is well established $[12,13]$ and has been used for studies of practical algorithms $[3,10,11,23,26]$, parameterized complexity [13, 14], decidability proofs [13, 31], etc. of HORS model checking. Our type-based characterization of HFL model checking is similar to (and actually simpler than) that for

[^0]HORS model checking. Thus, the type-based characterization clarifies the similarity and difference of HORS/HFL model checking. We also expect that the type-based approach to HFL will allow us to develop practical algorithms for HFL model checking, following the success of the corresponding approach to HORS model checking.

The rest of the paper is structured as follows. Section 2 reviews the definitions of HORS/HFL model checking problems. Section 3 presents a translation from HORS model checking to HFL model checking. Section 4 provides a type-based characterization of HFL model checking, and Section 5 uses it to prove the correctness of the translation of Section 3. Section 6 presents a translation from HFL model checking to HORS model checking, and proves its correctness. Section 7 discusses related work and Section 8 concludes the paper. Proofs omitted in the main text are found in Appendix.

## 2. Preliminaries

In this section, we first recall, in Section 2.1, the standard definitions of (infinite) trees, parity games and tree automata (that are required for defining HORS and HFL), and then review the definitions of higher-order recursion schemes (HORS) and higher-order modal fixpoint logic (HFL), and model checking problems on them in Sections 2.2 and 2.3.

### 2.1 Trees, Parity Games, and Alternating Parity Tree Automata

Let $\mathbb{N}_{+}$be the set of positive integers. Given a set $L$, an $L$-labeled tree T is a partial map from $\mathbb{N}_{+}^{*}$ to $L$ such that $\forall \pi \in \mathbb{N}_{+}^{*} . \forall i \in$ $\mathbb{N}_{+} \cdot \pi \cdot i \in \operatorname{dom}(T) \Longrightarrow\{\pi, \pi \cdot 1, \ldots \pi \cdot(i-1)\} \subseteq \operatorname{dom}(T)$. An element of $\operatorname{dom}(T)$ is called a node. For $n, n^{\prime} \in \operatorname{dom}(T), n^{\prime}$ is a child of $n$ if $n$ is the longest strict prefix of $n^{\prime}$.

A ranked alphabet $\Sigma$ is a map from a finite set of symbols to the set of non-negative integers, called arities. A $\Sigma$-labeled tree $T$ is a ranked tree if for every node $n \in \operatorname{dom}(T)$, the number of children of $n$ is $\Sigma(T(n))$.

A parity game is a two player game played by Player and Opponent and is defined by a tuple $\mathbf{G}=\left(V_{\forall}, V_{\exists}, v_{\text {init }}, E, \Omega\right)$, where $V_{\forall}, V_{\exists}$ are disjoint sets of positions, $v_{\text {init }} \in V_{\forall} \cup V_{\exists}$ is the initial position, $E \subseteq\left(V_{\forall} \cup V_{\exists}\right)^{2}$ is a set of moves, and $\Omega: V_{\forall} \cup V_{\exists} \rightarrow\{0, \ldots, p-1\}$ assigns to each position a priority. Positions in $V_{\exists}$ are called Player's positions, and positions in $V_{\forall}$ are called Opponent's positions.

A play is a finite or infinite sequence of positions $v_{0}, v_{1}, \ldots$ such that $v_{0}=v_{\text {init }}$ and $\left(v_{i}, v_{i+1}\right) \in E$ for all $i \geq 0$. The play is won by Player if either it is finite and the last position $v_{n} \in V_{\forall}$ is an Opponent's position such that $v_{n} E\left(=\left\{v \mid\left(v_{n}, v\right) \in E\right\}\right)=\emptyset$, or the play is infinite and the largest priority occurring infinitely often (i.e., $\left.\lim \sup _{i \rightarrow \infty} \Omega\left(v_{i}\right)\right)$ is even. A memoryless strategy for Player is $W \subseteq E$ such that $v W=v E$ for all $v \in V_{\forall}$ (Opponent's moves remain unchanged), and for all $v \in V_{\exists}$, there is at most one $v^{\prime}$ such that $\left(v, v^{\prime}\right) \in W$ (Player's moves are uniquely determined by the current position); it is a winning strategy for Player if all plays in the game $\left(V_{\forall}, V_{\exists}, v_{\text {init }}, E \cap W, \Omega\right)$ are won by Player.

Given a finite set $X$, the set $\mathrm{B}^{+}(X)$ of positive Boolean formulas over $X$ is defined by

$$
\mathrm{B}^{+}(X) \ni f::=\mathrm{tt}|\mathrm{ff}| x\left|f_{1} \vee f_{2}\right| f_{1} \wedge f_{2},
$$

where $x$ ranges over $X$.
Definition 1 (alternating parity tree automata). An alternating parity tree automaton (APT) is a quintuple $\mathcal{A}=\left(Q, \Sigma, \delta, q_{\text {init }}, \Omega\right)$ such that:

- $Q$ is a finite set of states with a distinguished initial state $q_{\text {init }} \in Q$.
- $\Sigma$ is a ranked alphabet.
- $\delta: Q \times \Sigma \rightarrow \mathrm{B}^{+}(\{1, \ldots, m\} \times Q)$ is a transition function, where $m$ is the largest arity of symbols in $\operatorname{dom}(\Sigma)$.
- $\Omega: Q \rightarrow\{0, \ldots, p-1\}$ assigns a priority to each state.

Given an APT $\mathcal{A}$ and a $\Sigma$-labeled ranked tree $T$, the acceptance game $\mathbf{G}(T, \mathcal{A})=\left(V_{\forall}, V_{\exists}, v_{\text {init }}, E, \Omega\right)$ is the parity game defined by $V_{\forall} \cup V_{\exists}:=\{(n, f) \mid n \in \operatorname{dom}(T), f$ is a subformula of $\delta(q, a)$ for some $(q, a) \in Q \times \operatorname{dom}(\Sigma)\}$, with $(n, f) \in V_{\forall}$ iff $f$ is a conjunction or $\mathrm{tt}, v_{\text {init }}:=\left(\epsilon, \delta\left(q_{\text {init }}, T(\epsilon)\right)\right)$, $E:=\left\{\left(\left(n, f_{1} * f_{2}\right),\left(n, f_{i}\right)\right) \mid n \in \operatorname{dom}(T), i \in\{1,2\}, * \in\right.$ $\{\vee, \wedge\}\} \cup\{((n,(i, q)),(n . i, \delta(q, T(n . i)))) \mid n, n . i \in \operatorname{dom}(T)\}$, $\Omega(n,(i, q))=\Omega(q)$, and $\Omega\left(n, f \vee f^{\prime}\right)=\Omega\left(n, f \wedge f^{\prime}\right)=0$. The language of $\mathcal{A}$, written $L(\mathcal{A})$, is the set of trees $T$ such that Player has a winning strategy for $\mathbf{G}(T, \mathcal{A})$.

Intuitively, a position $(n, f)$ of the game above represents a state where Player tries to prove that the node $n$ satisfies $f$, and Opponent tries to disprove it. If $f$ is a disjunction $f_{1} \vee f_{2}$, Player picks $i$ and tries to show that the node $n$ satisfies $f_{i}$. If $f$ is a conjunction $f_{1} \wedge f_{2}$, Opponent picks $i$ and tries to disprove that the node $n$ satisfies $f_{i}$. If $f=(i, q)$, then Player tries to show that the child $n . i$ satisfies $\delta(q, T(n . i))$ (i.e., is accepted from $q$ by the automaton). When a play continues indefinitely, Player wins iff the largest priority of states visited infinitely often is even.
Example 1. Consider the APT $\mathcal{A}_{0}=\left(\left\{q_{0}, q_{1}\right\}, \Sigma, \delta, q_{0}, \Omega\right)$, where:

$$
\begin{aligned}
& \Sigma=\{a \mapsto 2, b \mapsto 1, c \mapsto 0\} \\
& \delta\left(q_{i}, a\right)=\left(1, q_{0}\right) \wedge\left(2, q_{0}\right) \quad \delta\left(q_{i}, b\right)=\left(1, q_{1}\right) \quad \delta\left(q_{i}, c\right)=\mathrm{tt} \\
& \Omega\left(q_{0}\right)=1 \quad \Omega\left(q_{1}\right)=2
\end{aligned}
$$

Let $T$ be the tree where $\operatorname{dom}(T)=(2.1)^{*} \cup(2.1)^{*} .1 \cup(2.1)^{*} .2$, $T(n)=a$ if $n \in(2.1)^{*}, T(n)=c$ if $n \in(2.1)^{*} .1$, and $T(n)=b$ if $n \in(2.1)^{*} .2$. (Thus, $T$ is the regular infinite tree defined by $T=a c(b T)$. Let $D$ be $\operatorname{dom}(T)$. The acceptance game $\mathbf{G}\left(T, \mathcal{A}_{0}\right)$ is $\left(V_{\forall}, V_{\exists}, v_{\text {init }}, E, \Omega^{\prime}\right)$, where:

$$
\begin{aligned}
& V_{\forall}=\left\{\left(n,\left(1, q_{0}\right) \wedge\left(2, q_{0}\right)\right) \mid n \in D\right\} \cup\{(n, \mathrm{tt}) \mid n \in D\} \\
& V_{\exists}=\left\{(n, f) \mid n \in D, f \in\left\{\left(1, q_{0}\right),\left(2, q_{0}\right),\left(1, q_{1}\right)\right\}\right\} \\
& v_{\text {init }}=\left(\epsilon,\left(1, q_{0}\right) \wedge\left(2, q_{0}\right)\right) \\
& E=\left\{\left(\left(n,\left(1, q_{0}\right) \wedge\left(2, q_{0}\right)\right),\left(n,\left(i, q_{0}\right)\right)\right) \mid n \in D, i \in\{1,2\}\right\} \\
& \cup\left\{\left(\left(n,\left(1, q_{i}\right)\right),\left(n .1,\left(1, q_{0}\right) \wedge\left(2, q_{0}\right)\right)\right) \mid\right. \\
& \cup\left\{\left(\left(n \in\left(2, q_{i}\right)\right),\left(n .2,\left(1, q_{1}\right)\right)\right) \mid n \in(2.1)^{*} \cdot 2, i \in\{0,1\}\right\} \\
& \cup\left\{(2.1)^{*}, i \in\{0,1\}\right\} \\
& \cup\left\{\left(\left(n,\left(1, q_{i}\right)\right),(n .1, \mathrm{tt})\right) \mid n \in(2.1)^{*}, i \in\{0,1\}\right\} \\
& \Omega^{\prime}\left(n,\left(i, q_{j}\right)\right)=j+1 \text { for } n \in D, j \in\{0,1\}, \text { and } i \in\{1,2\} \\
& \Omega^{\prime}(n, f)=0 \text { for } n \in D, f \in\left\{\mathrm{tt},\left(1, q_{0}\right) \wedge\left(2, q_{0}\right)\right\} .
\end{aligned}
$$

$E$ itself is a winning strategy for $\mathbf{G}\left(T, \mathcal{A}_{0}\right)$; so, $T$ is accepted by $\mathcal{A}_{0}$. In general, a tree is accepted by $\mathcal{A}_{0}$ if and only if every infinite path of the tree contains infinitely many occurrences of $b$.
Remark 1. The acceptance of a tree by an APT can also be understood as follows, without using parity games. Let $\mathcal{A}=$ $\left(Q, \Sigma, \delta, q_{\text {init }}, \Omega\right)$ be an APT. The automaton has subformulas of $\delta(q, a)$ as "intermediate" states. Given a tree $T, \mathcal{A}$ runs a thread for reading the root with the initial state $q_{i n i t}$. Whenever a thread visits a node labeled with a at state $q$, it transits to an intermediate state $\delta(q, a)$. A thread in an intermediate state $f$ performs the following actions, depending on the shape of $f$.

- Case $f=f_{1} \wedge f_{2}$ : the thread splits into two threads with states $f_{1}$ and $f_{2}$.
- Case $f=f_{1} \vee f_{2}$ : the thread moves to either state $f_{1}$ or $f_{2}$.
- Case $f=(i, q)$ : the thread visits the $i$-th child of the current node with state $q$.
- Case $f=\mathrm{tt}$ : the thread terminates successfully.
- Case $f=\mathrm{ff}$ : the thread fails.

An APT $\mathcal{A}$ accepts a tree $T$ if there is a run in which no thread fails, and for every non-terminating thread, the largest priority of states visited infinitely often is even.

A labeled transition system (LTS) $\mathcal{L}$ is a quadruple $(U, A, \longrightarrow$, $s_{\text {init }}$ ), where $U$ is a finite set of states, $A$ is a finite set of actions, $\longrightarrow \subseteq U \times A \times U$ is a transition relation, and $s_{\text {init }}$ is the initial state. We write $s \xrightarrow{a} s^{\prime}$ when $\left(s, a, s^{\prime}\right) \in \longrightarrow$.

### 2.2 Model Checking of HORS

In this section, we review the definition of higher-order recursion schemes (HORS) and the model checking problem on them [24]. A HORS is a simply-typed, higher-order tree grammar for generating a labeled tree, and the model checking problem on it asks whether the tree generated by a given HORS satisfies a given property (expressed in terms of an alternating tree automaton or a modal $\mu$-calculus formula). When a tree is viewed as a transition system (where a node is regarded as a state and an edge as a transition), a HORS is considered a (possibly infinite) transition system. The trees generated by order-0 HORS's are regular, which correspond to finite state transition systems, whereas the trees generated by order-1 HORS's are those generated by pushdown systems. In that sense, the HORS model checking may be considered a strict extension of finite state model checking and pushdown model checking. Yet, the model checking problem remains decidable [24].

We first define types and terms. The set of simple types, ranged over by $\kappa$, is defined by:

$$
\kappa::=\star \mid \kappa_{1} \rightarrow \kappa_{2}
$$

The base type $\star$ is used as the type of trees below. The order of a type $\kappa$ is defined by: $\operatorname{ord}(\star)=0$ and $\operatorname{ord}\left(\kappa_{1} \rightarrow \kappa_{2}\right)=$ $\max \left(\operatorname{ord}\left(\kappa_{1}\right)+1, \operatorname{ord}\left(\kappa_{2}\right)\right)$. The set of (simply-typed) $\lambda$-terms, ranged over by $e$, is defined by:

$$
e::=x\left|e_{1} e_{2}\right| \lambda x: \kappa . e .
$$

A $\lambda$-term that does not contain $\lambda$ is called an applicative term. We often omit the type annotation and just write $\lambda x$.e for $\lambda x: \kappa . e$. As usual, the type judgment relation $\mathcal{K} \vdash e: \kappa$, where $\mathcal{K}$ is a map ${ }^{2}$ from a finite set of variables to the set of simple types, is defined as the least relation closed under the following rules:

$$
\begin{gathered}
\overline{\mathcal{K}, x: \kappa \vdash x: \kappa} \frac{\mathcal{K}, x: \kappa_{1} \vdash e: \kappa_{2}}{\mathcal{K} \vdash \lambda x: \kappa_{1} \cdot e: \kappa_{1} \rightarrow \kappa_{2}} \\
\frac{\mathcal{K} \vdash e_{0}: \kappa_{1} \rightarrow \kappa_{2} \quad \mathcal{K} \vdash e_{1}: \kappa_{1}}{\mathcal{K} \vdash e_{0} e_{1}: \kappa_{2}}
\end{gathered}
$$

Definition 2 (HORS). A higher-order recursion scheme (HORS, for short) $\mathcal{G}$ is a quadruple $(\Sigma, \mathcal{N}, \mathcal{R}, S)$, where:

- $\Sigma$ is a ranked alphabet. The elements of $\Sigma$ are called terminals.
- $\mathcal{N}$ is a map from a finite set of symbols (called non-terminals) to the set of simple types.
- $\mathcal{R}$ is a map from the set of non-terminals to the set of $\lambda$ terms (where both terminals and non-terminals are treated as variables). If $\mathcal{N}(A)=\kappa_{1} \rightarrow \cdots \rightarrow \kappa_{\ell} \rightarrow \star$, then $\mathcal{R}(A)$ must be of the form $\lambda x_{1}: \kappa_{1} \cdots \lambda x_{\ell}: \kappa_{\ell} . e$, where $e$ is an applicative term such that $\Sigma^{!} \cup \mathcal{N}, x_{1}: \kappa_{1}, \ldots, x_{\ell}: \kappa_{\ell} \vdash e: \star$. Here, $\Sigma^{!}$ denotes:

$$
\{a: \underbrace{\star \rightarrow \cdots \rightarrow \star}_{\Sigma(a)} \rightarrow \star \mid a \in \operatorname{dom}(\Sigma)\} .
$$

- $S$ is a non-terminal such that $\mathcal{N}(S)=\star$.

[^1]

Figure 1. The tree generated by $\mathcal{G}_{0}$ in Example 2.

The order of a HORS is $\max (\{\operatorname{ord}(\mathcal{N}(A)) \mid A \in \operatorname{dom}(\mathcal{N})\})$. The rewriting relation $e \longrightarrow \mathcal{G} e^{\prime}$ is the least relation closed under the following rules:

- $A e_{1} \ldots e_{\ell} \longrightarrow \mathcal{G}\left[e_{1} / x_{1}, \ldots, e_{\ell} / x_{\ell}\right] e$ if $\mathcal{R}(A)=\lambda x_{1}:$ $\kappa_{1} \cdots \lambda x_{\ell}: \kappa_{\ell} . e$.
- $a e_{1} \cdots e_{i} \cdots e_{\ell} \longrightarrow_{\mathcal{G}}$ a $e_{1} \cdots e_{i}^{\prime} \cdots, e_{\ell}$ if $e_{i} \longrightarrow_{\mathcal{G}} e_{i}^{\prime}$ and $\Sigma(a)=\ell$.

We often represent $\mathcal{R}$ in the form of rewriting rules, writing $A x_{1} \cdots x_{\ell} \rightarrow e$ for $\mathcal{R}(A)=\lambda x_{1}: \kappa_{1} \cdots \lambda x_{\ell}: \kappa_{\ell} . e$.

The tree generated by $\mathcal{G}$ is the one obtained from $S$ by (possibly) infinite rewriting. Formally, it is defined as follows.

Definition $3\left(T_{\mathcal{G}}\right)$. For an applicative term e of type $\star$, the $(\Sigma \cup$ $\{\perp \mapsto 0\}$ )-labeled tree $e^{\perp}$ is defined by:

$$
\left(a e_{1} \cdots e_{k}\right)^{\perp}=a e_{1}^{\perp} \cdots e_{k}^{\perp} \quad\left(A e_{1} \cdots e_{k}\right)^{\perp}=\perp
$$

We define the relation $\sqsubseteq$ on trees by: $T_{1} \sqsubseteq T_{2}$ iff $\operatorname{dom}\left(T_{1}\right) \subseteq$ $\operatorname{dom}\left(T_{2}\right)$ and for every $n \in \operatorname{dom}\left(T_{1}\right), T_{1}(n)=\perp$ or $T_{1}(n)=$ $T_{2}(n)$. The tree generated by $\mathcal{G}$, written $T_{\mathcal{G}}$, is $\bigsqcup\left\{e^{\perp} \mid S \longrightarrow \longrightarrow_{\mathcal{G}}^{*} e\right\}$, where $\bigsqcup U$ denotes the least upper bound of the trees in $U$ with respect to $\sqsubseteq^{3}{ }^{3}$
Example 2. Consider the HORS $\mathcal{G}_{0}=(\{a \mapsto 2, b \mapsto 1, c \mapsto$ $0\}, \mathcal{N}, \mathcal{R}, S)$, where $\mathcal{N}=\{S: \star, F:(\star \rightarrow \star) \rightarrow \star, B:(\star \rightarrow$ $\star) \rightarrow \star \rightarrow \star\}$, and $\mathcal{R}$ consists of the following rewriting rules:

$$
S \rightarrow F b \quad F g \rightarrow a c(g(F(B b))) \quad B g x \rightarrow b(g x)
$$

$S$ is reduced as follows:

$$
\begin{aligned}
& S \longrightarrow F b \longrightarrow a c(b(F(B b))) \longrightarrow a c(b(a c(B b(F(B(B b)))))) \\
& \longrightarrow a c(b(a c(b(b(F(B(B b)))))) \longrightarrow \cdots .
\end{aligned}
$$

The tree generated by $\mathcal{G}_{0}$ (i.e., $T_{\mathcal{G}_{0}}$ ) is shown in Figure 1, where $b^{i}$ denotes $i$ repetitions of $b$.
Definition 4 (model checking of HORS). We write $\mathcal{G} \vDash \mathcal{A}$ if $T_{\mathcal{G}} \in L(\mathcal{A})$. The HORS model checking problem is the problem of deciding whether $\mathcal{G} \models \mathcal{A}$, given a HORS $\mathcal{G}$ and an alternating parity tree automaton $\mathcal{A}$.
Example 3. Consider the APT $\mathcal{A}_{0}$ in Example 1 and the HORS $\mathcal{G}_{0}$ in Example 2. Then, $\mathcal{G}_{0}=\mathcal{A}_{0}$ holds.
Theorem 5 (Ong [24]). The HORS model checking problem is $k$-EXPTIME complete for order- $k$ HORS.

As in [13, 24], in the rest of this paper, we assume that $T_{\mathcal{G}}$ does not contain $\perp$. Given $\mathcal{G}$ and $\mathcal{A}$, we can always transform them to $\mathcal{G}^{\prime}$ and $\mathcal{A}^{\prime}$ such that (i) $\mathcal{G} \models \mathcal{A}$ if and only if $\mathcal{G}^{\prime} \models \mathcal{A}^{\prime}$ and (ii) $T_{\mathcal{G}^{\prime}}$ does not contain $\perp$.

[^2]
### 2.3 HFL Model Checking

In this section we review Higher-Order Modal Fixpoint Logic [33] (HFL) and its model-checking problem. HFL is an extension of the modal $\mu$-calculus with higher-order recursive predicates; HFL formulas $\varphi$ and HFL types $\eta$ are defined by the following grammar

$$
\begin{aligned}
& \varphi::=\top|\perp| X\left|\varphi_{1} \vee \varphi_{2}\right| \varphi_{1} \wedge \varphi_{2}|\langle a\rangle \varphi|[a] \varphi \\
&\left|\mu X^{\eta} . \varphi\right| \nu X^{\eta} . \varphi|\lambda X: \eta \cdot \varphi| \varphi_{1} \varphi_{2} \\
& \eta:=\bullet \mid \eta_{1} \rightarrow \eta_{2}
\end{aligned}
$$

The syntax of the formulas except the last two components ( $\lambda$ abstractions and applications) is almost identical to that of the modal $\mu$-calculus; in particular, as in the modal $\mu$-calculus, we have the least and great fixpoint operators $\mu$ and $\nu$; the difference is that they can be over higher-order predicates (created by a $\lambda$-abstraction $\lambda X: \eta \cdot \varphi)$. In its original formulation [33], HFL includes negations. In our setting, these are disallowed for simplicity, which is not a restriction since any closed HFL formula can be transformed to an equivalent negation-free formula [20].

Each binder $(\mu, \nu, \lambda)$ is annotated with the type of the bound variable (we may sometimes omit this annotation when it is clear from the context). The type $\bullet$ describes propositions, and the type $\eta_{1} \rightarrow \eta_{2}$ describes functions from $\eta_{1}$ to $\eta_{2}$. The order of an HFL type $\eta$ is defined by: $\operatorname{ord}(\bullet)=0$ and $\operatorname{ord}\left(\eta_{1} \rightarrow \eta_{2}\right)=$ $\max \left(\operatorname{ord}\left(\eta_{1}\right)+1, \operatorname{ord}\left(\eta_{2}\right)\right)$. A type judgment relation is of the form $\mathcal{H} \vdash \varphi: \eta$, where $\mathcal{H}$ is a map from a finite set of variables to the set of HFL types. Type judgments are derived from the following rules.

$$
\begin{aligned}
& \overline{\mathcal{H} \vdash \top: \bullet} \quad \overline{\mathcal{H} \vdash \perp: \bullet} \quad \overline{\mathcal{H}, X: \eta \vdash X: \eta} \\
& \frac{\mathcal{H} \vdash \varphi: \bullet}{\mathcal{H} \vdash\langle a\rangle \varphi: \bullet} \quad \frac{\mathcal{H} \vdash \varphi: \bullet}{\mathcal{H} \vdash[a] \varphi: \bullet} \quad \frac{\mathcal{H} \vdash \varphi_{1}: \bullet}{\mathcal{H} \vdash \varphi_{1} \vee \varphi_{2}: \bullet} \\
& \frac{\mathcal{H} \vdash \varphi_{1}: \bullet \mathcal{H} \vdash \varphi_{2}: \bullet}{\mathcal{H} \vdash \varphi_{1} \wedge \varphi_{2}: \bullet} \quad \frac{\mathcal{H}, X: \eta \vdash \varphi: \eta}{\mathcal{H} \vdash \mu X^{\eta} \cdot \varphi: \eta} \\
& \frac{\mathcal{H}, X: \eta \vdash \varphi: \eta}{\mathcal{H} \vdash \nu X^{\eta} \cdot \varphi: \eta} \quad \frac{\mathcal{H}, X: \eta_{1} \vdash \varphi: \eta_{2}}{\mathcal{H} \vdash \lambda X: \eta_{1} \cdot \varphi: \eta_{1} \rightarrow \eta_{2}} \\
& \frac{\mathcal{H} \vdash \varphi_{1}: \eta_{2} \rightarrow \eta \quad \mathcal{H} \vdash \varphi_{2}: \eta_{2}}{\mathcal{H} \vdash \varphi_{1} \varphi_{2}: \eta}
\end{aligned}
$$

A closed formula $\varphi$ is well-typed and has type $\eta$ if the type judgment $\emptyset \vdash \varphi: \eta$ is derivable from the above rules. In the remainder, we always implicitly assume that all the (closed) formulas are well-typed.

The order of a formula $\varphi$ is the largest order of the type of a subformula occurring in $\varphi$. A formula is said to be a formula of the modal $\mu$-calculus if its order is 0 .

Let $\left(U, A, \longrightarrow, s_{\text {init }}\right)$ be a fixed LTS. The semantics of a formula of type $\eta$ is an object of the lattice $\left(D_{\eta}, \sqcup_{\eta}, \sqcap_{\eta}\right)$ defined by induction on $\eta$ : Define $D_{\bullet}=\mathcal{P}(U)$ as the complete lattice of sets of states, and if $\eta=\eta_{1} \rightarrow \eta_{2}$ then define $D_{\eta}=D_{\eta_{1}} \rightarrow D_{\eta_{2}}$ as the complete lattice of monotone functions from $D_{\eta_{1}}$ to $D_{\eta_{2}}$. For every type $\eta$ and function $f \in D_{\eta \rightarrow \eta}, f$ has a unique least fixpoint $\operatorname{LFP}_{\eta}(f) \in D_{\eta}$ and a unique greatest fixpoint $\operatorname{GFP}_{\eta}(f) \in D_{\eta}$, respectively defined as $\Pi\left\{x \in D_{\eta} \mid f(x) \sqsubseteq x\right\}$ and $\bigsqcup\left\{x \in D_{\eta} \mid\right.$ $x \sqsubseteq f(x)\}$.

The interpretation $\llbracket \mathcal{H} \rrbracket$ of a type environment is the set of maps $\rho$ such that $\rho(X) \in D_{\mathcal{H}(X)}$ for each $X \in \operatorname{dom}(\rho)$. The interpretation
$\llbracket \mathcal{H} \vdash \varphi: \eta \rrbracket$ is a map from $\llbracket \mathcal{H} \rrbracket$ to $D_{\eta}$ defined by induction on $\varphi$ as follows:

$$
\begin{aligned}
& \llbracket \mathcal{H} \vdash \top: \bullet \rrbracket(\rho)=U \\
& \llbracket \mathcal{H} \vdash \perp: \bullet \rrbracket(\rho)=\emptyset \\
& \left.\begin{array}{l}
\mathcal{H}
\end{array}\right]: \eta \vdash X: \eta \rrbracket(\rho)=\rho(X) \\
& \llbracket \mathcal{H} \vdash\langle a\rangle \varphi: \bullet \rrbracket(\rho)=\left\{s \mid \exists s^{\prime} \in \llbracket \mathcal{H} \vdash \varphi: \bullet \rrbracket(\rho) . s \xrightarrow{a} s^{\prime}\right\} \\
& \llbracket \mathcal{H} \vdash[a] \varphi: \bullet \rrbracket(\rho) \\
& \quad=\left\{s \mid \forall s^{\prime} \in S .\left(s \xrightarrow{a} s^{\prime} \text { implies } s^{\prime} \in \llbracket \mathcal{H} \vdash \varphi: \bullet \rrbracket(\rho)\right)\right\} \\
& \llbracket \mathcal{H} \vdash \varphi_{1} \vee \varphi_{2}: \bullet \rrbracket(\rho)=\llbracket \mathcal{H} \vdash \varphi_{1}: \bullet \rrbracket(\rho) \cup \llbracket \mathcal{H} \vdash \varphi_{2}: \bullet \rrbracket(\rho) \\
& \llbracket \mathcal{H} \vdash \varphi_{1} \wedge \varphi_{2}: \bullet \rrbracket(\rho)=\llbracket \mathcal{H} \vdash \varphi_{1}: \bullet \rrbracket(\rho) \cap \llbracket \mathcal{H} \vdash \varphi_{2}: \bullet \rrbracket(\rho) \\
& \llbracket \mathcal{H} \vdash \mu X^{\eta} \cdot \varphi: \eta \rrbracket(\rho)=\mathrm{LFP}(\llbracket \mathcal{H} \vdash \lambda X: \eta \cdot \varphi \rrbracket(\rho)) \\
& \llbracket \mathcal{H} \vdash \nu X^{\eta} \cdot \varphi: \eta \rrbracket(\rho)=\operatorname{GFP}(\llbracket \mathcal{H} \vdash \lambda X: \eta \cdot \varphi \rrbracket(\rho)) \\
& \llbracket \mathcal{H} \vdash \lambda X: \eta_{1} \cdot \varphi: \eta_{1} \rightarrow \eta_{2} \rrbracket(\rho) \\
& \quad=\left\{V \mapsto \llbracket \mathcal{H}, X: \eta_{1} \vdash \varphi: \eta_{2} \rrbracket(v[X \mapsto V]) \mid V \in D_{\eta_{1}}\right\} \\
& \llbracket \mathcal{H} \vdash \varphi_{1} \varphi_{2}: \eta \rrbracket(\rho) \\
& \quad=\llbracket \mathcal{H} \vdash \varphi_{1}: \eta^{\prime} \rightarrow \eta \rrbracket(\rho)\left(\llbracket \mathcal{H} \vdash \varphi_{2}: \eta^{\prime} \rrbracket(\rho)\right)
\end{aligned}
$$

Note that, in the last clause, $\eta^{\prime}$ is uniquely determined by $\mathcal{H}$ and $\varphi_{2}$.
We often omit $\mathcal{H} \vdash \cdot: \eta$ and just write $\llbracket \varphi \rrbracket$ for $\llbracket \mathcal{H} \vdash \varphi: \eta \rrbracket$, with the understanding that each subformula is implicitly annotated with its type. For a closed formula $\varphi$ of type $\bullet$, we simply write $\llbracket \varphi \rrbracket$ for $\llbracket \emptyset \vdash \varphi: \bullet \rrbracket\left(\rho_{\emptyset}\right)$, where $\rho_{\emptyset}$ is the empty interpretation. We write $\mathcal{L} \models \varphi$ if $s_{\text {init }} \in \llbracket \varphi \rrbracket$.

We now review the definition of HFL model checking and the decidability/complexity result.
Definition 6 (HFL model checking). The HFL model checking problem is the problem of deciding whether $\mathcal{L} \models \varphi$, given a closed HFL formula $\varphi$ of type $\bullet$ and a labeled transition system $\mathcal{L}$.
Theorem 7 ([2,33]). The HFL model checking problem is decidable [33]. It is $k$-EXPTIME complete for order-k HFL formulas [2].
Example 4. Consider the following HFL formula $\varphi_{0}$ :

$$
\begin{aligned}
& \left(\nu F^{(\bullet \rightarrow \bullet) \rightarrow \bullet} . \lambda X: \bullet \rightarrow \bullet \bullet\langle a\rangle(X(F(\lambda Y: \bullet \cdot\langle b\rangle(X Y))))\right) \\
& \quad(\lambda Y: \bullet .\langle b\rangle Y) .
\end{aligned}
$$

It represents the property that there exists a transition sequence of the form: $a b a b^{2} a b^{3} a b^{4} \cdots$. In fact if we replace $F$ with
$\lambda X: \bullet \rightarrow \bullet\langle a\rangle(X(F(\lambda Y: \bullet .\langle b\rangle(X Y))))$ infinitely often and reduce the $\beta$-redexes, we obtain the formula:

$$
\langle a\rangle\langle b\rangle\langle a\rangle\langle b\rangle^{2}\langle a\rangle\langle b\rangle^{3}\langle a\rangle\langle b\rangle^{4} \cdots .
$$

Consider the LTS $\mathcal{L}_{0}=\left(\left\{s_{0}, s_{1}\right\},\{a, b\}, \longrightarrow, s_{0}\right)$, where $\longrightarrow$ is given by:

$$
s_{0} \xrightarrow{a} s_{1} \quad s_{1} \xrightarrow{b} s_{0} \quad s_{1} \xrightarrow{b} s_{1}
$$

Then we have $\mathcal{L}_{0} \models \varphi_{0}$.
Example 5. Consider the following formula $\varphi_{1}$ [19]:

$$
\mu E^{\bullet \rightarrow \bullet \bullet} . \lambda X: \bullet . \lambda Y: \bullet(X \wedge Y) \vee E(\langle a\rangle X)(\langle b\rangle Y)
$$

The formula $\varphi_{1} X Y$ means "there exists $n \geq 0$ such that $\langle a\rangle^{n} X$ and $\langle b\rangle^{n} Y$ holds. For example, $\varphi_{2}:=\varphi_{1} \varphi_{0}([b] \perp)$ (where $\varphi_{0}$ is the one given in Example 4) means that there exists $n \geq 0$ such that a transition sequence of the form: $a b a b^{2} a b^{3} a b^{4} \cdots$ is possible after $n$ steps of a-transitions, and no b-transition is possible after $n$ steps of b-transitions. The LTS $\mathcal{L}_{0}$ in Example 4 satisfies $\varphi_{2}$, since the property is satisfied for $n=0$.

For discussing transformations between HFL and HORS, it is convenient to express HFL formulas in the form of systems of equations, called HES.
Definition 8 (HES). A hierarchical equation system (HES) is a sequence of equations of the form $X_{1}^{\eta_{1}}={ }_{\alpha_{1}} \varphi_{1} ; \cdots ; X_{n}^{\eta_{n}}={ }_{\alpha_{n}}$ $\varphi_{n}$. where each $\alpha_{i}$ is $\nu$ or $\mu$, and for each $i=1, \ldots, n, \varphi_{i}$ is a formula without fixpoint binders such that $X_{1}: \eta_{1} \ldots, X_{n}: \eta_{n} \vdash$ $\varphi_{i}: \eta_{i}$.

For an HES $\mathcal{E}=\left(X_{1}^{\eta_{1}}={ }_{\alpha_{1}} \varphi_{1} ; \cdots ; X_{n}^{\eta_{n}}={ }_{\alpha_{n}} \varphi_{n}\right)$, we write $\mathcal{E}\left(X_{i}\right)$ for $\varphi_{i}$. We often omit the type annotation $\eta_{i}$. The HFL formula denoted by $\mathcal{E}:=\left(X_{1}^{\eta_{1}}={ }_{\alpha_{1}} \varphi_{1} ; \cdots ; X_{n}^{\eta_{1}}={ }_{\alpha_{n}} \varphi_{n}\right)$ is defined inductively by:

$$
\begin{aligned}
& \operatorname{toHFL}\left(X^{\eta}={ }_{\alpha} \varphi\right)=\alpha X^{\eta} . \varphi \\
& \operatorname{toHFL}\left(\mathcal{E} ; X^{\eta}={ }_{\alpha} \varphi\right)=\operatorname{toHFL}\left(\left[\alpha X^{\eta} . \varphi / X\right] \mathcal{E}\right) .
\end{aligned}
$$

We write $\mathcal{L} \models \mathcal{E}$ if $\mathcal{L} \models \operatorname{toHFL}(\mathcal{E})$. We sometimes write $X y_{1} \cdots y_{k}={ }_{\alpha} \varphi$ for $X={ }_{\alpha} \lambda y_{1} \cdots \lambda y_{k} . \varphi$.
Example 6. The HFL formula $\varphi_{0}$ in Example 4 can be represented as the following HES.

$$
\begin{aligned}
& S={ }_{\nu} F(\lambda Y: \bullet .\langle b\rangle Y) ; \\
& F={ }_{\nu} \lambda X: \bullet \rightarrow \bullet \cdot\langle a\rangle(X(F(\lambda Y: \bullet \cdot\langle b\rangle(X Y)))) .
\end{aligned}
$$

We can also restrict HES so that $\lambda$ occurs only at the top-level. For example, the HES above can further be transformed to the following equivalent HES $\mathcal{E}_{0}$.

$$
\begin{aligned}
& S={ }_{\nu} F B ; \quad F={ }_{\nu} \lambda X: \bullet \rightarrow \bullet \cdot\langle a\rangle(X(F(G X))) ; \\
& G={ }_{\nu} \lambda X: \bullet \rightarrow \bullet . \lambda Y: \bullet \bullet\langle b\rangle(X Y) ; \quad B={ }_{\nu} \lambda Y: \bullet .\langle b\rangle Y .
\end{aligned}
$$

Since the equations for $S, G, B$ are not recursive, it does not matter whether they are annotated with $\mu$ or $\nu$.
Example 7. Consider the following HES $\mathcal{E}_{\perp}$ :

$$
S={ }_{\mu} X ; \quad Y={ }_{\nu} \lambda Z .\langle a\rangle(Z \wedge X) ; \quad X={ }_{\mu}\langle a\rangle(Y X) .
$$

Then $\mathcal{E}_{\perp}$ is unsatisfiable. This can be checked by making the following observations:

- toHFL $\left(\mathcal{E}_{\perp}\right)$ is the formula $\mu X .\langle a\rangle(\varphi X)$ where $\varphi$ is the $H F L$ formula $\nu Y . \lambda Z .\langle a\rangle\left(Z \wedge\left(\mu X^{\prime} .\langle a\rangle\left(Y X^{\prime}\right)\right)\right)$.
- since $\varphi Z$ implies $\langle a\rangle Z$, toHFL $\left(\mathcal{E}_{\perp}\right)$ implies $\mu X .\langle a\rangle\langle a\rangle X$, which is unsatisfiable.


## 3. From HORS to HFL Model Checking

We introduce a reduction from HORS model checking to HFL model checking. The reduction proceeds by exchanging the roles of the model and the specification:

- the alternating parity tree automaton $\mathcal{A}$ of an instance of a HORS model-checking problem is encoded as the labeled transition system $\mathcal{L}_{\mathcal{A}}$ of an instance of the HFL model-checking problem; and
- similarly, the HORS $\mathcal{G}$ is encoded as a HFL formula $\varphi_{\mathcal{G}}$.

Intuitively, $\mathcal{L}_{\mathcal{A}}$ represents the transitions that can be made by the automaton $\mathcal{A}$ (according to the behavior of $\mathcal{A}$ described in Remark 1), and the formula $\varphi_{\mathcal{G}}$ describes that $\mathcal{L}_{\mathcal{A}}$ has transitions corresponding to a successful run of $\mathcal{A}$ for the tree generated by $\mathcal{G}$. We now present these encodings; we prove their soundness in Section 5.

### 3.1 Tree Automata Encoded as LTS

Let us fix an APT $\mathcal{A}=\left(Q, \Sigma, \delta, q_{\text {init }}, \Omega\right)$ and construct the labeled transition system $\mathcal{L}_{\mathcal{A}}$ encoding it. Intuitively, the control graph of $\mathcal{A}$ becomes the LTS, but since the transition relation of $\mathcal{A}$ uses positive Boolean formulas, these must be encoded as states of the transition system. Formally, the set of states of $\mathcal{L}_{A}$ is $Q \cup Q_{f}$, where $Q_{f}:=\{f \mid f$ is a subformula of $\delta(q, a)$ for some $(q, a) \in Q \times \operatorname{dom}(\Sigma)\}$. The rest of the encoding makes sure that the transition relation of the automaton and the state priorities are represented by the labeling of the transitions. The set of labels of $\mathcal{L}_{A}$ is the set

$$
\begin{array}{ll} 
& \left\{a_{i} \mid a \in \operatorname{dom}(\Sigma), i \in\{0,1, \ldots, p-1\}\right\} \\
\cup & \{d \mid d \in\{1, \ldots, m\}\} \\
\cup & \{\text { and, or, true }\}
\end{array}
$$



Figure 2. The LTS $\mathcal{L}_{\mathcal{A}_{0}}$ associated to the APT $\mathcal{A}_{0}$ of Example 1, where $f=\left(1, q_{0}\right) \wedge\left(2, q_{0}\right)$, and $q_{0}$ is the initial state.
where $p-1$ is the largest priority, and $m$ is the largest arity. The initial state $q_{\text {init }}$ of the automaton is also the initial state of the transition system, and the transition relation is defined by

$$
\begin{array}{ll}
q \xrightarrow{a_{\Omega(q)}} \delta(q, a) & (d, q) \xrightarrow{d} q \\
f_{1} \wedge f_{2} \xrightarrow{\text { and }} f_{i} & f_{1} \vee f_{2} \xrightarrow{\text { or }} f_{i} \quad \mathrm{tt} \xrightarrow{\text { true }} \mathrm{tt}
\end{array}
$$

for $q \in Q, a \in \operatorname{dom}(\Sigma)$, and $i=1,2$. Note how the priority of a state $q$ is determined by the index $i$ on the label of any transition $q \xrightarrow{\mathrm{a}_{i}}$ starting at $q$. The positive Boolean formulas are represented by their syntax tree, with each leaf having an outgoing transition towards the automaton state associated to it.

Example 8. Let $\mathcal{A}_{0}$ be the APT of Example 1. The LTS $\mathcal{L}_{\mathcal{A}}$ encoding $\mathcal{A}_{0}$ is depicted on Figure 2.

### 3.2 The Case of Trivial Automata

In order to get a better intuition of the encoding of $\mathcal{G}$ into an HFL formula $\varphi_{\mathcal{G}}$, we first discuss the special case where the automaton $\mathcal{A}$ is a trivial tree automaton [1], i.e., an alternating parity tree automaton where all the states have priority 0 . This class of automata has been used to verify higher-order programs against safety properties [12].

As explained at the beginning of this section, $\varphi_{\mathcal{G}}$ expresses the property that the automaton (or, the corresponding LTS $\mathcal{L}_{\mathcal{A}}$ constructed above) has a successful run for the tree generated by $\mathcal{G}$. Let us first consider a special case, namely where $\mathcal{G}$ generates the finite tree $a c(b c)$. Then, since the initial state of the automaton should be able to accept $a$, the $\operatorname{LTS} \mathcal{L}_{\mathcal{A}}$ should have a transition $a_{0}$; hence $\varphi_{\mathcal{G}}$ should be of the form $\left\langle a_{0}\right\rangle \varphi_{1}$, where $\varphi_{1}$ describes the property that should be satisfied by the state $s=\delta\left(q_{\text {init }}, a\right)$. The formula $\varphi_{1}$ is not aware of the shape of $\delta\left(q_{\text {init }}, a\right)$, but knows that the state $s$ of the LTS after the $a$-transition is a positive Boolean formula. Thus, $\varphi_{1}$ asserts the following property:

- If $s=(1, q)$, i.e., if there is a $\xrightarrow{1}$-transition, then the next state (corresponding to $q$ ) should have transitions corresponding to an accepting run of $\mathcal{A}$ for the first child $c$.
- If $s=(2, q)$, i.e., if there is $\mathrm{a} \xrightarrow{2}$-transition, then the next state should have transitions corresponding to an accepting run of $\mathcal{A}$ for the second child $b c$.
- If $s=f_{1} \wedge f_{2}$, then any state after a $\xrightarrow{\text { and }}$-transition should satisfy $\varphi_{1}$ again.
- If $s=f_{1} \vee f_{2}$, then some state after a $\xrightarrow{\text { or }}$-transition should satisfy $\varphi_{1}$ again.
- If $s=\mathrm{tt}$, i.e., if there is a $\xrightarrow{\text { true }}$-transition, then there is no further requirement.

Thus, $\varphi_{1}$ can be described as
$\nu X .\langle 1\rangle \varphi_{c} \vee\langle 2\rangle \varphi_{b c} \vee(\langle$ and $\rangle \top \wedge[$ and $] X) \vee(\langle$ or $\rangle X) \vee\langle$ true $\rangle \top$,
where $\varphi_{c}$ and $\varphi_{b c}$ describe the properties that the current state has transitions corresponding to accepting runs for $c$ and $b c$ respectively, which can be defined by:

$$
\begin{aligned}
& \varphi_{c}:=\left\langle c_{0}\right\rangle \nu X .(\langle\text { and }\rangle \top \wedge[\text { and }] X) \vee(\langle\text { or }\rangle X) \vee\langle\text { true }\rangle \top \\
& \varphi_{b c}:=\left\langle b_{0}\right\rangle \nu X .\langle 1\rangle \varphi_{c} \vee(\langle\text { and }\rangle \top \wedge[\text { and }] X) \vee(\langle\text { or }\rangle X) \vee\langle\text { true }\rangle T .
\end{aligned}
$$

By preparing the following formula $L_{n}$ :

$$
\begin{gathered}
\nu X . \lambda y_{1}, \ldots, y_{n} . \bigvee_{j=1}^{n}\langle j\rangle y_{j} \vee\left(\langle\text { and }\rangle \top \wedge[\operatorname{and}]\left(X y_{1} \ldots y_{n}\right)\right) \\
\vee\langle\text { or }\rangle\left(X y_{1} \ldots y_{n}\right) \vee\langle\text { true }\rangle \top
\end{gathered}
$$

the formula $\varphi_{\mathcal{G}}$ can be simplified to:

$$
\left\langle a_{0}\right\rangle\left(L_{2}\left(\langle c\rangle L_{0}\right)\left(\left\langle b_{0}\right\rangle\left(L_{1}\left(\left\langle c_{0}\right\rangle L_{0}\right)\right)\right)\right) .
$$

In general, for a finite tree $T$, the formula $\varphi_{T}$ that describes the property "the LTS $\mathcal{L}_{\mathcal{A}}$ has transitions corresponding to a successful run of $\mathcal{A}$ that accepts $T^{\prime \prime}$, can be constructed inductively by:

$$
\varphi_{a T_{1} \cdots T_{\ell}}=\left\langle a_{0}\right\rangle\left(L_{\ell} \varphi_{T_{1}} \cdots \varphi_{T_{\ell}}\right)
$$

In other words, the translation from a tree $T$ to the corresponding formula works as a homomorphism that replaces each tree constructor $a$ of arity $\ell$ with $\lambda x_{1} \cdot \cdots \lambda x_{\ell} \cdot\left\langle a_{0}\right\rangle\left(L_{\ell} x_{1} \cdots x_{\ell}\right)$. Thus, we can naturally extend the translation to one from a HORS to a formula, as given below.

For a given HORS $\mathcal{G}=(\Sigma, \mathcal{N}, \mathcal{R}, S)$, let $\mathcal{E}_{\mathcal{G}}$ be the HES $A_{0}={ }_{\nu}\left(e_{0}\right)^{\dagger} ; \ldots ; A_{m}={ }_{\nu}\left(e_{m}\right)^{\dagger} ; \mathcal{E}_{\text {aux }}$ where (i) $\mathcal{E}_{\text {aux }}$ is the set of definitions for $L_{n}$ :

$$
\begin{aligned}
L_{n}={ }_{\nu} \quad \lambda y_{1}, \ldots, y_{n} . \\
\bigvee_{j=1}^{n}\langle j\rangle y_{j} \vee\left(\langle\text { and }\rangle \top \wedge[\text { and }]\left(L_{n} y_{1} \ldots y_{n}\right)\right) \\
\vee\langle\text { or }\rangle\left(L_{n} y_{1} \ldots y_{n}\right) \vee\langle\text { true }\rangle \top
\end{aligned}
$$

for $n \in\{1, \ldots, k\}$ with $k$ being the largest arity; (ii) $A_{0}, \ldots, A_{m}$ are the non-terminals of $\mathcal{G}$ with $S=A_{0}$; (iii) $e_{i}=\mathcal{R}\left(A_{i}\right)$; and (iv) $(e)^{\dagger}$ is defined by induction on $e$ as follows.

$$
\begin{aligned}
& (\lambda y: \kappa \cdot e)^{\dagger}=\lambda y:(\kappa)^{\dagger} \cdot(e)^{\dagger} \\
& \left(e_{1} e_{2}\right)^{\dagger}=\left(e_{1}\right)^{\dagger}\left(e_{2}\right)^{\dagger} \\
& (z)^{\dagger}=z \text { if } z \text { is either a non-terminal or a variable } \\
& (\mathrm{a})^{\dagger}=\lambda y_{1}: \bullet \cdots \lambda y_{\Sigma(\mathrm{a})}: \bullet \cdot\left\langle\mathrm{a}_{0}\right\rangle\left(L_{\Sigma(\mathrm{a})} y_{1} \ldots y_{\Sigma(\mathrm{a})}\right) \\
& (\star)^{\dagger}=\bullet \\
& \left(\kappa_{1} \rightarrow \kappa_{2}\right)^{\dagger}=\left(\kappa_{1}\right)^{\dagger} \rightarrow\left(\kappa_{2}\right)^{\dagger} .
\end{aligned}
$$

As in the case for the translation from trees to formulas, we just need to replace each tree constructor $a$ of arity $\ell$ with
$\lambda y_{1}, \ldots y_{\ell}$. $\left\langle\mathbf{a}_{0}\right\rangle\left(L_{\ell} y_{1} \ldots y_{\ell}\right)$.
Example 9. Consider the HORS of Example 2. Then its encoding as a HFL formula is defined by the following HES (notice that some $\beta$-reductions have been done to ease readability).

$$
\begin{array}{ll}
S={ }_{\nu} & F\left(\lambda x \cdot\left\langle\mathrm{~b}_{0}\right\rangle\left(L_{1} x\right)\right) ; \\
F={ }_{\nu} & \lambda g \cdot\left\langle\mathrm{a}_{0}\right\rangle\left(L_{2}\left(\left\langle\mathrm{c}_{0}\right\rangle L_{0}\right)\left(g\left(F\left(B\left(\lambda x \cdot\left\langle\mathrm{~b}_{0}\right\rangle\left(L_{1} x\right)\right)\right)\right)\right)\right) ; \\
B={ }_{\nu} & \lambda g \cdot \lambda x \cdot\left\langle\mathrm{~b}_{0}\right\rangle\left(L_{1}(g x)\right) ; \\
L_{2}={ }_{\nu} \ldots ; L_{1}={ }_{\nu} \cdots ; L_{0}={ }_{\nu} \ldots
\end{array}
$$

The following theorem states the correctness of the translation above. We omit the proof, since it is a special case of Theorem 10 given later.
Theorem 9. For any trivial automaton $\mathcal{A}$ and $\operatorname{HORS} \mathcal{G}, T_{\mathcal{G}} \in L(\mathcal{A})$ if and only if $\mathcal{L}_{\mathcal{A}}=\mathcal{E}_{\mathcal{G}}$.

### 3.3 The General Case

In the general case where $\mathcal{A}$ is an APT with priorities $\{0, \ldots, p-1\}$, we need to take into account the parity acceptance condition and it must be reflected somehow in the resulting HFL formula. Let us first examine the case of an order-0 HORS. Assume $\mathcal{G}$ is a HORS where all non-terminals are of type $\star$ and all rules are of the form
$A \rightarrow \mathrm{a} A_{1} \ldots A_{\Sigma(\mathrm{a})}$. For each $A$, we prepare $p$ fixpoint variables $A^{\sharp 0}, \ldots, A^{\sharp p-1}$, defined by

$$
A^{\sharp i}=\alpha_{\alpha_{i}} \bigvee_{i^{\prime}=0, \ldots, p-1}\left\langle\mathrm{a}_{i^{\prime}}\right\rangle\left(L_{\Sigma(\mathrm{a})} A_{1}^{\sharp i^{\prime}} \ldots A_{\Sigma(\mathrm{a})}^{\sharp i^{\prime}}\right),
$$

where $\alpha_{i}$ is $\nu$ if $i$ is even and $\mu$ otherwise. As in the case of trivial automata, $A^{\sharp i}$ expresses the property that the current state has transitions corresponding to a accepting run of $\mathcal{A}$ over the tree generated by $A$; in addition, $A^{\sharp i}$ remembers that the priority of the previous state is $i$ (this intuition will be refined later). The priority of the previous state of the automaton is recorded in the subscript of the transition label $\mathrm{a}_{i^{\prime}}$, hence the above definition of $A^{\sharp i}$. If a priority $i$ is visited infinitely often by the automaton, then a fixpoint variable of the form $A^{\sharp i}$ is unfolded infinitely often. Thus, by letting $\mathcal{E}_{\mathcal{G}}^{(p)}=\left(\mathcal{E}_{p-1} ; \ldots, \mathcal{E}_{0} ; \mathcal{E}_{a u x}\right)$ where $\mathcal{E}_{i}$ contains a declaration for $A^{\sharp i}$ of the above form and $\mathcal{E}_{\text {aux }}$ is as given in the previous section, we can guarantee that the largest priority visited by $\mathcal{A}$ is even if and only if the largest index of the fixpoint variables expanded infinitely often is even. We thus obtain $\mathcal{L}_{\mathcal{A}} \models \mathcal{E}_{\mathcal{G}}^{(p)}$ if and only if $T_{\mathcal{G}} \in L(\mathcal{A})$.

In the case of a HORS of an arbitrary order, each rule of the form $A \rightarrow C\left[A_{1}, \ldots, A_{k}\right]$ should be replaced by a fixpoint equation of the form:

$$
A^{\sharp i}={ }_{\alpha_{i}} C^{\prime}\left[A_{1}^{\sharp i i_{1}}, \ldots, A_{k}^{\sharp i i_{k}}\right],
$$

where each $i_{j}$ is the largest priority visited since the unfolding of $A$ before $A_{j}$ is unfolded. The main difficulty arises when $A_{j}$ occurs as an argument of another non-terminal, as in $A \rightarrow B A_{j}$. In this case, only $B$ knows the largest priority visited before $A_{j}$ is unfolded. Thus, we replicate the argument of $B$ and translate $B A_{j}$ to $B^{\sharp 0} A_{j}^{\sharp 0} \cdots A_{j}^{\sharp p-1}$; here, $B^{\sharp 0}$ is defined so that it calls the $i$-th argument $A_{j}^{\sharp i}$ when the largest priority visited before unfolding $A_{j}$ inside the body of $B$ is $i$.

Let us present now the general construction of the $\operatorname{HES} \mathcal{E}_{\mathcal{G}}^{(p)}$ encoding the HORS $\mathcal{G}$ for any alternating parity automaton with priorities in $\{0, \ldots, p-1\}$. It is defined by $\mathcal{E}_{\mathcal{G}}^{(p)}:=\mathcal{E}_{p-1} ; \ldots ; \mathcal{E}_{0} ; \mathcal{E}_{\text {aux }}$ where for each non-terminal $A$ and for each priority $i$, there is a definition $A^{\sharp i}={ }_{\alpha_{i}}(\mathcal{R}(A))^{\sharp 0}$ in $\mathcal{E}_{i}$, with (. $)^{\sharp(.)}$ to be defined soon, and again with $\alpha_{i}=\nu$ if $i$ is even and $\mu$ otherwise.

For any term $e$ and for any priority $i \in\{0, \ldots, p-1\}$, let the formula $(e)^{\sharp i}$ be defined by induction on $e$ as follows:

$$
\begin{aligned}
& (\lambda y: \kappa . e)^{\sharp i}=\lambda y^{\sharp 0}: \kappa^{\sharp} \ldots \lambda y^{\sharp p-1}: \kappa^{\sharp} \cdot e^{\sharp i} \\
& \left(e_{1} e_{2}\right)^{\sharp i}=e_{1}^{\sharp i} e_{2}^{\sharp \max (0, i)} e_{2}^{\sharp \max (1, i)} \cdots e_{2}^{\sharp \max (p-1, i)} \\
& (z)^{\sharp i}=z^{\sharp i} \text { if } z \text { is either a non-terminal or a variable } \\
& (\mathrm{a})^{\sharp i}=\lambda y_{1}^{\sharp 0}: \bullet . \cdots \lambda y_{1}^{\sharp p-1}: \bullet \cdot \cdots \lambda y_{\Sigma(\mathrm{a})}^{\sharp 0}: \bullet \cdot \cdots y_{\Sigma(\mathrm{a})}^{\sharp p-1}: \bullet . \\
& \bigvee_{i^{\prime}=0, \ldots, p-1}\left\langle\mathbf{a}_{i^{\prime}}\right\rangle\left(L_{\Sigma(\mathrm{a})} y_{1}^{\sharp i^{\prime}} \cdots y_{\Sigma(\mathrm{a})}^{\sharp i^{\prime}}\right) \\
& (\star)^{\sharp}=\bullet \\
& \left(\kappa_{1} \rightarrow \kappa_{2}\right)^{\sharp}=\underbrace{\left(\kappa_{1}\right)^{\sharp} \rightarrow \cdots \rightarrow\left(\kappa_{1}\right)^{\sharp}}_{p \text { times }} \rightarrow\left(\kappa_{2}\right)^{\sharp}
\end{aligned}
$$

where the $L_{n}$ 's definitions are as before and introduced in $\mathcal{E}_{\text {aux }}$. Intuitively, $i$ in $(e)^{\sharp i}$ denotes the largest priority visited before the tree generated by $e$ is visited (since the last unfolding of a nonterminal).
Example 10. Consider the HORS $\mathcal{G}_{1}$ consisting of the rules:

$$
S \rightarrow F B \quad F g \rightarrow \mathrm{ac}(g(F g)) \quad B x \rightarrow \mathrm{~b} x
$$

which is a simpler variant of $\mathcal{G}_{0}$ in Example 2. It generates the regular tree $T$ such that $T=\mathrm{ac}(\mathrm{b} T)$. The $\operatorname{HES} \mathcal{E}_{\mathcal{G}}^{(3)}$ is:

$$
\begin{aligned}
& S^{\sharp 2}={ }_{\nu} \varphi_{S} ; F^{\sharp 2}={ }_{\nu} \varphi_{F} ; B^{\sharp 2}={ }_{\nu} \varphi_{B} ; \\
& S^{\sharp 1}={ }_{\mu} \varphi_{S} ; F^{\sharp 1}={ }_{\mu} \varphi_{F} ; B^{\sharp 1}={ }_{\mu} \varphi_{B} ; \\
& S^{\sharp 0}={ }_{\nu} \varphi_{S} ; F^{\sharp 0}={ }_{\nu} \varphi_{F} ; B^{\sharp 0}={ }_{\nu} \varphi_{B} ; \mathcal{E}_{\text {aux }},
\end{aligned}
$$

where

$$
\begin{aligned}
& \varphi_{S}=F^{\sharp 0} B^{\sharp 0} B^{\sharp 1} B^{\sharp 2} \\
& \varphi_{F}=\lambda g^{\sharp 0} \cdot \lambda g^{\sharp 1} \cdot \lambda g^{\sharp 2} \text {. } \\
& \left\langle\mathrm{a}_{0}\right\rangle\left(L_{2}\left(\left\langle\mathrm{c}_{0}\right\rangle L_{0} \vee\left\langle\mathrm{c}_{1}\right\rangle L_{0} \vee\left\langle\mathrm{c}_{2}\right\rangle L_{0}\right) \varphi_{g(F g)}^{(0)}\right) \\
& \vee\left\langle\mathrm{a}_{1}\right\rangle\left(L_{2}\left(\left\langle\mathrm{c}_{0}\right\rangle L_{0} \vee\left\langle\mathrm{c}_{1}\right\rangle L_{0} \vee\left\langle\mathrm{c}_{2}\right\rangle L_{0}\right) \varphi_{g(F g)}^{(1)}\right) \\
& \vee\left\langle\mathbf{a}_{2}\right\rangle\left(L_{2}\left(\left\langle\mathrm{c}_{0}\right\rangle L_{0} \vee\left\langle\mathrm{c}_{1}\right\rangle L_{0} \vee\left\langle\mathrm{c}_{2}\right\rangle L_{0}\right) \varphi_{g(F g)}^{(2)}\right) \\
& \varphi_{B}=\lambda x^{\sharp 0} \cdot \lambda x^{\sharp 1} \cdot \lambda x^{\sharp 2} . \\
& \left\langle\mathrm{b}_{0}\right\rangle\left(L_{1} x^{\sharp 0}\right) \vee\left\langle\mathrm{b}_{1}\right\rangle\left(L_{1} x^{\sharp 1}\right) \vee\left\langle\mathrm{b}_{2}\right\rangle\left(L_{1} x^{\sharp 2}\right) \\
& \varphi_{g(F g)}^{(0)}=g^{\sharp 0} \varphi_{F g}^{(0)} \varphi_{F g}^{(1)} \varphi_{F g}^{(2)} \quad \varphi_{F}^{(0)}=F^{\sharp 0} g^{\sharp 0} g^{\sharp 1} g^{\sharp 2} \\
& \varphi_{g(F g)}^{(1)}=g^{\sharp 1} \varphi_{F}^{(1)} g \varphi_{F}^{(1)} \varphi_{F}^{(2)} \quad \varphi_{F}^{(1)} g=F^{\sharp 1} g^{\sharp 1} g^{\sharp 1} g^{\sharp 2} \\
& \varphi_{g(F g)}^{(2)}=g^{\sharp 2} \varphi_{F g}^{(2)} \varphi_{F g}^{(2)} \varphi_{F g}^{(2)} \quad \varphi_{F g}^{(2)}=F^{\sharp 2} g^{\sharp 2} g^{\sharp 2} g^{\sharp 2} .
\end{aligned}
$$

For the LTS $\mathcal{L}_{\mathcal{A}_{0}}$ in Figure 2, we can remove irrelevant parts of the formulas $\varphi_{S}, \varphi_{F}$ and $\varphi_{B}$ and simplify ${ }^{4}$ them to:

$$
\begin{aligned}
\varphi_{S}^{\prime}= & F^{\sharp 0} B^{\sharp 1} B^{\sharp 2} \\
\varphi_{F}^{\prime}= & \lambda g^{\sharp 1} \cdot \lambda g^{\sharp 2} . \\
& \left\langle\mathrm{a}_{1}\right\rangle\left(L_{2}\left(\left\langle\mathrm{c}_{1}\right\rangle L_{0}\right)\left(g^{\sharp 1}\left(F^{\sharp 1} g^{\sharp 1} g^{\sharp 2}\right)\left(F^{\sharp 2} g^{\sharp 2} g^{\sharp 2}\right)\right)\right) \\
& \quad \vee\left\langle\mathrm{a}_{2}\right\rangle\left(L_{2}\left(\left\langle\mathrm{c}_{1}\right\rangle L_{0}\right)\left(g^{\sharp 2}\left(F^{\sharp 2} g^{\sharp 2} g^{\sharp 2}\right)\left(F^{\sharp 2} g^{\sharp 2} g^{\sharp 2}\right)\right)\right) \\
\varphi_{B}^{\prime}= & \lambda x^{\sharp 1} \cdot \lambda x^{\sharp 2} \cdot\left(\left\langle\mathrm{~b}_{1}\right\rangle\left(L_{1} x^{\sharp 1}\right) \vee\left\langle\mathrm{b}_{2}\right\rangle\left(L_{1} x^{\sharp 2}\right)\right) .
\end{aligned}
$$

The simplified version of $S^{\sharp 2}$ can be expanded (with some further simplification) to:

$$
\begin{aligned}
& \left\langle\mathrm{a}_{1}\right\rangle\left(L_{2}\left(\left\langle\mathrm{c}_{1}\right\rangle L_{0}\right)\right. \\
& \quad\left(\langle \mathrm { b } _ { 1 } \rangle \left(L _ { 1 } \left(\langle \mathrm { a } _ { 2 } \rangle \left(L_{2}\left(\left\langle\mathrm{c}_{1}\right\rangle L_{0}\right)\right.\right.\right.\right. \\
& \left.\left.\left.\left.\quad\left(\left\langle\mathrm{b}_{1}\right\rangle\left(L_{1}\left(F^{\sharp 2} B^{\sharp 2} B^{\sharp 2}\right)\right)\right)\right)\right)\right)\right)
\end{aligned}
$$

and $F^{\sharp 2} B^{\sharp 2} B^{\sharp 2}$ may further be expanded to

$$
\begin{aligned}
\cdots \vee\left\langle\mathrm{a}_{2}\right\rangle\left(L_{2}\right. & \left(\left\langle\mathrm{c}_{1}\right\rangle L_{0}\right) \\
& \left.\left(\left\langle\mathrm{b}_{1}\right\rangle\left(L_{1}\left(F^{\sharp 2} B^{\sharp 2} B^{\sharp 2}\right)\right) \vee \cdots\right)\right) .
\end{aligned}
$$

The LTS in Figure 2 satisfies this property; note that $F^{\sharp 2}$ is defined by one of the outermost fixpoint operators $\nu$.

The correctness of the translation is stated in the theorem below. We prove it in Section 5, after preparing a type-based characterization of HFL model checking in Section 4.

Theorem 10. Let $\mathcal{A}$ be an APT with priorities in $\{0, \ldots, p-1\}$, and let $\mathcal{G}$ be a HORS. Then $T_{\mathcal{G}} \in L(\mathcal{A})$ iff $\mathcal{L}_{\mathcal{A}} \vDash \mathcal{E}_{\mathcal{G}}^{(p)}$.

It might be noticed that the size of $e^{\sharp i}$ is in $\mathcal{O}\left(p^{\text {an }(e)}|e|\right)$, where $p$ is the number of priorities, and $\mathrm{an}(e)$ is the nesting of applications inside arguments, defined via an $\left(e_{1} e_{2}\right)=\max \left(\operatorname{an}\left(e_{1}\right), 1+\operatorname{an}\left(e_{2}\right)\right)$, $\operatorname{an}(\lambda y . e)=\operatorname{an}(e)$, and $\operatorname{an}(A)=\operatorname{an}(\mathrm{a})=\operatorname{an}(y)=0$. This exponential blow-up might seem prohibitive, but it is easy to avoid. Indeed, by introducing some extra non-terminals, any HORS can be rewritten into an equivalent one with a linear blow-up such that for all non-terminal $A$, an $(\mathcal{R}(A)) \leq 2$.

Theorem 11. For every HORS $\mathcal{G}$ and every $p \geq 1$, there is an HES $\mathcal{E}$ of size linear in the size of $\mathcal{G}$ and polynomial in $p$ such that for any $A P T \mathcal{A}$ with priorities in $\{0, \ldots, p-1\}, T_{\mathcal{G}} \in L(\mathcal{A})$ iff $\mathcal{L}_{\mathcal{A}} \vDash \mathcal{E}$. Furthermore, $\mathcal{E}$ can be constructed in time polynomial in the size of $\mathcal{G}$ and $p$.

## 4. Intersection Types for HFL Model Checking

Inspired by Kobayashi and Ong's type system [13] for characterizing HORS model checking, this section develops a type system for

[^3]characterizing HFL model checking. It is parameterized by an LTS $\mathcal{L}$, and an HFL formula $\varphi$ that is typable in the type system if and only if $\mathcal{L} \models \varphi$. We shall use this type-based characterization for proving the correctness of the translation from HORS model checking to HFL model checking presented in Section 3 (Theorem 10). We expect that the type-based characterization is also useful for constructing a practical model checker for HFL.

We fix an LTS $\mathcal{L}=\left(U, A, \longrightarrow, s_{\text {init }}\right)$. We define the set of intersection types by:

$$
\tau::=s \mid \sigma \rightarrow \tau \quad \sigma::=\bigwedge\left\{\tau_{1}, \ldots, \tau_{k}\right\}
$$

Here, $s$ ranges over the set $U$ of states of $\mathcal{L}$. We often write $\tau_{1} \wedge \cdots \wedge \tau_{k}$ or $\bigwedge_{i \in\{1, \ldots, k\}} \tau_{i}$ for $\bigwedge\left\{\tau_{1}, \ldots, \tau_{k}\right\}$, and $\top$ for $\bigwedge \emptyset$.

Intuitively, the type $s$ describes propositions that are true in state $s$, and the type $\tau_{1} \wedge \cdots \wedge \tau_{k} \rightarrow \tau$ describes functions that take formulas having type $\tau_{i}$ for every $i$, and return a formula of type $\tau$. For example, the logical connective $\wedge$ (when viewed as a function that takes two propositions and returns a proposition) has type $s \rightarrow s \rightarrow s$ for any $s$, because given formulas $\varphi_{1}$ and $\varphi_{2}$ that are both true in state $s, \varphi_{1} \wedge \varphi_{2}$ is also true in state $s$. Similarly, $\vee$ has types $s \rightarrow \top \rightarrow s$ and $\top \rightarrow s \rightarrow s$ for every $s \in U$.

Each intersection type should be regarded as a refinement of a simple type $\kappa$ (constructed from $\bullet$ and $\rightarrow$, as introduced in Section 2.3). It does not make sense, for example, to consider an intersection type like $s \wedge\left(s_{1} \rightarrow s_{2}\right)$, where the part $s$ describes propositions whereas the part $s_{1} \rightarrow s_{2}$ describes functions on propositions. To exclude such an ill-formed intersection type, we define the refinement relations $\tau:: \kappa$ (which should be read " $\tau$ is a refinement of $\kappa$ ") and $\sigma:: \kappa$ inductively using the following rules:

$$
\frac{s \in U}{s:: \bullet} \frac{\tau_{i}:: \kappa \text { for each } i \in\{1, \ldots, k\}}{\tau_{1} \wedge \cdots \wedge \tau_{k}:: \kappa} \frac{\sigma:: \kappa}{(\sigma \rightarrow \tau)::\left(\kappa \rightarrow \kappa^{\prime}\right)}
$$

Henceforth, we consider only intersection types that are refinements of some simple types. We assume that each intersection type $\tau$ or $\sigma$ is implicitly annotated with the corresponding simple type (i.e., $\kappa$ such that $\tau:: \kappa$ or $\sigma:: \kappa)$ and write $\operatorname{Stype}(\tau)$ or $\operatorname{Stype}(\sigma)$ for $\kappa .{ }^{5}$

We assume below that an HFL formula is given in the form of an HES

$$
\mathcal{E}:=\left(X_{1}={ }_{\alpha_{1}} \varphi_{1} ; \cdots ; X_{n}={ }_{\alpha_{n}} \varphi_{n}\right)
$$

A type judgment for (fixpoint-free) HFL formulas is of the form $\Gamma \vdash \varphi: \tau$, where $\Gamma$, called an (intersection) type environment, is a set of type bindings of the form $X: \tau$. A type environment may contain multiple bindings for the same variable. We write $\Gamma(X)$ for $\tau_{1} \wedge \cdots \wedge \tau_{k}$ if $\{\sigma \mid X: \sigma \in \Gamma(X)\}=\left\{\tau_{1}, \ldots, \tau_{k}\right\}$. The type judgment relation is inductively defined by the typing rules in Figure 4. Note that in the rules HFL-T-ABS and HFL-T-APP above, $k$ may be 0 .

Most of the typing rules should be easy to understand, based on the intuition that $s$ is the type of a formula that is satisfied by the state $s$. For example, the rule HFL-T-SomE says that $s$ satisfies $\langle a\rangle \varphi$ if there exists a state $s^{\prime}$ and a transition $s \xrightarrow{a} s^{\prime}$ such that $s^{\prime}$ satisfies $\varphi$. The rules HFL-T-ABS and HFL-T-APP are the standard typing rules for abstractions and applications. The subtyping relation $\tau \leq \tau^{\prime}$ means, as usual, that a value of type $\tau$ may also be used as a value of type $\tau^{\prime}$.

Example 11. Consider the HES $\mathcal{E}_{0}$ of Example 6 and the LTS $\mathcal{L}_{0}$ of Example 4. Let $\Gamma=\left\{G:\left(s_{0} \rightarrow s_{1}\right) \rightarrow s_{0} \rightarrow s_{1}, G:\left(s_{1} \rightarrow\right.\right.$ $\left.\left.s_{1}\right) \rightarrow s_{1} \rightarrow s_{1}, F:\left(\left(s_{0} \rightarrow s_{1}\right) \wedge\left(s_{1} \rightarrow s_{1}\right)\right) \rightarrow s_{0}\right\}$. Then the type judgment $\Gamma \vdash \mathcal{E}(F):\left(\left(s_{0} \rightarrow s_{1}\right) \wedge\left(s_{1} \rightarrow s_{1}\right)\right) \rightarrow s_{0}$ holds (see the derivation in Figure 4).

[^4]\[

$$
\begin{aligned}
& \frac{s \in U}{\Gamma \vdash \top: s} \\
& \overline{\Gamma, X: \tau \vdash X: \tau} \\
& \frac{s \xrightarrow{a} s^{\prime} \quad \Gamma \vdash \varphi: s^{\prime}}{\Gamma \vdash\langle a\rangle \varphi: s} \\
& \Gamma \vdash \varphi: s^{\prime} \text { for every } s^{\prime} \text { such that } s \xrightarrow{a} s^{\prime} \\
& \Gamma \vdash[a] \varphi: s \\
& \frac{\Gamma \vdash \varphi_{1}: s \quad \Gamma \vdash \varphi_{2}: s}{\Gamma \vdash \varphi_{1} \wedge \varphi_{2}: s} \\
& \frac{\Gamma \vdash \varphi_{i}: s \text { for some } i \in\{1,2\}}{\Gamma \vdash \varphi_{1} \vee \varphi_{2}: s} \\
& \Gamma, X: \tau_{1}, \ldots, X: \tau_{k} \vdash \varphi: \tau \quad X \notin \operatorname{dom}(\Gamma) \\
& \tau_{i}:: \eta \text { for each } i \in\{1, \ldots, k\} \\
& \Gamma \vdash \lambda X: \eta \cdot \varphi: \tau_{1} \wedge \cdots \wedge \tau_{k} \rightarrow \tau \\
& \Gamma \vdash \varphi_{1}: \tau_{1} \wedge \cdots \wedge \tau_{k} \rightarrow \tau \\
& \Gamma \vdash \varphi_{2}: \tau_{i} \text { for each } i \in\{1, \ldots, k\} \\
& \Gamma \vdash \varphi_{1} \varphi_{2}: \tau \\
& \frac{\Gamma \vdash \varphi: \tau \quad \tau \leq \tau^{\prime}}{\Gamma \vdash \varphi: \tau^{\prime}} \\
& \overline{s \leq s} \\
& \frac{\sigma^{\prime} \leq \sigma \quad \tau \leq \tau^{\prime}}{\sigma \rightarrow \tau \leq \sigma^{\prime} \rightarrow \tau^{\prime}} \\
& \frac{\forall j \in\{1, \ldots, \ell\} \cdot \exists i \in\{1, \ldots, k\} \cdot \tau_{i} \leq \tau_{j}^{\prime}}{\tau_{1} \wedge \cdots \wedge \tau_{k} \leq \tau_{1}^{\prime} \wedge \cdots \wedge \tau_{\ell}^{\prime}}
\end{aligned}
$$
\]

(HFL-T-TRUE)
(HFL-T-VAR)
(HFL-T-SOME)
(HFL-T-ALL)
(HFL-T-AND)
(HFL-T-OR)
(HFL-T-ABS)
(HFL-T-APP)
(HFL-T-SUB)
(HFL-SUBT-BASE)
(HFL-SUBT-FUN)
(HFL-SubT-InT)
Figure 3. Typing rules for HFL formulas.

For an entire formula (represented in the form of an HES), we define typability in terms of a parity game.

Let $\operatorname{dep}(\mathcal{E})$ be the number of switches between $\nu$ and $\mu$ :

$$
\begin{aligned}
& \operatorname{dep}(\epsilon)=0 \\
& \operatorname{dep}\left(F={ }_{\nu} \varphi ; \mathcal{E}\right)= \begin{cases}\operatorname{dep}(\mathcal{E}) & \text { if } \operatorname{dep}(\mathcal{E}) \text { is even } \\
\operatorname{dep}(\mathcal{E})+1 & \text { if } \operatorname{dep}(\mathcal{E}) \text { is odd } \\
\operatorname{dep}(\mathcal{E}) & \text { if } \operatorname{dep}(\mathcal{E}) \text { is odd } \\
\operatorname{dep}(\mathcal{E})+1 & \text { if } \operatorname{dep}(\mathcal{E}) \text { is even }\end{cases}
\end{aligned}
$$

The priority of $F_{i}$ in $\mathcal{E}$, written $\Omega_{\mathcal{E}}\left(F_{i}\right)$ is defined as $\operatorname{dep}\left(F_{i}={ }_{\alpha_{i}}\right.$ $\left.\varphi_{i} ; \mathcal{E}_{2}\right)$ if $\mathcal{E}=\left(\mathcal{E}_{1} ; F_{i}={ }_{\alpha_{i}} \varphi_{i} ; \mathcal{E}_{2}\right)$. For example, for the HES $\mathcal{E}_{\perp}$ of Example $7, \Omega_{\mathcal{E}_{\perp}}(S)=3, \Omega_{\mathcal{E}_{\perp}}(Y)=2$, and $\Omega_{\mathcal{E}_{\perp}}(X)=1$. When $\mathcal{E}$ is clear from context, we omit the subscript and just write $\Omega\left(F_{i}\right)$.
Definition 12. Let $\mathcal{E}:=\left(F_{1}^{\eta_{1}}={ }_{\alpha_{1}} \varphi_{1} ; \cdots ; F_{n}^{\eta_{n}}={ }_{\alpha_{n}} \varphi_{n}\right)$ be a fixpoint-free $H E S$ with $\eta_{1}=\bullet$, and $\mathcal{L}=\left(U, A, \longrightarrow, s_{\text {init }}\right)$ an LTS. The typability game $\operatorname{TG}(\mathcal{L}, \mathcal{E})$ is the parity game $\left(V_{\forall}, V_{\exists}, v_{\text {init }}, E, \Omega\right)$, where:

- The set $V_{\forall}$ of Opponent's positions is the set of intersection type environments $\left\{\Gamma \mid \operatorname{dom}(\Gamma) \subseteq\left\{F_{1}, \ldots, F_{n}\right\} \wedge \forall\left(F_{i}: \tau\right) \in\right.$ $\left.\Gamma . \tau:: \eta_{i}\right\}$.
- The set $V_{\exists}$ of Player's positions is the set of type bindings that respect simple types, i.e., $\left\{F_{i}: \tau \mid \tau:: \eta_{i}\right\}$.
- $v_{\text {init }}$ is the initial position $F_{1}: s_{\text {init }}$.
- $E=E_{1} \cup E_{2}$, where $E_{1}$, the set of Player's moves, is $\left\{\left(F_{i}\right.\right.$ : $\left.\tau, \Gamma) \mid \Gamma \vdash \varphi_{i}: \tau\right\}$; and $E_{2}$, the set of Opponent's moves, is $\left\{\left(\Gamma, F_{i}: \tau\right) \mid F_{i}: \tau \in \Gamma\right\}$.
- The priority function $\Omega$, is defined by: $\Omega(\Gamma)=0$ for every $\Gamma \in V_{\forall}$, and $\Omega\left(F_{i}: \tau\right)=\Omega_{\mathcal{E}}\left(F_{i}\right)$ for every $F_{i}: \tau \in V_{\exists}$.

We write $\mathcal{L} \vdash \mathcal{E}$ when Player wins the parity game $\operatorname{TG}(\mathcal{L}, \mathcal{E})$.
Intuitively, in the game $\operatorname{TG}(\mathcal{L}, \mathcal{E})$ Player tries to prove that $\mathcal{L} \models \mathcal{E}$, and Opponent tries to disprove it. To this end, Player first shows that $\varphi_{1}$, the righthand side of $F_{1}$, has type $s_{\text {init }}$ (i.e., the initial state of $\mathcal{L}$ satisfies $\varphi_{1}$ ) under some type environment $\Gamma$, and Opponent challenges it by picking a type binding $F_{j}: \tau$ from $\Gamma$, and asking why $F_{j}$ has type $\tau$. Player then shows that $\varphi_{j}$ has type $\tau$ under some type environment $\Gamma^{\prime}$, and Opponent again challenges the assumption $\Gamma^{\prime}$, etc. Opponent gets stuck when Player's assumption $\Gamma^{\prime}$ is empty, in which case Player wins; Player gets stuck when she fails to show why $\varphi_{j}$ has type $\tau$, in which case Opponent wins. A play may continue indefinitely, in which case the winner is determined by the largest priority visited infinitely often.

Example 12. Consider again the HES $\mathcal{E}_{0}$ of Example 6 and the LTS $\mathcal{L}_{0}$ of Example 4. Let $\Gamma$ be like in Example 11. Then Player has a winning strategy by always moving to the type environment $\Gamma$ or the empty type environment (in which case Player wins).

- In the first round, Player is in position $S: s_{0}$, but it holds that $\Gamma \vdash \mathcal{E}(S)$ : $s_{0}$, so Player can move to $\Gamma$.
- In any next round, Player is in a successor position of $\Gamma$ chosen by Opponent, i.e. some type binding $A: \tau$ of $\Gamma$. If $A$ is either $G$ or $B$, Player can respond with the empty type environment, because $\emptyset \vdash \mathcal{E}(A): \tau$. Otherwise, Player is on position $F: \tau_{F}$ with $\tau_{F}=\left(\left(s_{0} \rightarrow s_{1}\right) \wedge\left(s_{1} \rightarrow s_{1}\right)\right) \rightarrow s_{0}$. We saw that $\Gamma \vdash F: \tau_{F}$ holds in Example 11, so Player is allowed to move to $\Gamma$.

Since the only infinite play according to this strategy is the one where Player's position (except the initial position) is always $F: \tau_{F}$, and since $F$ has priority 0, Player's strategy is a winning one.
Example 13. Consider the HFL formula $\varphi_{2}$ in Example 5, which is equivalent to the following HES $\mathcal{E}_{2}$ :

$$
\begin{aligned}
& S={ }_{\mu} E(F B)([b] \perp) ; \\
& E={ }_{\mu} \lambda X \cdot \lambda Y \cdot(X \wedge Y) \vee E(\langle a\rangle X)(\langle b\rangle Y) ; \\
& F={ }_{\nu} \lambda X \cdot\langle a\rangle(X(F(G X))) ; G={ }_{\nu} \lambda X . \lambda Y .\langle b\rangle(X Y) ; \\
& B={ }_{\nu} \lambda Y .\langle b\rangle Y .
\end{aligned}
$$

Then, we have:

$$
\begin{aligned}
& E: s_{0} \rightarrow s_{0} \rightarrow s_{0}, F:\left(\left(s_{0} \rightarrow s_{1}\right) \wedge\left(s_{1} \rightarrow s_{1}\right)\right) \rightarrow s_{0}, \\
& \quad B: s_{0} \rightarrow s_{1}, B: s_{1} \rightarrow s_{1} \vdash \mathcal{E}_{2}(S): s_{0} \\
& \emptyset \vdash \mathcal{E}_{2}(E): s_{0} \rightarrow s_{0} \rightarrow s_{0} \\
& \Gamma \vdash \mathcal{E}_{2}(F):\left(\left(s_{0} \rightarrow s_{1}\right) \wedge\left(s_{1} \rightarrow s_{1}\right)\right) \rightarrow s_{0} \\
& \emptyset \vdash \mathcal{E}_{2}(G):\left(s_{0} \rightarrow s_{1}\right) \rightarrow s_{0} \rightarrow s_{1} \\
& \emptyset \vdash \mathcal{E}_{2}(G):\left(s_{1} \rightarrow s_{1}\right) \rightarrow s_{1} \rightarrow s_{1} \\
& \emptyset \vdash \mathcal{E}_{2}(B): s_{0} \rightarrow s_{1} \quad \emptyset \vdash \mathcal{E}_{2}(B): s_{1} \rightarrow s_{1}
\end{aligned}
$$

where $\Gamma$ is the one given in Example 11. These type judgments determine a winning strategy for Player.

Example 14. Consider the unsatisfiable HES $\mathcal{E}_{\perp}$ of Example 7; recall that $\Omega_{\mathcal{E}_{\perp}}(S)=3, \Omega_{\mathcal{E}_{\perp}}(Y)=2$, and $\Omega_{\mathcal{E}_{\perp}}(X)=1$. Let $\mathcal{L}=(\{s\},\{a\}, \longrightarrow, s)$ with $s \xrightarrow{a} s$. A strategy for Player in $\mathbf{T G}\left(\mathcal{L}, \mathcal{E}_{\perp}\right)$ is to always play $\Gamma=\{X: s, Y: s \rightarrow s\}$. This strategy can be seen as a cyclic type derivation that is depicted in Figure 5. It is not a winning strategy: the dashed cycle has the largest priority 2, but the self loop on $X: s$ (depicted with a thick line) has the largest priority 1, hence Opponent can force an infinite play with the largest priority 1.

We now prove that the type-based characterization is sound and complete.
Theorem 13 (soundness and completeness of the type-based characterization). Let $\mathcal{E}$ be a fixpoint-free HES and $\mathcal{L}$ an LTS. Then, $\mathcal{L} \vdash \mathcal{E}$ if and only if $\mathcal{L} \models \mathcal{E}$.

$$
\begin{aligned}
& \underset{X}{\Gamma} \vdash G:\left(s_{0} \rightarrow s_{1}\right) \rightarrow s_{0} \rightarrow s_{1} \quad \underset{X}{\Gamma} \vdash G:\left(s_{1} \rightarrow s_{1}\right) \rightarrow s_{1} \rightarrow s_{1} \\
& X: s_{0} \rightarrow s_{1} \vdash X: s_{0} \rightarrow s_{1} \quad X: s_{1} \rightarrow s_{1} \vdash X: s_{1} \rightarrow s_{1} \\
& \Gamma \vdash F:\left(\left(s_{0} \rightarrow s_{1}\right) \wedge\left(s_{1} \rightarrow s_{1}\right)\right) \rightarrow s_{0} \quad \xlongequal{\Gamma, X: s_{0} \rightarrow s_{1} \vdash G X: s_{0} \rightarrow s_{1}} \quad \stackrel{X}{\Gamma, X: s_{1} \rightarrow s_{1} \vdash G X: s_{1} \rightarrow s_{1}} \\
& X: s_{0} \rightarrow s_{1} \vdash X: s_{0} \rightarrow s_{1} \quad \Gamma, X: s_{0} \rightarrow s_{1}, X: s_{1} \rightarrow s_{1} \vdash F(G X): s_{0} \\
& \Gamma, X: s_{0} \rightarrow s_{1}, X: s_{1} \rightarrow s_{1} \vdash X(F(G X)): s_{1} \\
& \overline{\Gamma, X: s_{0} \rightarrow s_{1}, X: s_{1} \rightarrow s_{1} \vdash\langle\mathrm{a}\rangle(X(F(G X))): s_{0}} \\
& \overline{\Gamma \vdash \lambda X .\langle\mathrm{a}\rangle(X(F(G X))):\left(\left(s_{1} \rightarrow s_{1}\right) \wedge\left(s_{0} \rightarrow s_{1}\right)\right) \rightarrow s_{0}}
\end{aligned}
$$

Figure 4. Type derivation for $\Gamma \vdash \mathcal{E}(F):\left(\left(s_{1} \rightarrow s_{1}\right) \wedge\left(s_{0} \rightarrow s_{1}\right)\right) \rightarrow s_{0}$ in Example 11.


Figure 5. A Player's strategy in the typing game of Example 14.

The proof of the above theorem is given in Appendix A; here we just give an outline. The proof uses a semantic counterpart $\mathbf{S G}(\mathcal{L}, \mathcal{E})$ of the typability game, which is obtained from $\operatorname{TG}(\mathcal{L}, \mathcal{E})$ by replacing the player's moves $\left\{\left(F_{i}: \tau, \Gamma\right) \mid \Gamma \vdash \varphi_{i}: \tau\right\}$ with $\left\{\left(F_{i}: \tau, \Gamma\right)|\Gamma|=\varphi_{i}: \tau\right\}$, where $\Gamma \models \varphi_{j}: \tau$ is a semantic type judgment relation. Since $\Gamma \vdash \varphi_{j}: \tau$ if and only $\Gamma \models \varphi_{j}: \tau$, the semantic typability game $\operatorname{SG}(\mathcal{L}, \mathcal{E})$ is actually isomorphic to the (syntactic) typability game $\operatorname{TG}(\mathcal{L}, \mathcal{E})$. We can then transform the semantic typability game step by step, preserving the winner, until we get the semantic typability game for the extended HES (where fixpoint binders may occur in definitions) consisting of the single equation $F_{1}=\operatorname{toHFL}(\mathcal{E})$. Because $\operatorname{SG}\left(\mathcal{L}, F_{1}=\operatorname{toHFL}(\mathcal{E})\right)$ is winning for Player if and only if $\mathcal{L} \models \mathcal{E}$, we have the required result.

As a corollary of Theorem 13 , we also have the following parameterized complexity result.

Theorem 14. Let $\mathcal{E}$ be a HES and $\mathcal{L}$ an LTS. Suppose that the following parameters are bounded above by constants: (i) the depth of $\mathcal{E}$; (ii) the size of the largest (simple) type in $\mathcal{E}$; and (iii) the size of $\mathcal{L}$ (i.e., the number of states plus the size of the transition relation $\longrightarrow)$. Then, $\mathcal{L} \stackrel{?}{=} \mathcal{E}$ can be decided in time polynomial in the size of $\mathcal{E}$.

The theorem follows from the same reasoning as that for the parameterized complexity result for HORS model checking [13]. Under the assumption above, for each variable of type $\eta$, the number of intersection types $\tau$ such that $\tau:: \eta$ is bounded above by a constant. Thus, the size of each type environment in the typability game is linear in the size of $\mathcal{E}$, hence also is the size of the typability game. By the assumption that the depth $\operatorname{dep}(\mathcal{E})$ is fixed, the game can be solved in time polynomial in the size of the game, hence also in the size of $\mathcal{E}$.

## 5. Correctness of the HORS-to-HFL Reduction (Proof of Theorem 10)

In this section, we establish the correctness of the HORS-to-HFL reduction (Theorem 13) we presented in Section 3. The proof relies on the type-based characterization of HORS model-checking based on Kobayashi and Ong's type system [13] (KO type system, for short). Below we first briefly review KO type system in Section 5.1. Then we show that the typability of a HORS model-checking
instance in the KO type system is equivalent to the typability of its HFL translation in the type system of Section 4.

### 5.1 KO Type System

We review here (a variation of) KO type system for characterizing HORS model checking [15]. We fix an alternating parity automaton $\mathcal{A}=\left(Q, \Sigma, \delta, q_{\text {init }}, \Omega\right)$. KO types are defined by the grammar

$$
\theta::=q \mid \varsigma \rightarrow \theta \quad \varsigma::=\bigwedge\left\{\left(\theta_{1}, m_{1}\right), \ldots,\left(\theta_{k}, m_{k}\right)\right\}
$$

Here, $q$ ranges over the set $Q$ of states of the automaton, and $m_{j}$ ranges over the set $\{0, \ldots, p-1\}$ of priorities of $\mathcal{A}$. As in the case of intersection types for HFL, we often write $\left(\theta_{1}, m_{1}\right) \wedge \cdots \wedge\left(\theta_{k}, m_{k}\right)$ or $\bigwedge_{i \in\{1, \ldots, k\}}\left(\theta_{i}, m_{i}\right)$ for $\wedge\left\{\left(\theta_{1}, m_{1}\right), \ldots,\left(\theta_{k}, m_{k}\right)\right\}$, and $T$ for $\wedge \emptyset$.

Intuitively, $q$ is the type of a tree that is accepted by $\mathcal{A}$ when $q$ is taken as the initial state, whereas $\varsigma_{1} \rightarrow \ldots \varsigma_{n} \rightarrow q$ with $\varsigma_{j}=$ $\left(\theta_{j, 1}, m_{j, 1}\right) \wedge \cdots \wedge\left(\theta_{j, k_{j}}, m_{j, k_{j}}\right)$ is the type of an $n$-ary function that may use the $j$-th argument as a value of types $\theta_{j, 1}, \ldots, \theta_{j, k_{j}}$ and generates a tree of type $q$. The part $m_{j, \ell}\left(\ell \in\left\{1, \ldots, k_{j}\right\}\right)$ expresses where the $j$-th argument may be used as a value of type $\theta_{j, \ell}$; intuitively, $\left(\theta_{j, \ell}, m_{j, \ell}\right)$ specifies that in constructing the output tree of type $q$, the $j$-th argument may be used as a value of type $\theta_{j, \ell}$ in a node of the tree in which the largest priority visited in the path from the root to this node is $m_{j, \ell}$. For the space restriction, we refer the reader to [15] for more intuitions on KO types. A slight difference between the original KO type system and the one presented here is that by "the largest priority visited in the path from the root", we exclude the priority of the current node, whereas the original type system included it. This change is just for technical convenience for matching the HFL type system in the previous section with KO type system.

As in the type system of Section 4, we only consider KO types $\varsigma$ that are refinements of simple types $\kappa$ (which we write $\varsigma:: \kappa$, defined in a similar manner as in Section 4), and the empty intersection type that refines $\kappa$ is written $\top^{\kappa}$ or just $\top$ when $\kappa$ is not meaningful. A type environment is a set $\Theta$ of bindings $x:(\varsigma, m)$ where $x$ is either a non-terminal or a term variable, and $m$ is a priority.

The typing rules of KO type system are given in Figure 6. In the rule $\mathrm{KO}-\mathrm{T}-\mathrm{Const}$, the relation $\mathbf{Q} \vDash f$ (where $f \in$ $\mathrm{B}^{+}(\{1, \ldots, n\} \times Q)$ and $\mathbf{Q}=\left(Q_{1}, \ldots, Q_{n}\right)$ with $Q_{i} \subseteq Q$ for each $i$ ) is defined by induction on $f$ : (i) $\mathbf{Q} \neq \mathrm{tt}$, (ii) $\mathbf{Q} \not \vDash \mathrm{ff}$, (iii) $\mathbf{Q} \vDash(i, q)$ if $\left(q \in Q_{i}\right)$, (iv) $\mathbf{Q} \vDash f_{1} \vee f_{2}$ if $\mathbf{Q} \models f_{1}$ or $\mathbf{Q} \mid=f_{2}$, and (v) $\mathbf{Q} \vDash f_{1} \wedge f_{2}$ if $\mathbf{Q} \vDash f_{1}$ and $\mathbf{Q} \vDash f_{2}$. The operation $\cdot \uparrow_{m}$ on type environments is defined by:

$$
\Theta \uparrow_{m}:=\left\{x:\left(\theta, \max \left(m, m^{\prime}\right)\right) \mid x:\left(\theta, m^{\prime}\right) \in \Theta\right\} .
$$

The KO typability game $\operatorname{KG}(\mathcal{G}, \mathcal{A})$ for a $\operatorname{HORS} \mathcal{G}=(\Sigma, \mathcal{N}, \mathcal{R}$, $S)$ and an APT $\mathcal{A}=\left(Q, \Sigma, \delta, q_{\text {init }}, \Omega\right)$ is a parity game $\left(V_{\forall}, V_{\exists}, v_{\text {init }}\right.$, $E, \Omega^{\prime}$, where:

- The set $V_{\forall}$ of Opponent's positions is the set of intersection type environments $\left\{\Theta \mid \forall\left(F_{i}: \theta\right) \in \Theta . \theta:: \mathcal{N}\left(F_{i}\right)\right\}$.

$$
\begin{aligned}
& \overline{x:(\theta, 0) \vdash_{\mathcal{A}}^{\text {HORS }} x: \theta}
\end{aligned}
$$

$$
\begin{aligned}
& \Theta_{0} \vdash_{\mathcal{A}}^{\text {HORS }} e_{0}: \bigwedge_{i \in I}\left(\theta_{i}, m_{i}\right) \rightarrow \theta \\
& \frac{\Theta_{i} \vdash_{\mathcal{A}}^{\text {HORS }} e_{1}: \theta_{i} \text { for each } i \in I}{\Theta_{0} \cup \bigcup_{i \in I}\left(\Theta_{i} \uparrow m_{i}\right) \vdash \vdash_{\mathcal{A}}^{\text {HoRS }} e_{0} e_{1}: \theta} \\
& \Theta \cup\left\{x:\left(\theta_{i}, m_{i}\right) \mid i \in I\right\} \stackrel{\vdash_{\mathcal{A}}^{\text {HORS }}}{ } e: \theta \\
& x \text { does not occur in } \Theta \\
& \Theta \vdash_{\mathcal{A}}^{\text {HORS }} \lambda x . e: \bigwedge_{i \in I}\left(\theta_{i}, m_{i}\right) \rightarrow \theta \\
& \frac{\Theta \vdash_{\mathcal{A}}^{\text {HORS }} e: \theta \quad \theta \leq \theta^{\prime}}{\Theta \vdash_{\mathcal{A}}^{\text {HoRS }} e: \theta^{\prime}} \\
& \overline{q \leq q} \\
& \frac{\theta \leq \theta^{\prime} \quad \forall i \in I . \exists j \in J .\left(\theta_{j}^{\prime} \leq \theta_{i} \wedge m_{j}^{\prime}=m_{i}\right)}{\bigwedge_{i \in I}\left(\theta_{i}, m_{i}\right) \rightarrow \theta \leq \bigwedge_{j \in J}\left(\theta_{j}^{\prime}, m_{j}^{\prime}\right) \rightarrow \theta^{\prime}} \\
& \text { (KO-T-APP) } \\
& \text { (KO-T-ABS) } \\
& \text { (KO-T-Sub) } \\
& \text { (KO-SubT-Base) } \\
& \text { (KO-SubT-Fun) }
\end{aligned}
$$

Figure 6. KO type system.

- The set $V_{\exists}$ of Player's positions is the set of type bindings that respect simple types, i.e., $\left\{F_{i}:(\theta, m) \mid \tau:: \mathcal{N}\left(F_{i}\right)\right\}$.
- $v_{\text {init }}$ is the initial position $F:\left(q_{\text {init }}, \Omega\left(q_{\text {init }}\right)\right)$.
- $E=E_{1} \cup E_{2}$, where $E_{1}$, the set of Player's moves, is $\left\{\left(F_{i}\right.\right.$ : $\left.(\theta, m), \Theta) \mid \Theta \vdash \mathcal{R}\left(F_{i}\right): \theta\right\}$; and $E_{2}$, the set of Opponent's moves, is $\left\{\left(\Theta, F_{i}:(\theta, m)\right) \mid F_{i}:(\theta, m) \in \Theta\right\}$.
- The priority function $\Omega^{\prime}$, is defined by: $\Omega^{\prime}(\Theta)=0$ for every $\Theta \in V_{\forall}$, and $\Omega^{\prime}\left(F_{i}:(\theta, m)\right)=m$ for every $F_{i}:(\theta, m) \in V_{\exists}$.

We write $\vdash_{\mathcal{A}}^{\text {HoRs }} \mathcal{G}$ if Player has a winning strategy for $\operatorname{KG}(\mathcal{G}, \mathcal{A})$. The following theorem states the soundness and completeness of KO type system. ${ }^{6}$

Theorem 15 (Kobayashi and Ong [15]). Suppose that $T_{\mathcal{G}}$ does not contain $\perp$. Then, $\vdash_{\mathcal{A}}^{\mathrm{HRS}} \mathcal{G}$ if and only if $T_{\mathcal{G}} \in L(\mathcal{A})$.

### 5.2 Preservation of the Typability

Fix a HORS $\mathcal{G}$ and an APT $\mathcal{A}$ with the set $\{0, \ldots, p-1\}$ of priorities. We want to relate the typing game for $\operatorname{KG}(\mathcal{G}, \mathcal{A})$ to the typing game $\operatorname{TG}\left(\mathcal{L}_{\mathcal{A}}, \mathcal{E}_{\mathcal{G}}^{(p)}\right)$. To avoid confusion, we write below $\Gamma \vdash^{\text {HFL }} \varphi: \tau$ for the type judgment in HFL.

We first identify types for HFL model-checking (Section 4) and KO types. We define the translation $(\cdot)^{\sharp}$ of KO types to the types in Section 4.

$$
\begin{aligned}
& (q)^{\sharp}=q \\
& \left(\bigwedge_{j \in J}\left(\theta_{j}, m_{j}\right) \rightarrow \theta\right)^{\sharp}= \\
& \quad \bigwedge_{j \in J, m_{j}=0}\left(\theta_{j}\right)^{\sharp} \rightarrow \cdots \rightarrow \bigwedge_{j \in J, m_{j}=p-1}\left(\theta_{j}\right)^{\sharp} \rightarrow(\theta)^{\sharp}
\end{aligned}
$$

For example, with $p=2,\left(\left(q_{0}, 0\right) \wedge\left(q_{1}, 0\right) \wedge\left(q_{1}, 1\right) \rightarrow q\right)^{\sharp}=$ $q_{0} \wedge q_{1} \rightarrow q_{1} \rightarrow q$. Note that $\theta:: \kappa$ implies $(\theta)^{\sharp}:: \kappa^{\sharp}$, and that for any HFL intersection type $\tau$, there is a KO type $\theta$ such that $\tau=(\theta)^{\sharp}$

[^5]if and only if $\tau:: \kappa^{\sharp}$ for some $\kappa$, and in that case, $\theta$ is unique. We write $(\tau)^{b}$ for this $\theta$. In particular, it holds that
\[

$$
\begin{aligned}
& (q)^{b}=q \\
& \left(\bigwedge_{j \in I_{0}} \tau_{j} \rightarrow \cdots \rightarrow \bigwedge_{j \in I_{p-1}} \tau_{j} \rightarrow \tau\right)^{b}= \\
& \quad \bigwedge_{i \in\{0, \ldots, p-1\}, j \in I_{i}}\left(\left(\tau_{j}\right)^{b}, i\right) \rightarrow(\tau)^{b} .
\end{aligned}
$$
\]

We extend (. $)^{\sharp}$ and (. $)^{b}$ to type environments:

$$
\begin{aligned}
& (\Gamma)^{b}=\left\{A:\left((\tau)^{b}, i\right) \mid A^{\sharp i}: \tau \in \Gamma\right\} \\
& (\Theta)^{\sharp}=\left\{A^{\sharp i}:(\theta)^{\sharp} \mid A:(\theta, i) \in \Theta\right\} \cup \Gamma_{a u x},
\end{aligned}
$$

where $\Gamma_{a u x}=\left\{L_{n}: \bigwedge_{q_{1} \in Q_{1}} q_{1} \rightarrow \cdots \bigwedge_{q_{n} \in Q_{n}} q_{n} \rightarrow f \mid\right.$ $\left.\left(Q_{1}, \ldots, Q_{n}\right) \models f\right\}$ is the type environment for all $L_{n}$. Note that $(\Gamma)^{b}$ is well defined for the type environments used in the typing game of $\mathbf{T G}\left(\mathcal{L}_{\mathcal{A}}, \mathcal{E}_{\mathcal{G}}^{(p)}\right)$ because it only contains bindings $A^{\sharp i}: \tau$ for intersection types $\tau$ that refine a type of the form $\kappa^{\sharp}$.

We can show that the transformation preserves typing.
Lemma 16. Let e be a term of a HORS. If $\Theta \vdash^{\text {HoRS }} e: \theta$, then $(\Theta)^{\sharp} \vdash^{\text {HFL }} e^{\sharp 0}:(\theta)^{\sharp}$. Conversely, if $\Gamma \vdash^{\text {HFL }} e^{\sharp 0}: \tau$, then $(\Gamma)^{b} \vdash$ HORS $e:(\tau)^{b}$.

The following lemma guarantees that $L_{n}: \tau \in \Gamma_{a u x}$ if and only if it is a winning position of $\operatorname{TG}\left(\mathcal{L}_{\mathcal{A}}, \mathcal{E}_{\mathcal{G}}^{(p)}\right)$.
Lemma 17. Let $f$ be a subformula of $\delta(q, a)$ with $\Sigma(a)=n$, and $Q_{1}, \ldots, Q_{n} \subseteq Q$. Then $\vdash^{\text {HFL }} L_{n}: \bigwedge_{q \in Q_{1}} q \rightarrow \bigwedge_{q \in Q_{2}} q \rightarrow$ $\cdots \rightarrow \bigwedge_{q \in Q_{n}} q \rightarrow f$ is a winning position of the HFL typability game if and only if $\left(Q_{1}, \ldots, Q_{n}\right) \models f$.

We can now prove that the reduction preserves typability.
Theorem 18. Let $\mathcal{G}$ be a HORS and $\mathcal{A}$ be an alternating parity tree automaton. Then, $\vdash_{\mathcal{A}}^{\text {HORS }} \mathcal{G}$ if and only if $\mathcal{L}_{\mathcal{A}} \vdash^{\text {HFL }} \mathcal{E}_{\mathcal{G}}^{(p)}$.
Proof. Let $\mathbf{G}$ be the parity game obtained from $\operatorname{TG}\left(\mathcal{L}_{\mathcal{A}}, \mathcal{E}_{\mathcal{G}}^{(p)}\right)$ by removing Player's positions of the form $L_{n}: \tau$, and the edges from/to those positions. By Lemma 17, the winners of $\operatorname{TG}\left(\mathcal{L}_{\mathcal{A}}, \mathcal{E}_{\mathcal{G}}^{(p)}\right)$ and $\mathbf{G}$ are the same.

Notice that (. $)^{\sharp}$ and (. $)^{b}$ are bijections between the positions of $\mathbf{G}$ and the ones of $\operatorname{KG}(\mathcal{G}, \mathcal{A})$. By Lemma 16, these bijections are graph isomorphisms between the graphs of the arenas of the games. Moreover, the priority of every Opponent's position is 0 in both games, and for Player's positions, $\Omega\left(x^{\sharp m}: \tau\right)=m=\Omega(x$ : $(\tau, m))$ holds. So both games are isomorphic.

Theorem 10 is an immediate corollary of Theorems 13,15 , and 18.

Remark 2. As mentioned in Section 1, since the decidability of HFL model checking is straightforward, the decidability of HORS model checking is an immediate corollary of Theorem 10. Our proof of Theorem 10 in this section, however, does not qualify as a new proof of the decidability of HORS model checking, because it relies on the soundness and completeness of the KO type system.

## 6. From HFL to HORS Model Checking

In this section, we present a reduction from HFL model checking to HORS model checking.

Recall that, over a (finite) LTS, by the Kleene Fixpoint Theorem, any fixpoint formula $\alpha F^{\eta} . \psi$ with $\alpha \in\{\mu, \nu\}$ and $\eta=\eta_{1} \rightarrow$ $\cdots \rightarrow \eta_{\ell} \rightarrow \bullet$ is equivalent to $F^{n}$ where

$$
\begin{aligned}
F^{0} & = \begin{cases}\lambda x_{1}: \eta_{1} \cdots \lambda x_{\ell}: \eta_{\ell} \cdot \top & \text { if } \alpha=\nu \\
\lambda x_{1}: \eta_{1} \cdots \lambda x_{\ell}: \eta_{\ell} \cdot \perp & \text { if } \alpha=\mu\end{cases} \\
F^{i+1} & =\left[F^{i} / F\right] \psi
\end{aligned}
$$

and $n$ is greater than the height of the lattice of $D_{\eta}$. For $\eta$ of order $k$, this height is a number $k$-fold exponential in the number of states of the LTS. Precise bounds can be found in [2]. Our aim is to create a HORS that generates the syntax tree of $F^{(n)}$, and then runs it against an alternating automaton that encodes the LTS in question.

### 6.1 Overview of the Translation

We first give an overview of the translation using an example. Let us consider the following HES $\mathcal{E}$ :

$$
S={ }_{\nu} F(\langle a\rangle \top) ; \quad F X={ }_{\mu} X \vee\langle b\rangle(F X) .
$$

It represents the property that the action $a$ may be enabled after finitely many $b$ transitions. For a sufficiently large number $n, \mathcal{E}$ is equivalent to the following HES $\mathcal{E}^{\prime}$, obtained by unfolding $F n$ times.

$$
\begin{aligned}
& S={ }_{\nu} F^{(n)}(\langle a\rangle \top) \\
& F^{(n)} X={ }_{\mu} X \vee\langle b\rangle\left(F^{(n-1)} X\right) \\
& \cdots \\
& F^{(1)} X={ }_{\mu} X \vee\langle b\rangle\left(F^{(0)} X\right) \\
& F^{(0)} X={ }_{\mu} \perp
\end{aligned}
$$

The annotations $\nu$ and $\mu$ in $\mathcal{E}^{\prime}$ above actually do not matter, because $\mathcal{E}^{\prime}$ does not contain any recursion. Now, by replacing each logical connective with the corresponding tree constructor, we obtain the following HORS $\mathcal{G}_{\mathcal{E}}$, which generates the syntax tree of the formula obtained by reducing $\mathcal{E}^{\prime}$ :

$$
\begin{aligned}
& S \rightarrow F^{(n)}(\langle a\rangle \top) \\
& F^{(n)} X \rightarrow \vee X\left(\langle b\rangle\left(F^{(n)} X\right)\right) \\
& \cdots \\
& F^{(1)} X \rightarrow \vee X\left(\langle b\rangle\left(F^{(0)} X\right)\right) \\
& F^{(0)} X \rightarrow \perp .
\end{aligned}
$$

Let $\mathcal{L}=\left(U, A, \longrightarrow, s_{\text {init }}\right)$ be an LTS. To check whether $\mathcal{L} \models \mathcal{E}^{\prime}$ (hence also $\mathcal{L} \models \mathcal{E}$ ) holds, it suffices to run a tree automaton to evaluate (the formula represented by) the tree $T_{\mathcal{G}_{\mathcal{E}}}$ against $\mathcal{L}$. Such an automaton $\mathcal{A}_{\mathcal{L}}$ would be of the form $\left(\left\{q_{s} \mid s \in U\right\}, \Sigma, \delta, q_{s_{\text {init }}}, \Omega\right)$ where $q_{s}$ is a state for checking whether $s$ satisfies the formula represented by the current subtree, the alphabet $\Sigma$ consists of the tree constructors corresponding to logical connectives, and the transition function $\delta$ is defined by: ${ }^{7}$

$$
\begin{aligned}
& \delta\left(q_{s}, \top\right)=\mathrm{tt} \quad \delta\left(q_{s}, \perp\right)=\mathrm{ff} \quad \delta\left(q_{s}, \vee\right)=\left(1, q_{s}\right) \vee\left(2, q_{s}\right) \\
& \delta\left(q_{s},\langle a\rangle\right)=\vee\left\{\left(1, q_{s^{\prime}}\right) \mid s \xrightarrow{a} s^{\prime}\right\} \quad \cdots .
\end{aligned}
$$

Then, we have $\mathcal{L} \models \mathcal{E}$ if and only if $\mathcal{G}_{\mathcal{E}} \models \mathcal{A}_{\mathcal{L}}$; thus we have reduced HFL model checking to HORS model checking.

The remaining problem is that $\mathcal{G}_{\mathcal{E}}$ is too large, because the required number $n$ of unfoldings is in general $k$-fold exponential in the size of $\mathcal{L}$ for an order- $k$ HES. To address the problem, we parameterize each non-terminal $F^{(j)}$ above by the number $j$, and encode numbers as terms of HORS. Thus, the resulting HORS is given by:

$$
\begin{aligned}
& S \rightarrow F n(\langle a\rangle \top) \\
& F j X \rightarrow \text { if }(\text { IsZero } j) \perp(\vee X(\langle b\rangle(F(j-1) X))) .
\end{aligned}
$$

Below, we first prepare an encoding of numbers in Section 6.2. We then present the general translation from HFL model checking to HORS model checking in Section 6.3.

### 6.2 Counting with HORS

As a first step, we show how to implement large numbers in HORS. Our encoding follows that of Jones [7]. Let $\exp _{k}(r)$ denote the $k$ fold exponent of $r$, defined by $\exp _{0}(r)$ and $\exp _{i+1}(r)=2^{\exp _{i}(r)}$.

[^6]For our purpose, we need to represent numbers up to $\exp _{k}(r)$ by terms of order at most $k-1$ and of size polynomial in $r$. Prepare Bit $=\{0,1\}$ and let $\mathbf{N u m}_{i}$ be defined by

$$
\begin{aligned}
& \mathbf{N u m}_{1}=\underbrace{\text { Bit } \times \cdots \times \text { Bit }}_{r} \\
& \mathbf{N u m}_{i+1}=\mathbf{N u m}_{i} \rightarrow \mathbf{B i t} .
\end{aligned}
$$

For every $i$, let $\llbracket \cdot \rrbracket_{i}:\left\{0, \ldots, \exp _{i}(r)-1\right\} \rightarrow \mathbf{N u m}_{i}$ be the bijection defined as follows: (i) for every $n \in\left\{1, \ldots, 2^{r}-1\right\}$, $\llbracket n \rrbracket_{1}=\left(b_{0}, \ldots, b_{r-1}\right)$, where $b_{0} \ldots b_{r-1}$ is the binary representation of $n$ starting with $b_{0}$ as the least significant bit; (ii) for every $n \in\left\{0, \ldots, \exp _{i+1}(r)-1\right\}$, for every $m \in\left\{0, \ldots, \exp _{i}(r)-1\right\}$ $\llbracket n \rrbracket_{i+1}$ maps $\llbracket m \rrbracket_{i}$ to $b_{m}$, where $b_{0} \ldots b_{\exp _{i}(r)-1}$ is the binary representation of $n$.

In order to compute with bits, we represent bit expressions as $\Sigma_{\text {Bit }}$-labeled (possibly infinite) trees where $\Sigma_{\text {Bit }}=\{1 \mapsto 0,0 \mapsto$ 0 , if $\mapsto 3\}$. We define the relation $T \Downarrow b$ inductively, by: (i) $1 \Downarrow 1$, (ii) $0 \Downarrow 0$, (iii) if $T_{0} T_{1} T_{2} \Downarrow b$ if $T_{0} \Downarrow 1$ and $T_{1} \Downarrow b$, and (iv) if $T_{0} T_{1} T_{2} \Downarrow b$ if $T_{0} \Downarrow 0$ and $T_{2} \Downarrow b$. We call $b$ the value of $T$ when $T \Downarrow b$ holds. Note that a bit expression $T$ may or may not have a value if $T$ is infinite.

We prepare an automaton to evaluate bit expressions. Let $\mathcal{A}^{\text {Bit }}$ be the APT $\left(\left\{q_{1}, q_{0}\right\}, \Sigma_{\text {Bit }}, \delta, q_{1}, \Omega\right)$, with

$$
\begin{aligned}
& \delta(q, \text { if })=\left(\left(1, q_{1}\right) \wedge(2, q)\right) \vee\left(\left(1, q_{0}\right) \wedge(3, q)\right) \\
& \delta\left(q_{1}, 1\right)=\delta\left(q_{0}, 0\right)=\mathrm{tt} \\
& \delta\left(q_{1}, 0\right)=\delta\left(q_{0}, 1\right)=\mathrm{ff} \\
& \Omega\left(q_{1}\right)=\Omega\left(q_{0}\right)=1 .
\end{aligned}
$$

Lemma 19. $\mathcal{A}^{\text {Bit }}$ accepts a tree $T$ from state $q_{1}\left(q_{0}\right.$, resp.) if and only if $T \Downarrow 1$ ( $T \Downarrow 0$, resp.).

We assume below that other bit operations are represented as order-1 non-terminals of HORS. For example, the bit complement Not and $\ell$-ary disjunction $\mathrm{OR}_{\ell}$ can be defined by the following rewriting rules:

$$
\begin{aligned}
& \text { Not } x \rightarrow \text { if } x 01 \\
& \mathrm{OR}_{1} x \rightarrow x \quad \mathrm{OR}_{\ell} x_{1} \cdots x_{\ell} \rightarrow \text { if } x_{1} 1\left(\mathrm{OR}_{\ell-1} x_{2} \cdots x_{\ell}\right)
\end{aligned}
$$

We introduce the HORS types Bit $^{\star}=\star$ and Num $_{i}^{\star}$ for all $i \geq 2$ as follows: $\operatorname{Num}_{2}^{\star}=\underbrace{\star \rightarrow \cdots \rightarrow \star}_{r} \rightarrow \star$, and for all $i \geq 2$, $\mathbf{N u m}_{i+1}^{\star}=\mathbf{N u m}_{i}^{\star} \rightarrow \star$ (note that $\mathbf{N u m}_{1}^{\star}$ is undefined only because HORS types do not have product).

For the purpose of encoding HFL formulas, we need to prepare the following terms of HORS:

```
Max}\mp@subsup{i}{i}{: Num
\mp@subsup{\operatorname{Dec}}{i}{}:\mp@subsup{N}{Num}{i}
```


(which represents $\exp _{i}(r)-1$ )
(decrement function)
(check if the argument is 0 )
for all $i \geq 2$. They are defined as follows, using the auxiliary functions ExistsOne ${ }_{i}$ and DecSub $_{j}$ :

```
\(\operatorname{Max}_{1} \equiv(1, \ldots, 1) \quad \operatorname{Max}_{i+1} g \rightarrow 1\)
\(\operatorname{Dec}_{1}\left(b_{0}, \ldots, b_{r-1}\right) \equiv\)
    \(\left(\operatorname{DecSub}_{0} b_{0}, \ldots\right.\), DecSub \(\left._{r-1} b_{0} \cdots b_{r-1}\right)\)
\(\operatorname{DecSub}_{0} b_{0} \rightarrow\) Not \(b_{0}\)
\(\mathrm{DecSub}_{j} b_{0} \cdots b_{j} \rightarrow\)
    (* Flip \(b_{j}\) only if \(b_{0}, \ldots, b_{j-1}\) are all \(0 *\) )
        if \(\left(\mathrm{OR}_{j} b_{0} \cdots b_{j-1}\right) b_{j}\left(\operatorname{Not} b_{j}\right)\)
\(\operatorname{Dec}_{i+1} f n \rightarrow\)
    (* Flip the \(n\)-th bit of \(f\) only if all the lower bits are \(0 .{ }^{*}\) )
        if \(\left(\right.\) ExistsOne \(\left._{i+1} f n\right)(f n)(\operatorname{Not}(f n))\)
ExistsOne \({ }_{i+1} f n \rightarrow\)
    (* Check whether some bit of \(f\) lower than the n-th bit is 0 *)
        if (IsZero \({ }_{i} n\) ) 0
                        \(\left(\mathrm{OR}_{2}\left(f\left(\operatorname{Dec}_{i} n\right)\right)\left(\right.\right.\) ExistsOne \(\left.\left.\left._{i+1} f\left(\operatorname{Dec}_{i} n\right)\right)\right)\right)\)
IsZero \(_{1}\left(b_{0}, \ldots, b_{r-1}\right) \rightarrow \operatorname{Not}\left(\mathrm{OR}_{r} b_{0} \cdots b_{r-1}\right)\)
IsZero \(_{i+1} f \rightarrow \operatorname{Not}\left(\mathrm{OR}_{2}\left(f \operatorname{Max}_{i}\right)\left(\right.\right.\) ExistsOne \(\left.\left._{i+1} f \operatorname{Max}_{i}\right)\right)\).
```

Here, $\equiv$ indicates that the lefthand side is a shorthand (or a macro) for the righthand side, and $\rightarrow$ indicates that the head symbol on the lefthand side is a non-terminal of HORS defined by the rewriting rule. The meta-variable $i$ ranges over $\{1, \ldots, k-1\}$, and $j$ ranges over $\{1, \ldots, r\}$. The encodings above should be easy to understand; $\operatorname{Max}_{i}$ represents the number whose bit representation is $\underbrace{11 \cdots 1}$,
$\boldsymbol{e x p}_{i-1}(r)$
hence defined as a function that always returns 1.
The following lemma states the correctness of our number encoding.
Lemma 20. Let $T$ be the tree generated by $\operatorname{IsZero}_{i}\left(\operatorname{Dec}_{i}^{m} \operatorname{Max}_{i}\right)$. Then, (i) if $m=\exp _{i}(r)-1$, then $T \Downarrow 1$; (ii) if $m<\exp _{i}(r)-1$, then $T \Downarrow 0$.

### 6.3 The Translation

Let $\mathcal{L}$ be an LTS $\left(U, A, \longrightarrow, s_{\text {init }}\right)$, and $\mathcal{E}$ be an order- $k$ HES $F_{n}={ }_{\alpha_{n}} \varphi_{n} ; \cdots ; F_{0}=\alpha_{0} \varphi_{0}$ where $F_{i}$ is of type $\eta_{i}$ (and thus $\eta_{n}=\bullet$ ). We assume that each $\varphi_{j}$ is of the form $\lambda x_{1} \cdots \lambda x_{\ell_{j}} \cdot \psi_{j}$ such that $\psi_{j}$ does not contain lambda abstractions.

Let $h_{j}$ be the height of the lattice of $D_{\eta_{j}}$, and $M$ the largest arity of types occurring in $\eta_{0}, \ldots, \eta_{n}$. By [2], Lemma 3.5, $\exp _{k}(r)-$ $1 \geq \max \left(h_{0}, \ldots, h_{n}\right)$ for $r>\log |U|+|U| \cdot(M+k)^{k}$. Let mh be $\exp _{k}(r)-1$ for the least such natural number $r$. Note that $r$ is polynomial in $|U|$ and $M$, assuming that the order $k$ of $\mathcal{E}$ is a constant.

Let $\beta=\left(\beta_{n}, \ldots, \beta_{j}\right)$ be a collection of non-negative integers. If $\beta_{j}>0$, define

$$
\begin{array}{ll}
\beta(\ell)=\left(\beta_{n}, \ldots, \beta_{\ell}\right) & \text { if } \ell>j \\
\beta(\ell)=(\beta_{n}, \ldots, \beta_{j}-1, \underbrace{\mathbf{m h}, \ldots, \mathbf{m h}}_{j-\ell \text { times }}) & \text { if } \ell \leq j
\end{array}
$$

Let $<$ be the lexicographic order on $\beta$ 's, i.e., the least transitive relation that satisfies: $\left(\beta_{n}, \ldots, \beta_{j+1}\right)<\left(\beta_{n}, \ldots, \beta_{j+1}, \beta_{j}\right)$ and $\left(\beta_{n}, \ldots, \beta_{j+1}, \beta_{j}\right)<\left(\beta_{n}, \ldots, \beta_{j+1}, \beta_{j}+1\right)$. We define the HFL formula $F_{j}^{\left(m_{n}, \ldots, m_{j}\right)}$ for each $j \in\{0, \ldots, n\}, m_{n}, \ldots, m_{j} \in$ $\{0, \ldots, \mathbf{m h}\}$ as follows, by well-founded induction on $<$.

$$
\begin{aligned}
& F_{j}^{\left(m_{n}, \ldots, m_{j+1}, 0\right)}=\lambda x_{1} \cdot \cdots \lambda x_{\ell_{j}} \cdot \widehat{\alpha_{j}} \\
& F_{j}^{\beta}=\left[F_{0}^{\beta(0)} / F_{0}, \ldots, F_{n}^{\beta(n)} / F_{n}\right] \varphi_{j} \\
& \quad \text { if } \beta=\left(m_{n}, \ldots, m_{j}\right) \text { with } m_{j}>0 .
\end{aligned}
$$

Here, $\widehat{\alpha_{j}}=\top$ if $\alpha_{j}=\nu$ and $\widehat{\alpha_{j}}=\perp$ if $\alpha_{j}=\mu$. By the Kleene Fixpoint Theorem, we have:
Lemma 21. $\llbracket t o H F L(\mathcal{E}) \rrbracket=\llbracket F_{n}^{(\mathbf{m h})} \rrbracket$.

Since $F_{n}^{(\mathbf{m h})}$ contains no fixpoint operators, we can reduce it to a formula in basic modal logic. Below we create a HORS that generates the syntax tree of this formula.

For each $F_{j}(j \in\{0, \ldots, n\})$ of $\mathcal{E}$, we prepare a non-terminal of the same name $F_{j}$ of a HORS, and the following rewriting rule:

$$
\begin{aligned}
& F_{j} y_{n}, \ldots, y_{j}, x_{1}, \ldots, x_{\ell_{j}} \rightarrow \\
& \quad \text { if }\left(\text { IsZero }_{k} y_{j}\right) \widehat{\alpha_{j}}\left(\llbracket \psi_{j} \rrbracket_{y_{n}, \ldots, y_{j+1}, \operatorname{Dec}_{k}\left(y_{j}\right)}\right) .
\end{aligned}
$$

Here, $\llbracket \psi_{j}^{\prime} \rrbracket_{y_{n}, \ldots, y_{j}}$ is defined by induction on formulas:

$$
\begin{aligned}
& \llbracket c \rrbracket_{y_{n}, \ldots, y_{j}}=c \quad \llbracket x_{\ell} \rrbracket_{y_{n}, \ldots, y_{j}}=x_{\ell} \\
& \llbracket F_{\ell} \rrbracket_{y_{n}, \ldots, y_{j}}= \begin{cases}F_{\ell} y_{n} \ldots y_{\ell} & \text { if } \ell \geq j \\
F_{\ell} y_{n} \ldots y_{j} \underbrace{\operatorname{Max}_{k} \ldots \operatorname{Max}_{k}}_{j-l \text { times }} & \text { if } \ell<j \\
\llbracket \varphi_{1} \varphi_{2} \rrbracket_{y_{n}, \ldots, y_{j}}=\llbracket \varphi_{1} \rrbracket_{y_{n}, \ldots, y_{j}} \llbracket \varphi_{2} \rrbracket_{y_{n}, \ldots, y_{j}}\end{cases}
\end{aligned}
$$

Here, $c$ ranges over $\vee, \wedge,\langle a\rangle,[a], \top, \perp$; so, for example, $\varphi_{1} \wedge \varphi_{2}$ is considered as $\left(\wedge \varphi_{1}\right) \varphi_{2}$ in the above definition. In the image of the translation, those constants are treated as tree constructors of the HORS. The arguments $y_{1}, \ldots, y_{j}$ are of type $\mathbf{N u m}_{k}^{\star}$; intuitively, $F_{j} \llbracket n_{1} \rrbracket_{k} \cdots \llbracket n_{j} \rrbracket_{k}$ corresponds to $F_{j}^{\left(n_{1}, \ldots, n_{j}\right)}$.

We write $\mathcal{G}_{\mathcal{E}, \mathcal{L}^{8}}$ for the HORS consisting of the above rules for $F_{j}, S \rightarrow F_{n} \operatorname{Max}_{k}$ (where $S$ is the start symbol), and the rules in Section 6.2 for encoding numbers.
Example 15. Recall the LTS $\mathcal{L}_{0}$ from Example 4, and the HES $\mathcal{E}_{0}$ from Example 6:

$$
\begin{aligned}
& S={ }_{\nu} F B ; \quad F={ }_{\nu} \lambda X: \bullet \rightarrow \bullet .\langle a\rangle(X(F(G X))) ; \\
& G={ }_{\nu} \lambda X: \bullet \rightarrow \rightarrow . \lambda Y: \bullet .\langle b\rangle(X Y) ; \quad B={ }_{\nu} \lambda Y: \bullet .\langle b\rangle Y .
\end{aligned}
$$

We obtain the HORS $\mathcal{G}_{\mathcal{E}_{0}, \mathcal{L}_{0}}$ with

$$
\begin{aligned}
& S^{\prime} \rightarrow S \operatorname{Max}_{2} \\
& S y_{S} \rightarrow \text { if }\left(\text { IsZero }_{2} y_{S}\right) \top \\
& \quad\left(F\left(\operatorname{Dec}_{2} y_{S}\right) \operatorname{Max}_{2}\left(B y_{S} \operatorname{Max}_{2} \operatorname{Max}_{2} \operatorname{Max}_{2}\right)\right) \\
& F y_{S} y_{F} x \rightarrow \\
& \quad \text { if }\left(\text { IsZero }_{2} y_{F}\right) \top \\
& \quad\left(\langle a\rangle\left(x\left(F y_{S}\left(\operatorname{Dec}_{2} y_{F}\right)\left(G y_{S}\left(\operatorname{Dec}_{2} y_{F}\right) \operatorname{Max}_{2} x\right)\right)\right)\right)
\end{aligned}
$$

$G y_{S} y_{F} y_{G} x y \rightarrow \operatorname{if}\left(\right.$ IsZero $\left._{2} y_{G}\right) \top(\langle b\rangle(x y))$
$B y_{S} y_{F} y_{G} y_{B} y \rightarrow$ if (IsZero $\left.{ }_{2} y_{B}\right) \top(\langle b\rangle y)$
where the $y_{j}$ 's have been renamed to their respective nonterminal for ease of understanding and the parameters $x_{j}$ have been renamed to lower case versions of their HFL correspondents, and the rules for $\mathrm{Dec}_{2}$ and $\mathrm{IsZero}_{2}$ are as per their definition.

Let $\mathcal{A}_{\mathcal{L}}$ be the APT $\left(\left\{q_{s} \mid s \in U\right\} \cup\left\{q_{1}, q_{0}\right\}, \Sigma, \delta, q_{s_{\text {init }}}, \Omega\right)$ where:

$$
\begin{aligned}
& \Sigma=\Sigma_{\text {Bit }} \cup\{\vee \mapsto 2, \wedge \mapsto 2, \top \mapsto 0, \perp \mapsto 0\} \\
& \cup \bigcup_{a \in A}\{\langle a\rangle \mapsto 1,[a] \mapsto 1\} \\
& \delta\left(q_{s},\langle a\rangle\right)=\vee\left\{\left(1, q_{s^{\prime}}\right) \mid s \xrightarrow{a} s^{\prime}\right\} \\
& \delta\left(q_{s},[a]\right)=\wedge\left\{\left(1, q_{s^{\prime}}\right) \mid s \xrightarrow{a} s^{\prime}\right\} \\
& \delta\left(q_{s}, \mathrm{~T}\right)=\mathrm{tt} \quad \delta\left(q_{s}, \perp\right)=\mathrm{ff} \\
& \delta\left(q_{s}, \vee\right)=\left(1, q_{s}\right) \vee\left(2, q_{s}\right) \quad \delta\left(q_{s}, \wedge\right)=\left(1, q_{s}\right) \wedge\left(2, q_{s}\right) \\
& \delta\left(q_{s}, 1\right)=\delta\left(q_{s}, 0\right)=\mathrm{ff} \quad(\text { for each } s \in U) \\
& \delta(q, \text { if })=\left(\left(1, q_{1}\right) \wedge(2, q)\right) \vee\left(\left(1, q_{0}\right) \wedge(3, q)\right) \\
& \text { (for every } q \in\left\{q_{s} \mid s \in U\right\} \cup\left\{q_{1}, q_{0}\right\} \text { ) } \\
& \delta\left(q_{1}, 1\right)=\mathrm{tt} \quad \delta\left(q_{1}, a\right)=\mathrm{ff} \text { if } a \notin\{1, \text { if }\} \\
& \delta\left(q_{0}, 0\right)=\mathrm{tt} \quad \delta\left(q_{0}, a\right)=\mathrm{ff} \text { if } a \notin\{0, \mathrm{if}\}
\end{aligned}
$$

and $\Omega(q)=1$ for every $q$. Note that $\mathcal{A}_{\mathcal{L}}$ is an extension of the automaton $\mathcal{A}^{\text {Bit }}$ in the previous subsection.

Theorem 22. Let $\mathcal{L}$ be an LTS and let $\mathcal{E}$ be an HES. Then $\mathcal{A}_{\mathcal{L}}$ accepts the tree generated by $\mathcal{G}_{\mathcal{E}, \mathcal{L}}$ if and only if $\mathcal{L} \models \mathcal{E}$. The size

[^7]of $\mathcal{G}_{\mathcal{E}, \mathcal{L}}$ is polynomial in the size of $\mathcal{E}$ and $\mathcal{L}$; and $\mathcal{A}_{\mathcal{L}}$ has $m+2$ states where $m$ is the number of states of $\mathcal{L}$. Furthermore, they can be constructed in time polynomial in the size of $\mathcal{E}$ and $\mathcal{L}$ (assuming that the order $k$ of $\mathcal{E}$ is a constant).

By the above theorem, the reduction combined with an optimal algorithm for HORS model checking yields an $k$-EXPTIME HFL model checking algorithm, which is optimal [2].

## 7. Related Work

The model checking problem for HORS has been studied since around 2000. Knapik et al. [8] proved the decidability of the problem for HORS with the safety restriction, and Ong [24] proved the decidability for arbitrary HORS, without the safety restriction and showed that the problem is $k$-EXPTIME complete for order- $k$ HORS. Since Ong's proof was complex, a number of alternative proofs have been developed since then $[6,13,27,31]$. Among others, Kobayashi and Ong [12, 13] have provided a type-based characterization of HORS model checking, which inspired our type system for HFL model checking in Section 4. The type-based characterization of HORS model checking has lead to development of practical algorithms for HORS model checking [3,10, 11, 23, 26]. We therefore expect that our type-based characterization of HFL model checking also yields practical algorithms for HFL model checking. The proof of the correctness of our type-based characterization (found in Appendix A) has been partially inspired by Salvati and Walukiewicz's model theoretic approach to HORS model checking [28]. On the practical side, HORS model checking has been applied to automated verification of higher-order programs [9, 16-18, 22, 25, 32, 34].

Independently of the above line of work, Viswanathan and Viswanathan [33] introduced HFL, a higher-order extension of modal $\mu$-calculus, and showed that, while model checking remains decidable for finite state systems, HFL is strictly more expressive than modal $\mu$-calculus and FLC (Modal Fixpoint Logic with Chop) [21], another extension of modal $\mu$-calculus. Axelsson et al. [2] proved that the model checking problem for order- $k$ HFL formulas is $k$-EXPTIME complete. The state of the art on practical algorithms for HFL model checking is much behind that on HORS model checking algorithms. In [19], the authors sketch a global model-checking algorithm that does not compute the entire representation of functions, but relies on neededness analysis in order to partially represent them. By contrast, the typing game presented in this paper may be seen as a higher-order extension of local model-checking [30].

Somewhat surprisingly, despite that both problems are higherorder extensions of finite state model checking that have been introduced and studied in the 2000's, and despite that both are $k$-EXPTIME complete for the order- $k$ fragment, we are not aware of any previous work that studies the connection between HORS and HFL model checking. The translation from HORS to HFL in Section 3 has been partially inspired by Kobayashi and Ong's type system for HORS model checking [13]. Their type system statically keeps track of the largest priority of states visited using types, whereas our translation dynamically keeps that information by duplicating arguments. This fact is reflected in the translation from their types to our types for HFL presented in Section 3. The translation from HORS to HFL model checking may also have some connection to Salvati and and Walukiewicz's recent work [29], which uses a model-theoretic approach to reduce HORS model checking to nested least/greatest fixpoint computations. In the translation from HFL to HORS, the key challenge was how to encode big numbers into order- $(k-1)$ terms of HORS. Our encoding may be seen as a combination of Jones' encoding of big numbers as functions [7], and encoding of Boolean expressions into order-0 terms (with an added automaton to evaluate these expressions); the
latter encoding was used in the benchmark of the HORS model checker Preface [26].

## 8. Conclusion

We have presented mutual translations between the HORS and HFL model checking problems, both higher-order extensions of finite state model checking. We have also proved the correctness of both translations. These translations preserve complexity, in the sense that the translation followed by an optimal algorithm for the target problem yields an optimal (i.e., $k$-EXPTIME) algorithm for the source problem. The results reveal the close connection between the two problems, enabling the cross-fertilization of the two threads of research. The type-based characterization of HFL model checking developed in Section 4 may be seen as the first outcome of such cross-fertilization, which may yield a practical algorithm for HFL model checking.

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## Appendix

## A. Proof of Theorem 13

We fix an LTS $\mathcal{L}=\left(U, A, \longrightarrow, s_{\text {init }}\right)$ and a HES:

$$
\mathcal{E}:=\left(F_{n}^{\eta_{n}}=\alpha_{n} \varphi_{n} ; \cdots ; F_{0}^{\eta_{0}}={ }_{\alpha_{0}} \varphi_{0}\right)
$$

where $\eta_{n}=\bullet$.
We assume: (i) $\alpha_{k}$ is $\nu$ if $k$ is even and $\mu$ otherwise; and (ii) $F_{n}$ occurs in none of $\varphi_{0}, \ldots, \varphi_{n}$. Those assumptions do not lose generality, because (i) if $\alpha_{i}=\alpha_{i+1}=\mu\left(\alpha_{i}=\alpha_{i+1}=\mu\right.$, resp. , then we can insert a dummy equation $F^{\bullet}={ }_{\nu} F\left(F^{\bullet}={ }_{\mu} F\right.$, resp.) between the equations for $F_{i}$ and $F_{i+1}$, without changing the semantics and typability of $\mathcal{E}$; and (ii) if $F_{n}$ occurs in $\varphi_{i}$, we can add $F_{n+1}^{\bullet}={ }_{\alpha_{n+1}} F_{n}$. By the assumption above, $\Omega\left(F_{k}\right)=k$.

As sketched in Section 4, we show Theorem 13 through semantic typability games. We first define the semantics of types and semantic typability games in Section A.1. We then introduce in Section A. 2 the semantic typability game, a semantic counterpart of the typability game defined in Section 4, and show that it is equivalent to the (syntactic) typability game introduced in Section 4. We then show soundness and completeness of the semantic typability game (with respect to $\mathcal{L} \models \mathcal{E}$ ) in Sections A. 3 and A. 4 respectively.

## A. 1 Semantics of types

The semantics of types $D_{\tau}\left(\subseteq D_{\operatorname{Stype}(\tau)}\right)$ and $D_{\sigma}\left(\subseteq D_{\operatorname{Stype}(\sigma)}\right)$ are defined by:

$$
\begin{aligned}
& D_{s}=\left\{x \in D_{\bullet} \mid s \in x\right\} \\
& D_{\tau_{1} \wedge \cdots \wedge \tau_{k}}=D_{\tau_{1}} \cap \cdots \cap D_{\tau_{k}} \\
& D_{\sigma \rightarrow \tau}= \\
& \quad\left\{f \in D_{\operatorname{Stype}(\sigma) \rightarrow \operatorname{Stype}(\tau)} \mid \forall x \in D_{\sigma .} f(x) \in D_{\tau}\right\}
\end{aligned}
$$

Recall that we are assuming that each $\tau$ or $\sigma$ is implicitly annotated with the corresponding simple type, so that $\operatorname{Stype}(\tau)$ and $\operatorname{Stype}(\sigma)$ are well defined. For each intersection type $\tau$, we define $\perp_{\tau} \in D_{\tau}$ by:

$$
\begin{aligned}
& \perp_{s}=\{s\} \\
& \perp_{\sigma \rightarrow \tau}= \\
& \quad \lambda x \cdot \begin{cases}\perp_{\tau} & \text { if } x \in D_{\sigma} \\
\perp_{\text {Stype }(\tau)} & \text { otherwise }\end{cases} \\
& \perp_{\tau_{1} \wedge \cdots \wedge \tau_{k}}^{=\perp_{\tau_{1}} \sqcup_{\operatorname{Stype}\left(\tau_{1}\right)} \cdots \sqcup_{\operatorname{Stype}\left(\tau_{1}\right)} \perp_{\tau_{k}}}
\end{aligned}
$$

When $\tau:: \eta$, the restriction of $\left(D_{\eta}, \sqcup_{\eta}, \sqcap_{\eta}\right)$ to $D_{\tau}$ forms a complete sublattice, having $\perp_{\tau}$ as the least element.

Lemma 23. Suppose $\tau:: \eta$. Then, the following conditions hold.

1. If $x, y \in D_{\tau}$, then $x \sqcup_{\eta} y, x \sqcap_{\eta} y \in D_{\tau}$.
2. $D_{\tau}$ is upward-closed, i.e., $x \in D_{\tau}$ and $x \sqsubseteq_{\eta} y$ imply $y \in D_{\tau}$. 3. $\perp_{\tau}$ is the least element of $D_{\tau}$.
3. If $x \in D_{\eta}$, then $x \in D_{\tau}$ if and only if $\perp_{\tau} \sqsubseteq_{\eta} x$.

Proof. The first property can be shown by induction on $\eta$.

- If $\eta=\bullet$, then $\tau=\bigwedge_{q \in Q} q$ for some $Q \subseteq U$ with $Q \subseteq x$, $Q \subseteq y$. So $Q \subseteq x \cap y \subseteq x \cup y$, henceforth $x \sqcap \bullet y, x \sqcup \bullet y \in D_{\tau}$.
- Assume $\eta=\eta_{1} \rightarrow \eta_{2}$ and the property 1 holds for $\eta_{2}$. Let $x, y \in D_{\eta_{1} \rightarrow \eta_{2}}$. For all $z \in D_{\eta_{1}}$. Then $\left(x \sqcap_{\eta_{1} \rightarrow \eta_{2}} y\right)(z)=$ $x(z) \sqcap_{\eta_{2}} y(z) \in D_{\eta_{2}}$ and $\left(x \sqcup_{\eta_{1} \rightarrow \eta_{2}} y\right)(z)=x(z) \sqcup_{\eta_{2}} y(z) \in$ $D_{\eta_{2}}$ by induction, henceforth $x \sqcap_{\eta_{1} \rightarrow \eta_{2}} y, x \sqcup_{\eta_{1} \rightarrow \eta_{2}} y \in$ $D_{\eta_{1} \rightarrow \eta_{2}}$.

The second and third properties also follow by straightforward induction on $\eta$. The fourth property follows as an immediate corollary of the second and third properties.

Lemma 24. If $\sigma \leq \sigma^{\prime}$ has a derivation then $D_{\sigma} \subseteq D_{\sigma^{\prime}}$.

Proof. By straightforward induction on the derivation of $\sigma \leq \sigma^{\prime}$ (see the three rules HFL-T-SubT-Base, HFL-SubT-Fun, and HFL-SubT-Int of Figure 4).

Let $\rho$ be an interpretation (i.e., a map from a finite set of variables to $\bigcup_{\eta} D_{\eta}$ ). We write $\rho \models \Gamma$ if $\rho(X) \in D_{\tau}$ for every binding $X: \tau \in \operatorname{dom}(\Gamma)$. We write $\Gamma \models \varphi: \tau(\Gamma \models \varphi: \sigma$, resp.) if $\llbracket \varphi \rrbracket(\rho) \in D_{\tau}\left(\llbracket \varphi \rrbracket(\rho) \in D_{\sigma}\right.$, resp.) holds for every interpretation $\rho$ such that $\rho \models \Gamma$.

We shall show that, for any formula $\varphi$ that does not contain fixpoint operators, the syntactic type judgment $\Gamma \vdash \varphi: \tau$ is sound and complete with respect to the semantic type judgment $\Gamma \models \varphi: \tau$
Lemma 25 (soundness of syntactic type judgment). Let $\varphi$ be a formula without fixpoint operators. Then, $\Gamma \vdash \varphi: \tau$ implies $\Gamma \models \varphi: \tau$.

Proof. By induction on the derivation of $\Gamma \vdash \varphi: \tau$.

- Case HFL-T-True: since $\tau=s \in U, \Gamma \models \top: \tau$.
- Case HFL-T-VAR: since $X: \tau \in \Gamma$, for any $\rho \models \Gamma, \rho \models X: \tau$.
- Case HFL-T-Some: then $\varphi=\langle a\rangle \varphi^{\prime}, \tau=s \in U, s \xrightarrow{a} s^{\prime}$, and $\Gamma \vdash \varphi^{\prime}: s^{\prime}$ for some $s^{\prime}$. By induction, $\Gamma \models \varphi^{\prime}: s^{\prime}$, and by HFL semantics, $\Gamma \models\langle a\rangle \varphi^{\prime}: s$.
- Case HFL-T-AlL: similar to previous case.
- Case HFL-T-AND: then $\varphi=\varphi_{1} \wedge \varphi_{2}, \tau=s \in U, \Gamma \vdash \varphi_{1}: s$, and $\Gamma \vdash \varphi_{2}: s$. By induction, $\Gamma \models \varphi_{1}: s$, and $\Gamma \models \varphi_{2}: s$, and by HFL semantics, $\Gamma \models \varphi_{1} \wedge \varphi_{2}: s$.
- Case HFL-T-OR: similar to previous case.
- Case HFL-T-ABS: then $\varphi=\lambda X: \eta \cdot \varphi^{\prime}, \tau=\tau_{1} \wedge \cdots \wedge \tau_{l} \rightarrow \tau^{\prime}$, and $\Gamma, X: \tau_{1}, \ldots, X: \tau_{k} \vdash \varphi^{\prime}: \tau^{\prime}$ for some $X \notin \operatorname{dom}(\Gamma)$. Let $\rho$ be such that $\rho=\Gamma$, and let $x \in D_{\tau_{1}} \sqcap \cdots \sqcap D_{\tau_{k}}$. Then $\rho \uplus\{X \mapsto x\} \models \Gamma,: \tau_{1}, \ldots, X: \tau_{k}$, thus by induction hypothesis $\rho \uplus\{X \mapsto x\} \models \varphi^{\prime}: \tau^{\prime}$. Since it holds for all such $x$, and by definition of $D_{\tau}, \rho \models \lambda X: \eta \cdot \varphi^{\prime}: \tau_{1} \wedge \cdots \wedge \tau_{k} \rightarrow \tau^{\prime}$, and since this holds for all such $\rho, \Gamma \models \lambda X: \eta \cdot \varphi^{\prime}: \tau_{1} \wedge \cdots \wedge \tau_{k} \rightarrow \tau^{\prime}$.
- Case HFL-T-ApP: then $\varphi=\varphi_{1} \varphi_{2}, \Gamma \vdash \varphi_{1}: \tau^{\prime}$ with $\tau^{\prime}=\tau_{1} \wedge \cdots \wedge \tau_{k} \rightarrow \tau$ and $\Gamma \vdash \varphi_{2}: \tau_{i}$ for all $i=1, \ldots, k$. Let $\rho$ be such that $\rho \models \Gamma$. By induction hypothesis, $\rho \models \varphi_{1}$ : $\tau_{1} \wedge \cdots \wedge \tau_{k} \rightarrow \tau$ and $\rho \models \varphi_{2}: \tau_{i}$ for all $i=1, \ldots, k$. By definition of $D_{\tau^{\prime}}$, it holds that $\rho \models \varphi_{1} \varphi_{2}: \tau$. Since this holds for all such $\rho, \Gamma \models \varphi_{1} \varphi_{2}: \tau$.
- Case HFL-T-SUB: straightforward by Lemma 24.

To prove the converse (completeness), we need some preparation. Given a type environment $\Gamma$, we define a canonical interpretation $\rho_{\Gamma}$ by:

$$
\operatorname{dom}\left(\rho_{\Gamma}\right)=\operatorname{dom}(\Gamma) \quad \rho_{\Gamma}(X)=\perp_{\Gamma(X)}
$$

We have:
Lemma 26. $\Gamma \models \varphi: \tau$ iff $\llbracket \varphi \rrbracket\left(\rho_{\Gamma}\right) \in D_{\tau}$ iff $\perp_{\tau} \sqsubseteq \llbracket \varphi \rrbracket\left(\rho_{\Gamma}\right)$.
Proof. • $\Gamma \models \varphi: \tau \Longrightarrow \llbracket \varphi \rrbracket\left(\rho_{\Gamma}\right) \in D_{\tau}$ : This follows immediately from the definition of $\Gamma \models \varphi: \tau$ and the fact $\rho_{\Gamma} \models \Gamma$.

- $\llbracket \varphi \rrbracket\left(\rho_{\Gamma}\right) \in D_{\tau} \Longrightarrow \Gamma \models \varphi: \tau$ : Suppose $\rho \models \Gamma$. Then, by the definition of $\rho_{\Gamma}$ and Lemma 23, we have $\rho_{\Gamma}(X) \sqsubseteq \rho(X)$ for every $X \in \operatorname{dom}(\Gamma)$. Thus, by the monotonicity of $\llbracket \varphi \rrbracket$ and the upward-closedness of $D_{\tau}$ (Lemma 23), we have $\llbracket \varphi \rrbracket(\rho) \in D_{\tau}$.
- $\llbracket \varphi \rrbracket\left(\rho_{\Gamma}\right) \in D_{\tau}$ iff $\perp_{\tau} \sqsubseteq \llbracket \varphi \rrbracket\left(\rho_{\Gamma}\right)$ follows immediately from Lemma 23.

For each value $x \in D_{\eta}$, we define the corresponding type $\sigma_{x, \eta}$ by:

$$
\begin{aligned}
& \sigma_{x, \bullet}=\bigwedge\{s \mid s \in x\} \\
& \sigma_{x, \eta_{1} \rightarrow \eta_{2}}^{=} \bigwedge_{y \in D_{\eta_{1}}}\left(\sigma_{y, \eta_{1}} \rightarrow \sigma_{x y, \eta_{2}}\right)
\end{aligned}
$$

Here, $\sigma_{1} \rightarrow \sigma_{2}$ is defined by:

$$
\sigma_{1} \rightarrow\left(\tau_{1} \wedge \cdots \wedge \tau_{k}\right)=\left(\sigma_{1} \rightarrow \tau_{1}\right) \wedge \cdots \wedge\left(\sigma_{1} \rightarrow \tau_{k}\right)
$$

Lemma 27. If $x \in D_{\eta}$, then $x \sqsubseteq_{\eta} y$ if and only if $y \in D_{\sigma_{x, \eta}}$.
Proof. We first show that $x \in D_{\eta}$ implies $x=\perp_{\sigma_{x, \eta}}$ by induction on $\eta$.

- Case $\eta=\bullet$ : In this case, $x=\left\{s_{1}, \ldots, s_{k}\right\}$ and $\sigma_{x, \eta}=$ $s_{1} \wedge \cdots \wedge s_{k}$. Thus, $x \in \perp_{\sigma_{x, \eta}}$ follows immediately.
- Case $\eta=\eta_{1} \rightarrow \eta_{2}$ : In this case, we have:

$$
D_{\sigma_{x, \eta}}=\bigwedge_{y \in D_{\eta_{1}}}\left(\sigma_{y, \eta_{1}} \rightarrow \sigma_{x y, \eta_{2}}\right)
$$

Suppose $y^{\prime} \in D_{\eta_{1}}$. We need to show

$$
x y^{\prime}=\sqcup_{\eta_{2}}\left\{\perp_{\sigma_{x y, \eta_{2}}} \mid \perp_{\sigma_{y, \eta_{1}}} \sqsubseteq y^{\prime}\right\} .
$$

By the induction hypothesis, the righthand side is equal to:

$$
\sqcup_{\eta_{2}}\left\{x y \mid y \sqsubseteq y^{\prime}\right\}=x y^{\prime}
$$

as required.
Now, If $x \in D_{\eta}$ and $x \sqsubseteq_{\eta} y$, then $\perp_{\sigma_{x, \eta}}=x \sqsubseteq_{\eta} y$. Thus, by Lemma 23, we have $y \in D_{\sigma_{x, \eta}}$. Conversely, if $x \in D_{\eta}$ and $y \in D_{\sigma_{x, \eta}}$, then $x=\perp_{\sigma_{x, \eta}} \sqsubseteq_{\eta} y$, as required.

Lemma 28. If $\perp_{\tau} \sqsubseteq_{\operatorname{Stype}(\tau)} \perp_{\tau^{\prime}}$, then $\tau^{\prime} \leq \tau$.
Proof. We show that $\perp_{\tau} \sqsubseteq_{\text {Stype }(\tau)} \perp_{\tau_{1} \wedge \cdots \wedge \tau_{k}}$ implies $\tau_{i} \leq \tau$ for some $i \in\{1, \ldots, k\}$ by induction on the structure of $\eta=\operatorname{Stype}(\tau)$. The lemma follows as a special case, where $k=1$.

- Case $\eta=\bullet$ : In this case, $\tau=s$ and $\tau_{i}=s_{i}$. Thus, by the assumption $\perp_{\tau} \sqsubseteq_{\eta} \perp_{\tau_{1} \wedge \cdots \wedge \tau_{k}}$, we have $\{s\} \subseteq\left\{s_{1}, \ldots, s_{k}\right\}$, which implies $\tau=s=s_{i}=\tau_{i}$ for some $i$.
- Case $\eta=\eta_{1} \rightarrow \eta_{2}$ : In this case, $\tau=\sigma \rightarrow \tau^{\prime}$ and $\tau_{i}=\sigma_{i} \rightarrow$ $\tau_{i}^{\prime}$. By the condition $\perp_{\tau} \sqsubseteq_{\eta} \perp_{\tau_{1} \wedge \cdots \wedge \tau_{k}}$, we have

$$
\perp_{\tau^{\prime}}=\perp_{\tau}\left(\perp_{\sigma}\right) \sqsubseteq_{\eta_{2}} \perp_{\tau_{1} \wedge \cdots \wedge \tau_{k}}\left(\perp_{\sigma}\right) .
$$

The righthand side is equal to:

$$
\sqcup_{\eta_{2}}\left\{\perp_{\tau_{i}^{\prime}} \mid i \in\{1, \ldots, k\}, \perp_{\sigma_{i}} \sqsubseteq \perp_{\sigma}\right\} .
$$

Thus, by the induction hypothesis, there must exist $i$ such that $\tau_{i}^{\prime} \leq \tau^{\prime}$ and $\perp_{\sigma_{i}} \sqsubseteq \perp_{\sigma}$. Let $\sigma=\tau_{1}^{\prime \prime} \wedge \cdots \wedge \tau_{m}^{\prime \prime}$ and $\sigma_{i}=\tau_{1}^{\prime \prime \prime} \wedge \cdots \wedge \tau_{n}^{\prime \prime \prime}$. Then $\perp_{\sigma_{i}} \sqsubseteq \perp_{\sigma}$ implies $\perp_{\tau_{j}^{\prime \prime \prime}} \sqsubseteq \perp_{\sigma}$ for each $j \in\{1, \ldots, n\}$. By the induction hypothesis, for each $j$, there exists $j^{\prime} \in\{1, \ldots, m\}$ such that $\tau_{j^{\prime}}^{\prime \prime} \leq \tau_{j}^{\prime \prime \prime}$. Thus, we have $\sigma \leq \sigma_{i}$. We have, therefore, $\tau_{i} \leq \tau$ as required.

We are now ready to prove the completeness of the syntactic type judgment.
Lemma 29 (completeness of syntactic type judgment). Let $\varphi$ be a formula without fixpoint operators. Then, $\Gamma \vDash \varphi: \tau$ implies $\Gamma \vdash \varphi: \tau$.

Proof. The proof proceeds by induction on the structure of $\varphi$.

- Case $\varphi=\mathrm{T}$ : Since $\llbracket \varphi \rrbracket\left(\rho_{\Gamma}\right)=U$, we have $U \in D_{\tau}$, which implies $\tau=s \in U$. Thus, by using HFL-T-TruE we obtain $\Gamma \vdash \varphi: \tau$.
- Case $\varphi=\perp$ : This cannot happen, since $\llbracket \perp \rrbracket(\rho)=\emptyset$.
- Case $\varphi=X$ : By Lemma 26, we have $\perp_{\tau} \sqsubseteq \llbracket X \rrbracket\left(\rho_{\Gamma}\right)=$ $\rho_{\Gamma}(X)=\perp_{\Gamma(X)}$. By Lemma 28, we have $\Gamma(X) \leq \tau$. By using HFL-T-VAR and HFL-T-SUB, we obtain $\Gamma \vdash \bar{X}: \tau$ as required.
- Case $\varphi=\langle a\rangle \varphi^{\prime}$ : By Lemma 26, we have:

$$
\perp_{\tau} \sqsubseteq \bullet \llbracket \varphi \rrbracket\left(\rho_{\Gamma}\right)=\left\{s \mid s \xrightarrow{a} s^{\prime}, s^{\prime} \in \llbracket \varphi^{\prime} \rrbracket\left(\rho_{\Gamma}\right)\right\} \text {. }
$$

Thus, $\tau=s$ with $s \xrightarrow{a} s^{\prime}$ and $s^{\prime} \in \llbracket \varphi^{\prime} \rrbracket\left(\rho_{\Gamma}\right)$ for some $s, s^{\prime}$. By $s^{\prime} \in \llbracket \varphi^{\prime} \rrbracket\left(\rho_{\Gamma}\right)$ and Lemma 26, we have $\Gamma \models \varphi^{\prime}: s^{\prime}$. By the induction hypothesis, we have $\Gamma \vdash \varphi^{\prime}: s^{\prime}$. Thus, by using HFL-T-Some, we obtain $\Gamma \vdash \varphi: \tau$ as required.

- Case $\varphi=[a] \varphi^{\prime}$ : By Lemma 26, we have:

$$
\perp_{\tau} \sqsubseteq \bullet \llbracket \varphi \rrbracket\left(\rho_{\Gamma}\right)=\left\{s \mid s \xrightarrow{a} s^{\prime} \Longrightarrow s^{\prime} \in \llbracket \varphi^{\prime} \rrbracket\left(\rho_{\Gamma}\right)\right\} .
$$

Thus, $\tau=s$ form some $s \in U$, and $s^{\prime} \in \llbracket \varphi^{\prime} \rrbracket\left(\rho_{\Gamma}\right)$ holds for every $s^{\prime} \in U$ such that $s \xrightarrow{a} s^{\prime}$. By Lemma 26 and the induction hypothesis, we have $\Gamma \vdash \varphi^{\prime}: s^{\prime}$ for every $s^{\prime} \in U$ such that $s \xrightarrow{a} s^{\prime}$. Thus, by using HFL-T-ALL, we obtain $\Gamma \vdash \varphi: \tau$ as required.

- Case $\varphi=\varphi_{1} \wedge \varphi_{2}$ : By Lemma 26, we have:

$$
\perp_{\tau} \sqsubseteq \bullet \llbracket \varphi \rrbracket\left(\rho_{\Gamma}\right)=\llbracket \varphi_{1} \rrbracket\left(\rho_{\Gamma}\right) \cap \llbracket \varphi_{2} \rrbracket\left(\rho_{\Gamma}\right) .
$$

Thus, by using Lemma 26 and the induction hypothesis, we get $\Gamma \vdash \varphi_{1}: \tau$ and $\Gamma \vdash \varphi_{2}: \tau$. Thus, by using HFL-T-AND, we obtain $\Gamma \vdash \varphi: \tau$ as required.

- Case $\varphi=\varphi_{1} \vee \varphi_{2}$ : By Lemma 26, we have:

$$
\perp_{\tau} \sqsubseteq \bullet \llbracket \varphi \rrbracket\left(\rho_{\Gamma}\right)=\llbracket \varphi_{1} \rrbracket\left(\rho_{\Gamma}\right) \cup \llbracket \varphi_{2} \rrbracket\left(\rho_{\Gamma}\right) .
$$

Thus, $\tau=s$ for some $s \in U$, and $s \in \llbracket \varphi_{i} \rrbracket\left(\rho_{\Gamma}\right)$ for $i=1$ or 2. By using Lemma 26 and the induction hypothesis, we get $\Gamma \vdash \varphi_{1}: \tau$ or $\Gamma \vdash \varphi_{2}: \tau$. Thus, by using HFL-T-OR, we obtain $\Gamma \vdash \varphi: \tau$ as required.

- Case $\varphi=\varphi_{1} \varphi_{2}$ : By the assumption $\Gamma \models \varphi_{1} \varphi_{2}: \tau$, we have:

$$
\llbracket \varphi_{1} \rrbracket\left(\rho_{\Gamma}\right)\left(\llbracket \varphi_{2} \rrbracket\left(\rho_{\Gamma}\right)\right) \in D_{\tau} .
$$

Suppose $x \in D_{\sigma_{\llbracket \varphi_{2} \rrbracket\left(\rho_{\Gamma}\right), \eta_{2}}}$, where $\eta_{2}$ is the simple type of $\varphi_{2}$. By Lemma 27, $\llbracket \varphi_{2} \rrbracket\left(\rho_{\Gamma}\right) \sqsubseteq x$. By the monotonicity of $\llbracket \varphi_{1} \rrbracket\left(\rho_{\Gamma}\right)$, we have $\llbracket \varphi_{1} \rrbracket\left(\rho_{\Gamma}\right)\left(\llbracket \varphi_{2} \rrbracket\left(\rho_{\Gamma}\right) \sqsubseteq \llbracket \varphi_{1} \rrbracket\left(\rho_{\Gamma}\right)(x)\right.$. Since $D_{\sigma_{\llbracket \varphi_{2} \rrbracket\left(\rho_{\Gamma}\right), \eta_{2}}}$ is upward-closed (Lemma 23), $\llbracket \varphi_{1} \rrbracket\left(\rho_{\Gamma}\right)(x) \in$ $D_{\tau}$. Thus, we have:

$$
\llbracket \varphi_{1} \rrbracket\left(\rho_{\Gamma}\right) \in D_{\sigma_{\llbracket \varphi_{2} \rrbracket\left(\rho_{\Gamma}\right), \eta_{2}} \rightarrow \tau} .
$$

By Lemma 26, we have $\Gamma \vDash \varphi_{1}: \sigma_{\llbracket \varphi_{2} \rrbracket\left(\rho_{\Gamma}\right), \eta_{2}} \rightarrow \tau$. By Lemma 27, we also have: $\llbracket \varphi_{2} \rrbracket\left(\rho_{\Gamma}\right) \in D_{\sigma_{\llbracket \varphi_{2}} \rrbracket\left(\rho_{\Gamma}\right), \eta_{2}}$, which implies

$$
\Gamma \models \varphi_{2}: \sigma_{\llbracket \varphi_{2} \rrbracket\left(\rho_{\Gamma}\right), \eta_{2}}
$$

by Lemma 26. By the induction hypothesis, we have $\Gamma \vdash \varphi_{1}$ : $\sigma_{\Pi \varphi_{2} \rrbracket\left(\rho_{\Gamma}\right), \eta_{2}} \rightarrow \tau$ and $\Gamma \vdash \varphi_{2}: \sigma_{\llbracket \varphi_{2} \rrbracket\left(\rho_{\Gamma}\right), \eta_{2}}$, which imply $\Gamma \vdash \varphi_{1} \varphi_{2}: \tau$ as required.

- Case $\varphi=\lambda X . \varphi^{\prime}$ : In this case, $\tau=\sigma \rightarrow \tau^{\prime}$ for some $\sigma$ and $\tau^{\prime}$. By the assumption $\Gamma \models \lambda X . \varphi^{\prime}: \tau$ and Lemma 26, we have $\llbracket \lambda X . \varphi^{\prime} \rrbracket\left(\rho_{\Gamma}\right) \in D_{\tau}$, which implies $\llbracket \lambda X . \varphi^{\prime} \rrbracket\left(\rho_{\Gamma}\right)\left(\perp_{\sigma}\right)=$ $\llbracket \varphi^{\prime} \rrbracket\left(\rho_{\Gamma}\left\{X \mapsto \perp_{\sigma}\right\}\right) \in D_{\tau^{\prime}}$. Thus, we have $\Gamma, X: \sigma \models \varphi^{\prime}: \tau^{\prime}$. By the induction hypothesis, we have $\Gamma, X: \sigma \vdash \varphi^{\prime}: \tau^{\prime}$. Therefore, we obtain $\Gamma \vdash \varphi: \tau$ as required.


## A. 2 Semantic typability games

We call

$$
F_{n}^{\eta_{n}}={ }_{\alpha_{n}} \varphi_{n} ; \cdots ; F_{j}^{\eta_{j}}=\alpha_{j} \varphi_{j}
$$

an extended $H E S$ if $\varphi_{i}$ may contain fixpoint operators. As for HES, we assume: (i) $\alpha_{k}$ is $\nu$ if $k$ is even and $\mu$ otherwise; and (ii) $F_{n}$ occurs in none of $\varphi_{j}, \ldots, \varphi_{n}$. Thus, $\Omega_{\mathcal{E}}\left(F_{i}\right)=i-j$ if $j$ is even, and $\Omega_{\mathcal{E}}\left(F_{i}\right)=i-j+1$ otherwise.

The advantage of semantic type judgments introduced in the previous subsection is that we can define a typability game also for extended HES's.

The semantic typability game for an extended HES

$$
\mathcal{E}:=\left(F_{n}^{\eta_{n}}={ }_{\alpha_{n}} \varphi_{n} ; \cdots ; F_{j}^{\eta_{j}}={ }_{\alpha_{j}} \varphi_{j}\right)
$$

and an LTS $\mathcal{L}=\left(U, A, \longrightarrow, s_{\text {init }}\right)$, written $\operatorname{SG}(\mathcal{L}, \mathcal{E})$, is a parity game ( $V_{\forall}, V_{\exists}, v_{\text {init }}, E, \Omega$ ), where:

- The set $V_{\forall}$ of Opponent's positions is the set of intersection type environments $\left\{\Gamma \mid \forall F_{i}: \tau \in \Gamma . \tau:: \eta_{i}\right\}$.
- The set $V_{\exists}$ of Player's positions is the set of type bindings that respect simple types, i.e., $\left\{F_{i}: \tau \mid \tau:: \eta_{i}\right\}$.
- $v_{\text {init }}$ is the initial position $F: s_{\text {init }}$.
- $E=E_{1} \cup E_{2}$, where $E_{1}$, the set of Player's moves, is $\left\{\left(F_{i}: \tau, \Gamma\right) \mid \Gamma \models \varphi_{i}: \tau\right\}$; and $E_{2}$, the set of Opponent's moves, is $\left\{\left(\Gamma, F_{i}: \tau\right) \mid F_{i}: \tau \in \Gamma\right\}$.
- The priority function $\Omega$ is defined by: $\Omega(\Gamma)=0$ for every $\Gamma \in V_{\forall}$, and $\Omega\left(F_{i}: \tau\right)=\Omega_{\mathcal{E}}\left(F_{i}\right)$ for every $F_{i}: \tau \in V_{\exists}$.
For an ordinary HES (i.e., HES where fixpoint operators do not occur on the righthand side), the semantic typability game coincides with the (syntactic) typability game.

Lemma 30. Let $\mathcal{E}$ be an HES. Player wins $\operatorname{TG}(\mathcal{L}, \mathcal{E})$ if and only if Player wins $\mathbf{S G}(\mathcal{L}, \mathcal{E})$.

Proof. By the definition of the games, the sets of Opponent's Player's moves in $\mathbf{T G}(\mathcal{L}, \mathcal{E})$ and $\operatorname{SG}(\mathcal{L}, \mathcal{E})$ are identical. By Lemmas 25 and Lemmas 29, the sets of Player's moves are also identical. Thus, the two games are isomorphic.

## A. 3 Soundness of the Semantic Typability Game

We shall show that if Player wins the semantic typability game $\operatorname{SG}(\mathcal{L}, \mathcal{E})$, then $\mathcal{L} \models \mathcal{E}$ holds. To this end, we transform the semantic parity game step by step, until we obtain the trivial semantic parity game for $\mathcal{E}^{\prime}:=\left(F_{n}={ }_{\alpha_{n}}\right.$ toHFL(E)$)$. Player winning the game means $\emptyset \models t o H F L(\mathcal{E})$ : $s_{\text {init }}$, i.e., $s_{\text {init }} \in$ $\llbracket t o H F L(\mathcal{E}) \rrbracket$, which implies $\mathcal{L} \models \mathcal{E}$.

For $i=0, \ldots, n$, we define an (extended) HES $\mathcal{E}^{(i)}$ as follows. $\mathcal{E}^{(0)}$ is $\mathcal{E}=\left(F_{n}^{\eta_{n}}={ }_{\alpha_{n}} \varphi_{n} ; \cdots ; F_{0}^{\eta_{0}}={ }_{\alpha_{0}} \varphi_{0}\right)$. Given $\mathcal{E}^{(i)}$ :

$$
F_{n}^{\eta_{n}}={ }_{\alpha_{n}} \varphi_{n}^{(i)} ; \cdots ; F_{i}^{\eta_{i}}={ }_{\alpha_{i}} \varphi_{i}^{(i)}
$$

$\mathcal{E}^{(i+1)}$ is defined as

$$
F_{n}^{\eta_{n}}={ }_{\alpha_{n}} \varphi_{n}^{(i+1)} ; \cdots ; F_{i+1}^{\eta_{i}}={ }_{\alpha_{i+1}} \varphi_{i+1}^{(i+1)}
$$

where $\varphi_{j}^{(i+1)}=\left[\alpha_{i} F_{i}^{\eta_{i}} \cdot \varphi_{i}^{(i)} / F_{i}\right] \varphi_{j}^{(i)}$. Thus, $\mathcal{E}^{(i+1)}$ is obtained by removing the last equation $F_{i}^{\eta_{i}}={ }_{\alpha_{i}} \varphi_{i}^{(i)}$, and replacing $F_{i}$ with $\alpha_{i} F_{i}^{\eta_{i}} \cdot \varphi_{i}^{(i)}$. Note that $\mathcal{E}^{(n)}=\left(F_{n}=\alpha_{n}\right.$ toHFL(E)$)$ (recall that we assumed that $F_{n}$ does not occur on the righthand side of $\mathcal{E}$ ). We write $\varphi_{j}^{(i)}$ below for the righthand side of the equation for $F_{j}$ in $\mathcal{E}^{(i)}$.

We shall show that the transformation from $\mathcal{E}^{(i)}$ to $\mathcal{E}^{(i+1)}$ preserves the winner of the semantic parity game. To this end, we construct a winning strategy for $\operatorname{SG}\left(\mathcal{L}, \mathcal{E}^{(j+1)}\right)$ from that for $\operatorname{SG}\left(\mathcal{L}, \mathcal{E}^{(j)}\right)$. Let $\mathcal{W}^{(j)}$ be a (memoryless) winning strategy for $\mathbf{S G}\left(\mathcal{L}, \mathcal{E}^{(j)}\right)$. For each winning position $F: \tau$ of $\mathbf{S G}\left(\mathcal{L}, \mathcal{E}^{(j)}\right)$, we define the closure of $F: \tau$, written $\operatorname{clos}_{\mathcal{W}^{(j)}}(F: \tau)$, as the least type environment such that:

- $\mathcal{W}^{(j)}(F: \tau) \subseteq \operatorname{clos}_{\mathcal{W}^{(j)}}(F: \tau)$
- If $F_{j}: \tau^{\prime} \in \operatorname{clos}_{\mathcal{W}^{(j)}}(F: \tau)$, then $\mathcal{W}^{(j)}\left(F_{j}: \tau^{\prime}\right) \subseteq \operatorname{clos}_{\mathcal{W}^{(j)}}(F$ : $\tau)$.
For example, if $\mathcal{W}^{(j)}\left(F: \tau_{1}\right)=\left\{F: \tau_{2}, F_{j}: \tau_{3}\right\}$ and $\mathcal{W}^{(j)}\left(F_{j}: \tau_{3}\right)=$ $\left\{F: \tau_{4}, F_{j}: \tau_{3}\right\}$, then $\operatorname{clos}_{\mathcal{W}^{(j)}}\left(F: \tau_{1}\right)=\left\{F: \tau_{2}, F_{j}: \tau_{3}, F: \tau_{4}\right\}$. We define Player's memoryless strategy $\mathcal{W}^{(j+1)}$ for $\operatorname{SG}\left(\mathcal{L}, \mathcal{E}^{(j+1)}\right)$ by:

$$
\mathcal{W}^{(j+1)}\left(F_{k}: \tau\right)=\left\{F_{\ell}: \tau^{\prime} \mid F_{\ell}: \tau^{\prime} \in \operatorname{closw}\left(F_{k}: \tau\right), \ell>j\right\}
$$

if $k>j$ and $F_{k}: \tau$ is a winning position of $\varphi^{(j)}$, and $\mathcal{W}^{(j+1)}\left(F_{k}: \tau\right)$ is undefined otherwise. We show that $\mathcal{W}^{(j+1)}$ is a valid strategy (i.e., $\left.\left(\left(F_{k}:, \tau\right), \mathcal{W}^{(j+1)}\left(F_{k}: \tau\right)\right) \in E\right)$, and $\mathcal{W}^{(j+1)}$ is a winning strategy. To show that $\mathcal{W}^{(j+1)}$ is valid, it suffices to prove:

$$
\mathcal{W}^{(j+1)}\left(F_{k}: \tau\right) \models \varphi_{k}^{(j+1)}: \tau
$$

We shall use the following lemma.
Lemma 31 (semantic substitution lemma). If $\Gamma_{0}, F: \tau_{1}, \ldots, F$ : $\tau_{k} \models \varphi: \tau$ with $F \notin \operatorname{dom}\left(\Gamma_{0}\right)$ and $\Gamma_{i} \models \varphi^{\prime}: \tau_{i}$ for each $i \in\{1, \ldots, k\}$, then $\Gamma_{0}, \Gamma_{1}, \ldots, \Gamma_{k} \models\left[\varphi^{\prime} / F\right] \varphi: \tau$.
Proof. This follows by straightforward induction on the structure of $\varphi$.

Using the lemma above, we show that $\mathcal{W}^{(j+1)}$ is a valid strategy, by case analysis on $\alpha_{j}$.

- Case $\alpha_{j}=\mu$ :

Let us define $\operatorname{clos}_{\mathcal{W}^{(j)}}^{(i)}\left(F_{k}: \tau\right)$ by: $\operatorname{clos}_{\mathcal{W}^{(j)}}^{(0)}\left(F_{k}: \tau\right)=\mathcal{W}^{(j)}\left(F_{k}\right.$ : $\tau)$ and $\operatorname{clos}_{\mathcal{W}^{(j)}}^{(i+1)}\left(F_{k}: \tau\right)=\left\{F: \tau^{\prime} \in \operatorname{clos}_{\mathcal{W}^{(j)}}^{(i)}\left(F_{k}: \tau\right) \mid\right.$ $\left.F \neq F_{j}\right\} \cup \bigcup_{F_{j}: \tau^{\prime} \in \operatorname{clos}{ }_{\mathcal{W}}{ }^{(j)}\left(F_{k}: \tau\right)} \mathcal{W}^{(j)}\left(F_{j}: \tau^{\prime}\right)$. Since the set of types is finite, and $\mathcal{W}^{(j)}$ is a winning strategy, we have $\operatorname{clos}_{\mathcal{W}(j)}^{(m)}\left(F_{k}: \tau\right)=\mathcal{W}^{(j+1)}\left(F_{k}: \tau\right)$ for some $m$. By repeatedly applying the semantic substitution lemma to $\mathcal{W}^{(j)}\left(F_{k}: \tau\right) \models$ $\varphi_{k}^{(j)}: \tau$, we obtain:

$$
\mathcal{W}^{(j+1)}\left(F_{k}: \tau\right) \models\left[\varphi_{j}^{(j)} / F_{j}\right]^{m} \varphi_{k}^{(j)}: \tau
$$

Thus, we have

$$
\mathcal{W}^{(j+1)}\left(F_{k}: \tau\right) \models\left[\mu F_{j}^{\eta_{j}} \cdot \varphi_{j}^{(j)} / F_{j}\right] \varphi_{k}^{(j)}: \tau
$$

as required.

- Case $\alpha_{j}=\nu$ :

Let $\left\{\tau_{1}, \ldots, \tau_{\ell}\right\}$ be $\left\{\tau^{\prime} \mid F_{j}: \tau^{\prime} \in \operatorname{clos}_{\mathcal{W}^{(j)}}\left(F_{k}: \tau\right)\right\}$. Then, we have:

$$
\mathcal{W}^{(j+1)}\left(F_{k}: \tau\right), F_{j}: \tau_{1}, \ldots, F_{j}: \tau_{\ell} \models \varphi_{j}^{(j)}: \tau_{i}
$$

which implies

$$
\mathcal{W}^{(j+1)}\left(F_{k}: \tau\right) \models \lambda F_{j} . \varphi_{j}^{(j)}: \tau_{1} \wedge \cdots \wedge \tau_{\ell} \rightarrow \tau_{i}
$$

for every $i \in\{1, \ldots, \ell\}$. By Lemma 26, we have:

$$
\perp_{\tau_{1} \wedge \cdots \wedge \tau_{\ell}} \sqsubseteq_{\eta_{j}} \llbracket \lambda F_{j} \cdot \varphi_{j}^{(j)} \rrbracket\left(\rho_{\mathcal{W}^{(j+1)}\left(F_{k}: \tau\right)}\right)\left(\perp_{\tau_{1} \wedge \cdots \wedge \tau_{\ell}}\right) .
$$

Thus, we have

$$
\perp_{\tau_{1} \wedge \cdots \wedge \tau_{\ell}} \sqsubseteq_{\eta_{j}} \llbracket \nu F_{j}^{\eta_{j}} . \varphi_{j}^{(j)} \rrbracket\left(\rho_{\mathcal{W}^{(j+1)}\left(F_{k}: \tau\right)}\right),
$$

from which we obtain

$$
\mathcal{W}^{(j+1)}\left(F_{k}: \tau\right) \models \nu F_{j} \cdot \varphi_{j}^{(j)}: \tau_{1} \wedge \cdots \wedge \tau_{\ell}
$$

by using Lemma 26. Thus, by Lemma 31, we have:

$$
\mathcal{W}^{(j+1)}\left(F_{k}: \tau\right) \models\left[\nu F_{j} . \varphi_{j}^{(j)} / F_{j}\right] \varphi_{k}^{(j)}: \tau
$$

as required.

Finally, to see that $\mathcal{W}^{(j+1)}$ is a winning strategy, notice that for each segment $\left(F_{k}: \tau\right)\left(\mathcal{W}^{(j+1)}\left(F_{k}: \tau\right)\right)\left(F^{\prime}: \tau^{\prime}\right)$ of a play that conforms to the strategy $\mathcal{W}^{(j+1)}$, there is a corresponding segment $\left(F_{k}: \tau\right)\left(\mathcal{W}^{(j)}\left(F_{k}: \tau\right)\right)\left(F_{j}: \tau^{\prime \prime}\right)\left(\mathcal{W}^{(j)}\left(F_{j}: \tau^{\prime \prime}\right)\right) \cdots\left(F^{\prime}: \tau^{\prime}\right)$ of a play that conforms to the strategy $\mathcal{W}^{(j)}$, where the largest priorities in the segments are the same. Thus, every play that conforms to $\mathcal{W}^{(j+1)}$ is won by Player.

By the discussion above, we have:

Lemma 32. Let $\mathcal{E}$ be an HES and $\mathcal{L}$ be an LTS. If Player wins $\mathbf{S G}(\mathcal{L}, \mathcal{E})$, then $\mathcal{L} \models \mathcal{E}$.

## A. 4 Completeness of the Semantic Typability Game

We show the converse of Lemma 32: if $\mathcal{L} \models \mathcal{E}$ then Player wins the semantic typability game $\operatorname{SG}(\mathcal{E}, \mathcal{L})$. Essentially, we just need to do the inverse of the argument for the soundness proof. We start with a winning strategy for the semantic typability game of $\mathcal{E}^{(n)}$ and construct those for the semantic parity games of $\mathcal{E}^{(n-1)}, \ldots, \mathcal{E}^{(0)}=\mathcal{E}$ step by step, where $\mathcal{E}^{(0)}, \ldots, \mathcal{E}^{(n)}$ are as defined in Section A.3.

Actually, we use a slightly different notion of semantic typability game. The fat semantic typability game for an extended $\mathcal{E}$ :

$$
F_{n}^{\eta_{n}}={ }_{\alpha_{n}} \varphi_{n} ; \cdots ; F_{j}^{\eta_{j}}={ }_{\alpha_{j}} \varphi_{j}
$$

(with $\eta_{n}=\bullet$ ) and an $\operatorname{LTS} \mathcal{L}=\left(U, A, \longrightarrow, s_{\text {init }}\right)$ is a parity game $\mathbf{F G}(\mathcal{L}, \mathcal{E})=\left(V_{\forall}, V_{\exists}, V_{\text {init }}, E, \Omega\right)$, where:

- The set $V_{\forall}$ of Opponent's positions is the set of intersection type environments $\left\{\Gamma \mid \forall F_{i}: \tau \in \Gamma . \tau:: \eta_{i}\right\}$.
- The set $V_{\exists}$ of Player's positions is the set of type bindings that respect simple types, i.e., $\left\{F_{i}: \sigma \mid \sigma:: \eta_{i}, \sigma \neq \top\right\}$.
- $V_{\text {init }}$ is the set of initial positions: $\left\{F_{n}: s_{1} \wedge \cdots \wedge s_{k} \mid s_{\text {init }} \in\right.$ $\left.\left\{s_{1}, \ldots, s_{k}\right\}\right\}$.
- $E=E_{1} \cup E_{2}$, where $E_{1}$, the set of Player's moves, is $\left\{\left(F_{i}: \sigma, \Gamma\right) \mid \Gamma \models \varphi_{i}: \sigma\right\}$; and $E_{2}$, the set of Opponent's moves, is $\left\{\left(\Gamma, F_{i}: \sigma\right) \mid \sigma=\Gamma\left(F_{i}\right)\right\}$.
- The priority function $\Omega$, is defined by: $\Omega(\Gamma)=0$ for every $\Gamma \in V_{\forall}$, and $\Omega\left(F_{i}: \sigma\right)=\Omega_{\mathcal{E}}\left(F_{i}\right)$ for every $F_{i}: \tau \in V_{\exists}$.

In the last but one clause, $\Gamma\left(F_{j}\right)$ denotes $\left\{\tau \mid F_{j}: \tau \in \Gamma\right\}$. Player wins if there is a winning strategy from one of the initial positions. The difference from the (non-fat) semantic typability game is that Player's position is of the form $F: \sigma$, instead of $F: \tau$.

Assuming $\mathcal{L} \models \mathcal{E}$, we construct winning strategies for $\mathbf{F G}\left(\mathcal{L}, \mathcal{E}^{(n)}\right)$, $\mathbf{F G}\left(\mathcal{L}, \mathcal{E}^{(n-1)}\right), \ldots, \mathbf{F G}\left(\mathcal{L}, \mathcal{E}^{(0)}\right)$ in this order. For $\mathcal{E}^{(n)}$, there is a trivial winning strategy defined by: $\mathcal{W}^{(n)}\left(F_{n}: \perp_{\llbracket t o H F L(\mathcal{E}) \rrbracket, \bullet}\right)=\emptyset$.

Assume we are given a memoryless winning strategy $\mathcal{W}^{(j+1)}$ for $\mathbf{F G}\left(\mathcal{L}, \mathcal{E}^{(j+1)}\right)$. Recall that $\mathcal{E}^{(j+1)}$ is:

$$
F_{n}=\alpha_{n} \varphi_{n}^{(j+1)} ; \cdots ; \cdots ; F_{j+1}=\alpha_{j+1} \varphi_{j+1}^{(j+1)} F_{n}
$$

where $\varphi_{i}^{(j+1)}=\left[\alpha_{j} F_{j} . \varphi_{j}^{(j)} / F_{j}\right] \varphi_{i}^{(j)}$. Without loss of generality, we assume that $\mathcal{W}^{(j+1)}$ is defined only for Player's winning positions of $\mathbf{F G}\left(\mathcal{L}, \mathcal{E}^{(j+1)}\right)$.

We define Player's history-sensitive strategy ${ }^{9} \mathcal{W}^{\prime(j)}$ for $\mathbf{F G}\left(\mathcal{L}, \mathcal{E}^{(j)}\right)$ as the partial function given by:

$$
\begin{gathered}
\mathcal{W}^{\prime(j)}\left(h\left(F_{k}: \sigma\right)\right)=\Gamma, F_{j}: \sigma_{\llbracket \alpha_{j} F_{j} \eta_{j}} \cdot \varphi_{j}^{(j)} \mathbb{( \rho _ { \Gamma } ) , \eta _ { j }} \\
\text { if } k>j \text { and } \mathcal{W}^{(j+1)}\left(F_{k}: \sigma\right)=\Gamma \\
\begin{array}{c}
\mathcal{W}^{\prime(j)}\left(h\left(\Gamma, F_{j}: \sigma_{j}\right)\left(F_{j}: \sigma_{j}\right)\right)=\left(\Gamma, F_{j}: \sigma_{j}\right) \\
\text { if } \alpha_{j}=\nu, \text { and } \sigma_{j}=\sigma_{\llbracket \nu F_{j}^{\eta_{j}} \cdot \varphi_{j}^{(j)} \rrbracket\left(\rho_{\Gamma}\right), \eta_{j}} \\
\\
\mathcal{W}^{\prime(j)}\left(h\left(\Gamma, F_{j}: \sigma_{j, \ell}\right)\left(F_{j}: \sigma_{j, \ell)}\right)=\left(\Gamma, F_{j}: \sigma_{j, \ell-1}\right)\right. \\
\text { if } \alpha_{j}=\mu, \text { and } \sigma_{j, \ell}=\sigma_{\llbracket F_{j}^{(\ell)} \rrbracket\left(\rho_{\Gamma}\right), \eta_{j}} \neq \sigma_{\llbracket F_{j}^{(\ell-1)} \mathbb{( \rho _ { \Gamma } ) , \eta _ { j }}}=\sigma_{j, \ell-1}
\end{array} .
\end{gathered}
$$

Here, the formula $F_{j}^{(i)}$ occurring in the last clause is defined by:

$$
F_{j}^{(0)}=\lambda X_{1}, \ldots, X_{\ell_{j}} . \text { ff } \quad F_{j}^{(i+1)}=\left[F_{j}^{(i)} / F_{j}\right] \varphi_{j}^{(j)}
$$

(Thus, $\llbracket F_{j}^{(\ell)} \rrbracket\left(\rho_{\Gamma}\right)=\llbracket \mu F_{j}^{\eta_{j}} \cdot \varphi_{j}^{(j)} \rrbracket\left(\rho_{\Gamma}\right)$ for a sufficiently large $\ell$.) $\mathcal{W}^{\prime(j)}(h)$ is undefined if it does not match any of the three clauses above.

We show that $\mathcal{W}^{\prime(j)}$ is a valid strategy, i.e., $\mathcal{W}^{\prime(j)}\left(h\left(F_{k}: \sigma\right)\right)=\Gamma$ implies $\Gamma \models \varphi_{k}^{(j)}: \sigma$. We perform case analysis on which caluse has been used for deriving $\mathcal{W}^{\prime(j)}\left(h\left(F_{k}: \sigma\right)\right)=\Gamma$.

- The first clause:

In this case, $\Gamma=\Gamma^{\prime}, F_{j}: \sigma_{\llbracket \alpha_{j} F_{j} . \varphi_{j}^{(j)} \rrbracket\left(\rho_{\Gamma}\right), \eta_{j}}$, with $k>j$ and $\mathcal{W}^{(j+1)}\left(F_{k}: \sigma\right)=\Gamma^{\prime}$. By the validity of the strategy $\mathcal{W}^{(j+1)}$, we have $\Gamma^{\prime} \models \varphi_{k}^{(j+1)}$ : $\sigma$, i.e.,

$$
\Gamma^{\prime} \models\left[\alpha_{j} F_{j} \cdot \varphi_{j}^{(j)} / F_{j}\right] \varphi_{k}^{(j)}: \sigma
$$

Thus, we have

$$
\Gamma^{\prime}, F_{j}: \sigma_{\llbracket \alpha_{j} F_{j} \cdot \varphi_{j}^{(j)} \rrbracket\left(\rho_{\Gamma}\right), \eta_{j}} \models \varphi_{k}^{(j)}: \sigma
$$

as required.

- The second clause:

In this case, $h=h^{\prime} \Gamma$ and $\Gamma=\Gamma^{\prime}, F_{j}: \sigma_{j}$ with $\alpha_{j}=\nu$ and $\sigma_{j}=\sigma_{\llbracket \nu F_{j} \cdot \varphi_{j}^{(j)} \rrbracket\left(\rho_{\Gamma^{\prime}}\right), \eta_{j}}$. Thus, we have $\Gamma^{\prime}, F_{j}: \sigma_{j} \models \varphi_{j}^{(j)}: \sigma_{j}$ as required.

- The third clause:

In this case, $h=h^{\prime}\left(\Gamma, F_{j}: \sigma_{j, \ell}\right)$ and $\Gamma=\Gamma^{\prime}, F_{j}: \sigma_{j, \ell-1}$, with $\alpha_{j}=\mu$, and $\sigma_{j, \ell}=\sigma_{\llbracket F_{j}^{(\ell)} \mathbb{1}\left(\rho_{\Gamma^{\prime}}\right), \eta_{j}} \neq \sigma_{\llbracket F_{j}^{(\ell-1)} \rrbracket\left(\rho_{\Gamma}\right), \eta_{j}}=$ $\sigma_{j, \ell-1}$, where $F_{j}^{(\ell)}=\left[F_{j}^{(\ell-1)} / F_{j}\right] \varphi_{j}^{(j)}$. Since $\llbracket F_{j}^{(\ell)} \rrbracket\left(\rho_{\Gamma}\right)=$ $\llbracket \varphi_{j}^{(j)} \rrbracket\left(\rho_{\Gamma^{\prime}}\left\{F_{j} \mapsto \llbracket F_{j}^{(\ell-1)} \rrbracket\left(\rho_{\Gamma}\right)\right\}\right)$, we have

$$
\Gamma^{\prime}, F_{j}: \sigma_{\llbracket F_{j}^{(\ell-1)} \rrbracket\left(\rho_{\Gamma^{\prime}}\right), \eta_{j}} \models \varphi_{j}^{(j)}: \sigma_{\llbracket F_{j}^{(\ell)} \rrbracket\left(\rho_{\Gamma^{\prime}}\right), \eta_{j}},
$$

as required.
To check that $\mathcal{W}^{\prime(j)}$ is a winning strategy, it suffices to observe that (i) for each fragment $\left(F_{k}: \sigma\right) h^{\prime}\left(F_{k^{\prime}}: \sigma^{\prime}\right)$ of a play with $k, k^{\prime}>j$, there exists a corresponding fragment of a play (consisting of two moves) $\left(F_{k}: \sigma\right) \Gamma\left(F_{k^{\prime}}: \sigma^{\prime}\right)$ conforming to $\mathcal{W}^{(j+1)}$; (ii) if there exists an infinite play that visits only $F_{j}$, then $\alpha_{j}$ must be even (since the third clause in the definition of $\mathcal{W}^{\prime(j)}$ can generate only finite plays); and (iii) Player never gets stuck (note that in the third clause, $\sigma_{j, 0}=\mathrm{\top}$, and that in the first clause, $F_{k}: \sigma$ comes from the co-domain of $\mathcal{W}^{(j+1)}$ ).

Now, by a standard theorem on parity games, there is also a memoryless winning strategy $\mathcal{W}^{(j)}$.

[^8]By repeating the above steps, we obtain a memoryless winning stragety $\mathcal{W}^{(0)}$ for $\operatorname{FG}(\mathcal{L}, \mathcal{E})$. From $\mathcal{W}^{(0)}$, we can construct a history-sensitve winning strategy $\mathcal{W}^{\prime}$ for the non-fat semantic typability game $\mathbf{S G}(\mathcal{L}, \mathcal{E})$ as follows.

```
\(\mathcal{W}^{\prime}\left(F_{n}: s_{\text {init }}\right)=\mathcal{W}^{(0)}\left(F_{n}: \sigma_{0}\right)\)
    where \(F_{n}: \sigma_{0}\) is an initial, winning position of the fat game.
\(\mathcal{W}^{\prime}(h \Gamma(F: \tau))=\mathcal{W}^{(0)}(F: \Gamma(F))\).
```

We can further convert $\mathcal{W}^{\prime}$ to a memoryless winning strategy $\mathcal{W}$ for $\mathbf{S G}(\mathcal{L}, \mathcal{E})$.

Thus, we have:
Lemma 33. Let $\mathcal{E}$ be an HES and $\mathcal{L}$ be an LTS. If $\mathcal{L} \models \mathcal{E}$, then Player wins $\operatorname{SG}(\mathcal{L}, \mathcal{E})$.

Theorem 13 follows as an immediate corollary of Lemmas 30, 32 , and 33 .

## B. Proofs for Lemmas in Section 5

We show that the KO typing game $\operatorname{TG}(\mathcal{G}, \mathcal{A})$ is isomorphic to the HFL typing game $\operatorname{TG}\left(\mathcal{L}_{\mathcal{A}}, \mathcal{E}_{\mathcal{G}}\right)$ where positions of the form $L_{n}: \tau$ have been omitted.

Let $\Gamma_{a u x}=\left\{L_{n}: \bigwedge_{q_{1} \in Q_{1}} q_{1} \rightarrow \cdots \bigwedge_{q_{n} \in Q_{n}} q_{n} \rightarrow f \mid\right.$ $\left.\left(Q_{1}, \ldots, Q_{n}\right) \models f\right\}$.

The positions that are omitted precisely are the ones of $\Gamma_{a u x}$. We first show that these are winning positions for Player.

Proof of Lemma 17. The claim is that always playing $\Gamma_{a u x}$ is a winning strategy for Player in the typing game starting at position $\vdash^{\mathrm{HFL}} L_{n}: \bigwedge_{q \in Q_{1}} q \rightarrow \bigwedge_{q \in Q_{2}} q \rightarrow \cdots \rightarrow \bigwedge_{q \in Q_{n}} q \rightarrow f$. To prove this, we reason by induction on $f$. Let $\sigma_{l}=\bigwedge_{q \in Q_{l}} q$, $\Gamma=\left\{y_{1}: \sigma_{1}, \ldots, y_{n}\right\}$ and $\varphi=\langle$ and $\left.\rangle \mathrm{tt} \wedge[\operatorname{and}]\left(L_{n} y_{1} \ldots y_{n}\right)\right) \vee$ $\langle$ or $\rangle\left(L_{n} y_{1} \ldots y_{n}\right) \vee \bigvee_{j=1}^{n}\langle j\rangle y_{j} \vee\langle$ true $\rangle \uparrow$. By case analysis on $f$, we show that $\Gamma, \Gamma_{\text {aux }} \vdash^{\text {HFL }} \varphi: f$ iff $\left(Q_{1}, \ldots, Q_{n}\right) \models f$.

- if $f=(j, q)$, then $f \xrightarrow{j} q$ and this is the only transition from $f$, so $\vdash^{\text {HFL }} \varphi: f$ iff $\vdash^{\text {HFL }}\langle j\rangle y_{j}: f$, if and only if $\vdash^{\text {HFL }} y_{j}: q$, if and only if $q \in Q_{j}$, if and only if $\left(Q_{1}, \ldots, Q_{n}\right) \models f$.
$\bullet$ if $f=f_{1} \wedge f_{2}$, then $f \xrightarrow{\text { and }} f_{1}, f \xrightarrow{\text { and }} f_{2}$. Then $\Gamma, \Gamma_{\text {aux }} \vdash^{\text {HFL }} \varphi$ : $f$ iff $\Gamma, \Gamma_{a u x} \vdash^{\text {HFL }} L_{n} y_{1} \ldots y_{n}: f_{i}$ for $i=1,2$, iff (by induction) $\left(Q_{1}, \ldots, Q_{n}\right) \models f_{i}$ for $i=1,2$ iff $\left(Q_{1}, \ldots, Q_{n}\right) \models f$.
- the case $f=f_{1} \vee f_{2}$ is similar
- if $f=\mathrm{tt}$, then $f \xrightarrow{\text { true }} f$, therefore $\Gamma \vdash^{\text {HFL }}\langle$ true $\rangle \top: f$ and $\Gamma \vdash^{\text {HFL }} \varphi: f$. Moreover, $\left(Q_{1}, \ldots, Q_{n}\right) \models \mathrm{tt}$, so the equivalence holds.
Hence $\Gamma, \Gamma_{a u x} \vdash^{\text {HFL }} \varphi: f$ iff $\left(Q_{1}, \ldots, Q_{n}\right) \models f$, which ends the proof.

We now move to identifying Player's positions of the KO typing game with Players' position of the HFL typing game.
Lemma 34. Let e be a term of a HORS. If $\Gamma \vdash^{\text {HFL }} e^{\sharp m}: \tau$ then there exists $\Theta$ such that $\Theta \vdash^{\text {HORS }} e:(\tau)^{b}$ with $\Gamma \supseteq\left(\Theta \uparrow_{m}\right)^{\sharp}$.

Proof. By induction on $e$ :

- if $e=x$ for a variable or a non-terminal $x$, then by T-VAR $\Gamma \supseteq x^{\sharp m}: \tau=\left(\Theta \uparrow_{m}\right)^{\sharp}$ with $\Theta:=\left\{x:\left((\tau)^{b}, 0\right)\right\}$ such that $\Theta \vdash^{\text {HORS }} x:(\tau)^{b}$
- if $e=a$ with $\Sigma(a)=n$, then by definition of $(.)^{\sharp m}$ and by T-ABS, there are $\sigma_{l, m^{\prime}}=\bigwedge_{q^{\prime} \in Q_{l, m^{\prime}}} q^{\prime}$ and $q \in Q$ such that
- $\tau=\sigma_{1,0} \rightarrow \cdots \rightarrow \sigma_{1, p-1} \rightarrow \cdots \rightarrow \sigma_{n, 0} \rightarrow \cdots \rightarrow$ $\sigma_{n, p-1} \rightarrow q$
- $\Gamma, \Gamma^{\prime} \vdash^{\mathrm{HFL}} \bigvee_{m^{\prime}=0}^{p-1}\left\langle\mathbf{a}_{m^{\prime}}\right\rangle\left(L_{n} y_{1}^{\sharp m^{\prime}} \ldots y_{n}^{\sharp m^{\prime}}\right): q$
- $\Gamma^{\prime}=\left\{y_{l}^{\sharp m^{\prime}}: \sigma_{l, m^{\prime}} \mid\left(l, m^{\prime}\right) \in\{1, \ldots, n\} \times\{0, \ldots, p-\right.$ 1\}\}
By construction of $\mathcal{L}_{\mathcal{A}}$, fixing $m^{\prime}:=\Omega(q)$,

$$
\Gamma, \Gamma^{\prime} \vdash^{\mathrm{HFL}} L_{n} y_{1}^{\sharp m^{\prime}} \ldots y_{n}^{\sharp m^{\prime}}: \delta_{\mathcal{A}}(q, a),
$$

and by Lemma 17 there is $\mathbf{Q} \in\left(2^{Q}\right)^{n}$ such that $\mathbf{Q} \models \delta_{\mathcal{A}}(q, a)$ and $\Gamma, \Gamma^{\prime} \vdash^{\text {HFL }} y_{l}^{\sharp m^{\prime}}: \bigwedge_{q^{\prime} \in Q_{l}} q^{\prime}$ for all $l=1, \ldots, n$. So it holds that $\left(Q_{1, m^{\prime}}, \ldots, Q_{n, m^{\prime}}\right) \models \delta_{\mathcal{A}}(q$, a), and by T-ConsT in KO type system, $\vdash^{\text {HORS }} \mathrm{a}: \theta$ with

$$
\theta:=\bigwedge_{q^{\prime} \in Q_{1, m^{\prime}}}\left(q^{\prime}, m^{\prime}\right) \rightarrow \cdots \rightarrow \bigwedge_{q^{\prime} \in Q_{n, m^{\prime}}}\left(q^{\prime}, m^{\prime}\right) \rightarrow q
$$

Finally, $(\tau)^{b} \leq \theta$, hence by T-SUB $\vdash^{\text {HoRS }} \mathrm{a}:(\tau)^{b}$.

- if $e=e_{1} e_{2}$, then there are types $\tau_{m^{\prime}, j}$ such that

1. $\Gamma \vdash^{\text {HFL }} e_{1}^{\sharp m}: \bigwedge_{j \in J_{0}} \tau_{0, j} \rightarrow \cdots \rightarrow \bigwedge_{j \in J_{p-1}} \tau_{p-1, j} \rightarrow \tau$, and
2. $\Gamma \vdash^{\text {HFL }} e_{2}^{\sharp \max \left(m, m^{\prime}\right)}: \tau_{m^{\prime}, j}$ for all $m^{\prime}=0, \ldots, p-1$ and for all $j \in J_{m^{\prime}}$
By induction hypothesis
3. there is $\Theta_{1}$ such that $\Gamma \supseteq\left(\Theta_{1} \uparrow_{m}\right)^{\sharp}$ and $\Theta_{1} \vdash^{\text {HoRS }} e_{1}$ : $\bigwedge_{m^{\prime}=0, \ldots, p-1, j \in J_{m^{\prime}}}\left(\left(\tau_{m^{\prime}, j}\right)^{b}, m^{\prime}\right) \rightarrow(\tau)^{b}$
4. there are $\Theta_{m^{\prime}, j}$ such that $\Gamma \supseteq\left(\Theta_{m^{\prime}, j} \uparrow_{\max \left(m, m^{\prime}\right)}\right)^{\sharp}$ and $\Theta_{m^{\prime}, j} \vdash^{\text {HORS }} e_{2}:\left(\tau_{m^{\prime}, j}\right)^{b}$
Let $\Theta:=\Theta_{1} \cup \bigcup\left\{\Theta_{m^{\prime}, j} \uparrow_{m^{\prime}} \mid m^{\prime}=0, \ldots, p-1, j \in J_{m^{\prime}}\right\}$. Then $\Gamma \supseteq\left(\Theta \uparrow_{m}\right)^{\sharp}$, and $\Theta \vdash^{\text {HORS }} e_{1} e_{2}:(\tau)^{b}$

Lemma 35. Let e be a term of a HORS. If $\Theta \vdash \vdash^{\text {HoRS }} e: \theta$, then $\left(\Theta \uparrow_{m}\right)^{\sharp} \vdash^{\text {HORS }} e^{\sharp m}:(\theta)^{\sharp}$

Proof. By induction on $e$ :

- if $e=x$, then $\Theta \supseteq\{x:(\theta, 0)\}$, so $\left(\Theta \uparrow_{m}\right)^{\sharp} \supseteq\left\{x^{\sharp m}:(\theta)^{\sharp}\right\}$, and $\left(\Theta \uparrow_{m}\right)^{\sharp} \vdash^{\text {HFL }} x^{\sharp m}:(\theta)^{\sharp}$
- if $e=$ a with $\Sigma(\mathrm{a})=n$ then by T-Const it holds that $\left.\left.\theta=\bigwedge_{j \in J_{1}}\left(q_{1 j}, \Omega(q)\right)\right) \rightarrow \cdots \rightarrow \bigwedge_{j \in J_{n}}\left(q_{n j}, \Omega(q)\right)\right) \rightarrow q$ for some $q, q_{l j}$ such that $\left\{\left(l, q_{l j}\right) \mid l \in\{1, \ldots, n\}, j \in\right.$ $\left.J_{l}\right\} \models \delta(q, a)$. Let $m=\Omega(q)$ and $\Gamma=\left\{y_{l}^{\sharp m}: q_{l j} \mid l \in\right.$ $\left.\{1, \ldots, n\}, j \in J_{l}\right\}$. Then $\left(\Theta \uparrow_{m}\right)^{\sharp} \vdash^{\text {HFL }}\left\langle\mathrm{a}_{m}\right\rangle\left(L_{n} y_{1}^{\sharp m} \ldots y_{n}^{\sharp m}\right)$ since $\left(\Theta \uparrow_{m}\right)^{\sharp} \supseteq \Gamma_{\text {aux }}$. Let $\sigma_{l, m^{\prime}}=\top$ if $m^{\prime} \neq m$, and $\sigma_{l, m}=\bigwedge_{j \in J_{l}} q_{l j}$, so that $(\theta)^{\sharp}=\sigma_{1,0} \rightarrow \ldots \sigma_{1, p-1} \rightarrow$ $\cdots \rightarrow \sigma_{n, 0} \cdots \rightarrow \sigma_{n, p-1} \rightarrow q$. Let $\Gamma^{\prime}=\left\{y_{l}^{\sharp m}: \sigma_{l, m} \mid\right.$ $l \in\{1, \ldots, n\}, m \in\{0, \ldots, p-1\}\}$. Since $\Gamma \subseteq \Gamma^{\prime}$, $\Gamma^{\prime},\left(\Theta \uparrow_{m}\right)^{\sharp} \vdash^{\mathrm{HFL}}\left\langle\mathrm{a}_{m}\right\rangle_{( }\left(L_{n} y_{1}^{\sharp m} \ldots y_{n}^{\sharp m}\right): q$, so $\Gamma^{\prime},\left(\Theta \uparrow_{m}\right)^{\sharp} \vdash^{\mathrm{HFL}}$ $\bigvee_{m^{\prime}=0}^{p-1}\left\langle\mathrm{a}_{m^{\prime}}\right\rangle\left(L_{n} y_{1}^{\sharp m^{\prime}} \ldots y_{n}^{\sharp m^{\prime}}\right): q$, and finally $\left(\Theta \uparrow_{m}\right)^{\sharp} \vdash^{\mathrm{HFL}}$ $(\mathrm{a})^{\sharp m}:(\theta)^{\sharp}$.
- if $e=e_{1} e_{2}$, then by T-APP $\Theta=\Theta_{0} \cup \bigcup_{j \in J} \Theta_{j} \uparrow m_{j}$ for some $\Theta_{j}$ and $m_{j}$, and $\Theta \vdash^{\text {HORS }} e_{1}: \bigwedge_{j \in J}\left(\theta_{j}, m_{j}\right) \rightarrow \theta$, and $\Theta_{j} \vdash^{\text {HoRS }} e_{2}: \theta_{j}$. Let $\bigwedge_{j \in J}\left(\theta_{j}, m_{j}\right)=\bigwedge_{m^{\prime}=0}^{p-1} \bigwedge_{j \in J_{m^{\prime}}}\left(\theta_{j}, m^{\prime}\right)$. By definition, $\left(\Theta \uparrow_{m}\right)^{\sharp}=\left(\Theta_{0} \uparrow_{m}\right)^{\sharp} \cup \bigcup_{j \in J} \Theta_{j} \uparrow_{\max \left(i, m_{j}\right)}$ By induction hypothesis, $\left(\Theta \uparrow_{m}\right)^{\sharp} \vdash^{\text {HORS }} e_{1}^{\sharp m}: \bigwedge_{j \in J_{0}}\left(\theta_{j}\right)^{\sharp} \rightarrow$ $\cdots \rightarrow \bigwedge_{j \in J_{p-1}}\left(\theta_{j}\right)^{\sharp} \rightarrow(\theta)^{\sharp}$ and $\left(\Theta_{j} \uparrow_{m^{\prime}}\right)^{\sharp} \vdash^{\text {HORS }} e_{2}^{\sharp m^{\prime}}:$ $\left(\theta_{j}\right)^{\sharp}$ for all $j \in J$ and for all $m^{\prime}$. In particular, for all $m^{\prime}=0, \ldots, p-1$, for all $j \in J_{m^{\prime}},\left(\Theta \uparrow_{m}\right)^{\sharp} \vdash^{\text {HORS }} e_{2}^{\sharp \max \left(i, m^{\prime}\right)}$ : $\left(\theta_{j}\right)^{\sharp}$, so by T-APP and by definition of $(.)^{\sharp m},\left(\Theta \uparrow_{m}\right)^{\sharp} \vdash^{\text {HORS }}$ $\left(e_{1} e_{2}\right)^{\sharp m}:(\theta)^{\sharp}$.

Proof of Lemma 16. Follows immediately from Lemmas 34 and 35 in the special case $m=0$.

## C. Proofs for Section 6

Proof of Lemma 20. Recall that a number $n>0$ is decremented by one by flipping exactly those bits in its binary representation such that all bits of lesser significance are zero. In particular, the least significant bit must be flipped.

Note that the order 1 nonterminals representing boolean operations work as intended: If $T$ is the tree generated by $x$, and $T^{\prime}$ is the tree generated by Not $x$ then $T \Downarrow b$ iff $T^{\prime} \Downarrow \bar{b}$, where $b \in\{1,0\}$ and $\bar{b}$ is the opposite constant. Moreover, if $T_{j}$ is the tree generated by $x_{j}$, for $1 \leq j \leq \ell$, and $T$ is the tree generated by $\mathrm{OR}_{\ell} x_{1}, \cdots, x_{\ell}$, then $T \Downarrow 1$ iff $T_{j} \Downarrow 1$ for at least one $j$, and $T \Downarrow 0$ iff $T_{i} \Downarrow 0$ for all $j$.

The proof of the lemma is by induction on $i$. Let $i=1$. By the above, if $T$ is the tree generated by IsZero $_{1}\left(b_{0}, \ldots, b_{r-1}\right)$ and $T_{j}$ is the tree generated by $b_{j}$, for $j$ with $0 \leq j \leq r-1$, then $T \Downarrow 1$ if $T_{j} \Downarrow 0$ for all $j$ and $T \Downarrow 1$ if there exists $j$ such that $T_{j} \Downarrow 1$ and $T_{j^{\prime}} \Downarrow 0$ for all $j^{\prime}<j$. Consider $\operatorname{Dec}_{1}^{m} \operatorname{Max}_{1}$ for $0 \leq m \leq \exp _{1}(r)-1$ and let $T_{j}$ be the tree generated by the $j$-th bit in this tuple. We observe that $T_{j} \Downarrow 0$ if the $j$-th bit in the binary representation of $\exp _{1}(r)-1-m$ is zero and $T_{j} \Downarrow 1$ if it is one. We prove this by induction over $m$. For $m=0$ the claim is by definition since $T_{j} \Downarrow 1$ for all $j$. Consider the statement proved for $m<r-1$ and let $T_{j}^{\prime}$ the the tree generated by bit number $j$ in $\operatorname{Dec}_{1}^{m+1} \operatorname{Max}_{1}$. For $j=0$, via DecSub $b_{0} \rightarrow$ Not $b_{j}$ we obtain that $T_{0} \Downarrow b$ iff $T_{0}^{\prime} \Downarrow \bar{b}$. Since the least significant bit of $\exp _{1}(r)-1-(m+1)$ must be the opposite of the least significant bit of $\exp _{1}(r)-1-m$, this proves the statement for $j=0$. From

$$
\operatorname{DecSub}_{j} b_{0} \cdots b_{j} \rightarrow \text { if }\left(\mathrm{OR}_{j} b_{0} \cdots b_{j-1}\right) b_{j}\left(\operatorname{Not} b_{j}\right)
$$

we conclude that, if $T_{j} \Downarrow b$ then $T_{j}^{\prime} \Downarrow \bar{b}$ iff $T_{j^{\prime}} \Downarrow 0$ for all $j^{\prime}<j$ and $T_{j}^{\prime} \Downarrow b$ else. If $T_{j}^{\prime} \Downarrow \bar{b}$ then, by the induction hypothesis, all bits of lesser significance than $j$ in the binary representation of $\exp _{1}(r)-1-m$ are zero, whence the $j$-th bit must be flipped in the binary representation of $\exp _{1}(r)-1-m-1=$ $\exp _{1}(r)-1-(m+1)$, which it is. Conversely, if $T_{j} \Downarrow b$ then $T_{j}^{\prime} \Downarrow b$ iff $T_{j^{\prime}} \Downarrow 1$ for some $j^{\prime}<j$. Hence, by the induction hypothesis, the $j^{\prime}$-th bit of $m$ is one and, hence the $j$-th bit of $\exp _{1}(r)-1-m-1=\exp _{1}(r)-1-(m+1)$ equals the $j$-th bit of $\exp _{1}(r)-1-m-1=\exp _{1}(r)-1-(m)$. This finishes the induction and yields the claim of the lemma for $i=1$.

Assume that the lemma is proved for some $i$. Note that the binary representation of $\exp _{i+1}(r)-1$ has $\exp _{i}(r)-1$ bits, none of which are zero.

Consider the trees $T_{m^{\prime}}^{m}$ generated by $\left(\operatorname{Dec}_{i+1}^{m} \operatorname{Max}_{i+1}\right)\left(\operatorname{Dec}_{i}^{m^{\prime}} \operatorname{Max}_{i}\right)$ and $T_{m^{\prime}}^{\prime m}$ generated by ExistsOne $i_{+1}\left(\operatorname{Dec}_{i+1}^{m} \operatorname{Max}_{i+1}\right)\left(\operatorname{Dec}_{i}^{m^{\prime}} \operatorname{Max}_{i}\right)$. We claim that $T_{m^{\prime}}^{m} \Downarrow 0$ iff the $\exp _{i}(r)-1-m^{\prime}$-th bit of $\exp _{i+1}(r)-1-m$ is zero and that $T_{m^{\prime}}^{m} \Downarrow 1$ if it is one. Moreover we claim that $T_{m^{\prime}}^{\prime m} \Downarrow 1$ if $T_{m^{\prime \prime}}^{m} \Downarrow 1$ for some $m^{\prime \prime}$ with $\exp _{i+1}(r)-1 \geq m^{\prime \prime}>m^{\prime}$ and that $T_{m^{\prime}}^{\prime m} \Downarrow 0$ if $T_{m^{\prime \prime}}^{m} \Downarrow 0$ for all $\exp _{i+1}(r)-1 \geq m^{\prime \prime}>m^{\prime}$. The proof is by double induction on $m$ and $m^{\prime}$. For the outer induction, consider the case $m=0$. Clearly $\operatorname{Max}_{i+1}\left(\operatorname{Dec}_{i}^{m^{\prime}} \operatorname{Max}_{i}\right)$ generates the tree $T_{m^{\prime}}^{0}=1$ for all $m^{\prime}$. Hence, also $T_{m^{\prime}}^{\prime 0} \Downarrow 1$ if $m^{\prime}<\exp _{i}(r)-1$ and $T_{m}^{\prime 0} \Downarrow 0$ if $m^{\prime}=\exp _{i}(r)-1$ by induction over $m^{\prime}$.

Consider the claim proved for some $m<\exp _{i+1}(r)-1$. We have to show that $T_{m^{\prime}}^{m+1} \Downarrow 1$ if the $\exp _{i}(r)-1-m^{\prime}$-th bit of
$\exp _{i+1}(r)-1-(m+1)$ is zero and that $T_{m^{\prime}}^{m+1} \Downarrow 1$ if it is one. Consider

$$
\operatorname{Dec}_{i+1} f g \rightarrow \text { if }\left(\text { ExistsOne }_{i+1} f g\right)(f g)(\operatorname{Not}(f g)) .
$$

There are two cases: If the $\exp _{i}(r)-1-m^{\prime \prime}$-th bit of the binary representation of $\exp _{i+1}(r)-1-m$ is one for some $m^{\prime \prime}$ with $\exp _{i}(r)-1 \geq m^{\prime \prime}>m^{\prime}$, then, by the induction hypothesis, $T_{m^{\prime}}^{\prime m} \Downarrow 1$ and the second clause of the if statement is relevant. In other words, if $T_{m^{\prime}}^{m} \Downarrow b$ then $T_{m^{\prime}}^{m+1} \Downarrow b$, which is as desired since the $\exp _{i}(r)-1-m^{\prime}$-th bit of $\exp _{i+1}(r)-1-(m+1)$ must equal the same bit of $\exp _{1}(r)-1-m$, whence the claim holds for this case. If the $\exp _{i}(r)-1-m^{\prime \prime}$-th bit of the binary representation of $\exp _{i+1}(r)-1-m$ is zero for all $m^{\prime \prime}$ with $\exp _{i}(r)-1 \geq m^{\prime \prime}>m^{\prime}$, then the $\exp _{i}(r)-1-m^{\prime \prime}$-th bit of $\exp _{i+1}(\bar{r})-1-(m+1)$ must be opposite to that of $\exp _{i+1}(r)-1-m$. By the induction hypothesis, $T_{m^{\prime}}^{\prime m} \Downarrow 0$ whence, if $T_{m^{\prime}}^{m} \Downarrow b$, then $T_{m^{\prime}}^{m+1} \Downarrow \bar{b}$.

It remains to show that $T_{m^{\prime}}^{\prime m+1} \Downarrow 1$ if $T_{m^{\prime \prime}}^{m+1} \Downarrow 1$ for some $m^{\prime \prime}$ with $\exp _{i+1}(r)-1 \geq m^{\prime \prime}>m^{\prime}$ and that $T_{m^{\prime}}^{\prime m+1} \Downarrow 0$ if $T_{m^{\prime \prime}}^{m} \Downarrow 0$ for all $m^{\prime \prime}$ with $\exp _{i+1}(r)-1 \geq m^{\prime \prime}>m^{\prime}$. By the claim of the lemma for $i$, if $m^{\prime}=\exp _{i+1}(r)-1$, then the clause IsZero $_{i} g$ in the definition of ExistsOne $i_{+1}$ will generate a tree $T$ such that $T \Downarrow 1$ and $T_{m^{\prime \prime}}^{m+1} \Downarrow 0$, which is correct since there is no valid $m^{\prime \prime}>m^{\prime}$. The rest of the claim proceeds by induction over $m^{\prime}$. Consider it proved for $m^{\prime}>0$. We show that it holds for $m^{\prime}-1$. By definition of ExistsOne $i_{i+1}$, we have that $T_{m^{\prime}-1}^{\prime m+1}$ is that generated by

$$
\text { if } \left.\left(f\left(\operatorname{Dec}_{i} g\right)\right) 1\left(\text { ExistsOne }_{i+1} f\left(\operatorname{Dec}_{i} g\right)\right)\right)
$$

where $f=\operatorname{Dec}_{i+1}^{m+1} \operatorname{Max}_{i+1}$ and $\operatorname{Dec}_{i} g=\operatorname{Dec}_{i}^{m^{\prime}-1+1} \operatorname{Max}_{i}$. Since $T_{m^{\prime}}^{m+1} \Downarrow 1$ if the $\exp _{i}(r)-1-\left(m^{\prime}\right)$-th bit of the binary representation is one, we get that $T_{m-1}^{\prime m+1} \Downarrow 1$ if the $\exp _{i}(r)-1-m^{\prime}-$ th bit of the binary representation of $\exp _{i+1}(r)-1-(m+1)$ is one. Since $T_{m^{\prime}}^{m+1} \Downarrow 0$ if the $\exp _{i}(r)-1-\left(m^{\prime}\right)$-th bit of the binary representation is zero, we get that $T_{m^{\prime}-1}^{\prime m+1} \Downarrow b$ iff $T_{m^{\prime}}^{\prime m+1} \Downarrow b$. By the induction hypothesis, $T_{m^{\prime}}^{\prime m+1} \Downarrow 1$ iff there is $m^{\prime \prime}$ with $0 \geq m^{\prime \prime} \geq m^{\prime}$, such that the $\exp _{i}(r)-1-m^{\prime \prime}$-th bit of the binary representation of $\exp _{i+1}(r)-1-(m+1)$ is one, which finishes the induction.

Putting it all together, we obtain that, if $T$ is the tree generated by $\operatorname{IsZero}_{i+1} \operatorname{Dec}_{i+1}^{m} \operatorname{Max}_{i+1}$, then $T \Downarrow 1$ if $m=\exp _{i}(r)-1$ and $T \Downarrow 0$ if $m<\exp _{i}(r)-1$, which is the claim for the case $i+1$ in the main induction. Hence, the lemma is proved.

Below we write $\mathbf{F V}(\varphi)$ for the set of free variables occurring in $\varphi$.

Proof of Lemma 21. We define the substitution $\gamma_{i}(i \in\{0, \ldots, n, n+$ 1\}) by:

$$
\begin{aligned}
& \gamma_{0}=[] \quad \text { (i.e., the empty substitution) } \\
& \gamma_{i+1}=\left[\alpha_{i} F_{i} . \gamma_{i} \varphi_{i} / F_{i}\right] \circ \gamma_{i}
\end{aligned}
$$

Note that $\operatorname{toHFL}(\mathcal{E})=\gamma_{n+1} F_{n}=\alpha_{n} F_{n} \cdot \gamma_{n} \varphi_{n}$.
For $\beta \in\{0, \ldots, \mathbf{m h}\}^{n-j+1}$, we define the HFL formula $\varphi_{j}^{\beta}$ by:

$$
\begin{aligned}
& \varphi_{j}^{\left(m_{n}, \ldots, m_{j+1}, 0\right)}=\lambda x_{1} \cdot \cdots \lambda x_{\ell_{j}} \cdot \widehat{\alpha_{j}} \\
& \varphi_{j}^{\beta}=\left[\varphi_{n}^{\beta(n)} / F_{n}, \ldots, \varphi_{j}^{\beta(j)} / F_{j}\right] \gamma_{j} \varphi_{j} \\
& \quad \text { if } \beta=\left(m_{n}, \ldots, m_{j}\right) \text { with } 0<m_{j}<\mathbf{m h} . \\
& \varphi_{j}^{\beta}=\left[\varphi_{n}^{\beta(n)} / F_{n}, \ldots, \varphi_{j+1}^{\beta(j+1)} / F_{j+1}\right] \alpha_{j} F_{j} \cdot \gamma_{j} \varphi_{j} \\
& \quad \text { if } \beta=\left(m_{n}, \ldots, m_{j}\right) \text { with } m_{j}=\mathbf{m h} .
\end{aligned}
$$

We shall show that

$$
\llbracket \varphi_{j}^{\beta} \rrbracket=\llbracket F_{j}^{\beta} \rrbracket
$$

by well-founded induction on $\beta$. Let $\beta=\left(\beta_{n}, \ldots, \beta_{j}\right)$.

- Case $\beta_{j}=0$ : The result follows immediately, since

$$
\varphi_{j}^{\beta}=\lambda x_{1} \cdots \lambda x_{\ell_{j}} \cdot \widehat{\alpha_{j}}=F_{j}^{\beta} .
$$

- Case $\beta_{j}>0$ : We first show that

$$
\varphi_{\ell}^{\beta(\ell)}=\left[\varphi_{n}^{\beta(n)} / F_{n}, \ldots, \varphi_{j}^{\beta(j)} / F_{j}\right] \gamma_{j} F_{\ell}
$$

holds for every $\ell<j$, by induction on $j-\ell>0$. Since $\beta(\ell)=(\beta(\ell+1), \mathbf{m h})$, by the definition of $\varphi_{j}^{\beta}$, we have:

$$
\begin{aligned}
& \varphi_{\ell}^{\beta(\ell)}=\left[\varphi_{n}^{\beta(n)} / F_{n}, \ldots, \varphi_{\ell+1}^{\beta(\ell+1)} / F_{\ell+1}\right] \alpha_{\ell} F_{\ell} \cdot \gamma_{\ell} \varphi_{\ell} \\
& \left.\quad \text { (by the definition of } \varphi_{\ell}^{\beta}\right) \\
& =\left[\varphi_{n}^{\beta(n)} / F_{n}, \ldots, \varphi_{j}^{\beta(j)} / F_{j}\right] \\
& \quad\left[\gamma_{j} F_{j-1} / F_{j-1}, \ldots, \gamma_{j} F_{\ell+1} / F_{\ell+1}\right] \alpha_{\ell} F_{\ell} \cdot \gamma_{\ell} \varphi_{\ell} \\
& \text { (by the induction hypothesis) } \\
& =\left[\varphi_{n}^{\beta(n)} / F_{n}, \ldots, \varphi_{j}^{\beta(j)} / F_{j}\right] \gamma_{j}\left(\alpha_{\ell} F_{\ell \cdot} \cdot \gamma_{\ell} \varphi_{\ell}\right) \\
& \left(\text { by dom }\left(\gamma_{j}\right) \cap \mathbf{F V}\left(\alpha_{\ell} F_{\ell} \cdot \gamma_{\ell} \varphi_{\ell}\right) \subseteq\left\{F_{\ell+1}, \ldots, F_{æ-1}\right\}\right) \\
& =\left[\varphi_{n}^{\beta(n)} / F_{n}, \ldots, \varphi_{j}^{\beta(j)} / F_{j}\right] \gamma_{j} F_{\ell}
\end{aligned}
$$

as required.
Now, if $\beta_{j}<\mathbf{m h}$, we have

$$
\begin{aligned}
F_{j}^{\beta} & =\left[F_{n}^{\beta(n)} / F_{n}, \ldots, F_{0}^{\beta(0)} / F_{0}\right] \varphi_{j} \\
\varphi_{j}^{\beta} & =\left[\varphi_{n}^{\beta(n)} / F_{n}, \ldots, \varphi_{j}^{\beta(j)} / F_{j}\right] \gamma_{j} \varphi_{j} \\
& =\left[\varphi_{n}^{\beta(n)} / F_{n}, \ldots, \varphi_{j}^{\beta(j)} / F_{j},\right. \\
& \left.\gamma^{\prime} \gamma_{j} F_{j-1} / F_{j-1}, \ldots, \gamma^{\prime} \gamma_{j} F_{0} / F_{0}\right] \varphi_{j}
\end{aligned}
$$

by the definition of $F_{j}^{\beta}$ and $\varphi_{j}^{\beta}$, where

$$
\gamma^{\prime}=\left[\varphi_{n}^{\beta(n)} / F_{n}, \ldots, \varphi_{j}^{\beta(j)} / F_{j}\right] .
$$

By the induction hypothesis, $\llbracket F_{\ell}^{\beta(\ell)} \rrbracket=\llbracket \varphi_{\ell}^{\beta(\ell)} \rrbracket$ for $\ell \geq j$. For $\ell<j$, we have:

$$
\begin{gathered}
\llbracket F_{\ell}^{\beta(\ell)} \rrbracket=\llbracket \varphi_{\ell}^{\beta(\ell)} \rrbracket \\
=\llbracket \gamma^{\prime} \gamma_{j} F_{\ell} \rrbracket
\end{gathered} \quad \text { (by the induction hypothesis) } \quad \text { (by property (*) above) } .
$$

Thus, we have the required result.
The remaining is the case where $\beta_{j}=\mathbf{m h}$. For any $\beta^{\prime}=$ $\left(\beta_{n}, \ldots, \beta_{j+1}, m\right)$ for $0<m \leq \mathbf{m h}$, we have

$$
\begin{aligned}
& \llbracket F_{j}^{\beta^{\prime}} \rrbracket=\llbracket\left[F_{n}^{\beta^{\prime}(n)} / F_{n}, \ldots, F_{0}^{\beta^{\prime}(0)} / F_{0}\right] \varphi_{j} \rrbracket \\
& =\llbracket\left[\varphi_{n}^{\beta^{\prime}(n)} / F_{n}, \ldots, \varphi_{0}^{\beta^{\prime}(0)} / F_{0}\right] \varphi_{j} \rrbracket \\
& \quad \text { (by the induction hypothesis) } \\
& =\llbracket\left[\varphi_{n}^{\beta^{\prime}(n)} / F_{n}, \ldots, \varphi_{j}^{\beta^{\prime}(j)} / F_{j}\right]\left(\gamma_{j} \varphi_{j}\right) \rrbracket \\
& \quad \text { (by property }\left(^{*}\right) \text { above) } \\
& =\llbracket\left[\varphi_{j}^{\beta^{\prime}(j)} / F_{j}\right]\left[\varphi_{n}^{\beta^{\prime}(n)} / F_{n}, \ldots, \varphi_{j+1}^{\beta^{\prime}(j+1)} / F_{j+1}\right]\left(\gamma_{j} \varphi_{j}\right) \rrbracket \\
& \quad \text { (since } \varphi_{j}^{\beta^{\prime}(k)} \text { s sare closed) } \\
& =\llbracket\left(\lambda F_{j} \cdot\left[\varphi_{n}^{\beta(n)} / F_{n}, \ldots, \varphi_{j+1}^{\beta(j+1)} / F_{j+1}\right]\left(\gamma_{j} \varphi_{j}\right)\right) \rrbracket \llbracket \varphi_{j}^{\beta^{\prime}(j)} \rrbracket .
\end{aligned}
$$

Thus, we have:

$$
\llbracket F_{j}^{\beta} \rrbracket=f^{\mathbf{m h}} \llbracket \lambda x_{1} \cdots \lambda x_{\ell_{j}} \cdot \widehat{\alpha_{j}} \rrbracket
$$

for $f=\left(\llbracket\left(\lambda F_{j} \cdot\left[\varphi_{n}^{\beta(n)} / F_{n}, \ldots, \varphi_{j+1}^{\beta(j+1)} / F_{j+1}\right]\left(\gamma_{j} \varphi_{j}\right)\right) \rrbracket\right.$. By the Knaster-Tarski Theorem, we have:

$$
\llbracket F_{j}^{\beta} \rrbracket=\alpha_{j} F_{j} \cdot\left[\varphi_{n}^{\beta(n)} / F_{n}, \ldots, \varphi_{j+1}^{\beta(j+1)} / F_{j+1}\right]\left(\gamma_{j} \varphi_{j}\right)=\llbracket \varphi_{j}^{\beta} \rrbracket
$$

as required.
Finally, the required result follows as a special case of $\llbracket \varphi_{j}^{\beta} \rrbracket=\llbracket F_{j}^{\beta} \rrbracket$, where $j=n$ and $\beta=\mathbf{m h}$.

We assume below that $\eta_{j}=\eta_{j, 1} \rightarrow \cdots \rightarrow \eta_{j, \ell_{j}} \rightarrow \bullet$. We define $\lambda$-terms $e_{j}^{\beta}$ for each $j \in\{0, \ldots, n\}, \beta \in\{0, \ldots, \mathbf{m h}\}^{n-j+1}$ by induction on $\beta$ (with respect to the well-founded relation $<$ ):

$$
\begin{aligned}
& e_{j}^{\left(m_{n}, \ldots, m_{j+1}, 0\right)}=\lambda x_{1}: \eta_{j, 1}^{!} \cdots \lambda x_{\ell_{j}}: \eta_{j, \ell_{j}}^{!} \cdot \widehat{\alpha_{j}} \\
& e_{j}^{\beta}=\left[e_{0}^{\beta(0)} / F_{0}, \ldots, e_{n}^{\beta(n)} / F_{n}\right] \varphi_{j}^{!} \\
& \quad \text { if } \beta=\left(m_{n}, \ldots, m_{j}\right) \text { with } m_{j}>0 .
\end{aligned}
$$

Here, $(\cdot)^{!}$translates HFL formulas and types to terms and types of HORS, by simply replacing the proposition type with the tree type, and every logical connective with the corresponding tree constructor:

$$
\begin{array}{lll}
(\bullet)! \\
(c)^{!}=\star & \left(\eta_{1} \rightarrow \eta_{2}\right)^{!}=\eta_{1}^{!} \rightarrow \eta_{2}^{!} \\
(x)^{!}=x & \left(F_{i}\right)^{!}=F_{i} & \left(\varphi_{1} \varphi_{2}\right)^{!}=\left(\varphi_{1}\right)^{!}\left(\varphi_{2}\right)^{!}
\end{array}
$$

In the above definition, $c$ ranges over $\vee, \wedge,\langle a\rangle,[a], \top, \perp$, and the righthand side of $(c)^{!}$is the corresponding tree constructor of the same name. Notice that $e_{j}^{\beta}$ is essentially the same as the HFL formula $F_{j}^{\beta}$ defined in Section 6, except that each logical connective has been replaced by the corresponding tree constructor. We have:
Lemma 36. $s_{\text {init }} \in \llbracket F_{n}^{(\mathrm{mh})} \rrbracket$, if and only if $T_{e_{n}^{(\mathrm{mh})}}$ (i.e., the tree generated by $\left.e_{n}^{(\mathrm{mh})}\right)$ is accepted by $\mathcal{A}_{\mathcal{L}}$.

Proof. We define the logical relation $\sim_{\eta}$ between closed (fixpointfree) HFL formulas and $\lambda$-terms by:

- $\varphi \sim_{\bullet} e$ if (i) $\vdash \varphi: \bullet$, (ii) $e: \star$, and (iii) for every $s \in U$, $s \in \llbracket \varphi \rrbracket$ if and only if $T_{e}$ is accepted by $\mathcal{A}_{\mathcal{L}}$ from $q_{s}$.
- $\varphi \sim_{\eta_{1} \rightarrow \eta_{2}} e$ if (i) $\vdash \varphi: \eta_{1} \rightarrow \eta_{2}$, (ii) $\vdash e:\left(\eta_{1} \rightarrow \eta_{2}\right)^{!}$, and (iii) $\varphi \varphi^{\prime} \sim_{\eta_{2}} e e^{\prime}$ holds for every $\varphi^{\prime}, e^{\prime}$ such that $\varphi^{\prime} \sim_{\eta_{1}} e^{\prime}$.

Then, it follows that for every logical connective $c$ (and the corresponding tree constructor), $c \sim_{\eta_{c}} c$ holds (where $\eta_{\wedge}=\eta_{\vee}=\bullet \rightarrow$ $\bullet \rightarrow \bullet, \eta_{\langle a\rangle}=\eta_{[a]}=\bullet \rightarrow \bullet$, and $\left.\eta_{\top}=\eta_{\perp}=\bullet\right)$. By using the standard argument on logical relations and well-founded induction on $\beta$, we can prove $F_{j}^{\beta} \sim_{\eta_{j}} e_{j}^{\beta}$, from which $F_{n}^{(\mathbf{m h})} \sim_{\bullet} e_{n}^{(\mathbf{m h})}$ follows as a special case. Thus, we have the required result.

Now it remains to show that $e_{n}^{(\mathbf{m h})}$ is essentially equivalent to $\mathcal{G}_{\mathcal{E}, \mathcal{L}}$. For a term $e$ of HORS $\mathcal{G}_{\mathcal{E}, \mathcal{L}}$, we just write $T_{e}$ for the tree generated from $e$ (instead of the start symbol $S$ ).
Lemma 37. $T_{e_{n}^{(m h)}}$ is accepted by $\mathcal{A}_{\mathcal{L}}$ if and only if so is $T_{\mathcal{G}_{\mathcal{E}, \mathcal{L}}}$.
Proof. Let $\mathcal{N}$ be the second component of $\mathcal{G}_{\mathcal{E}, \mathcal{L}}$ (which is a map from non-terminals to their simple types). We define another logical relation $\sim_{\kappa}^{\prime}$ between terms of $\mathcal{G}_{\mathcal{E}, \mathcal{L}}$ (which may contain $\lambda$ abstractions) by:

- $e \sim_{\star}^{\prime} e^{\prime}$ if (i) $\vdash e: \star$, (ii) $\mathcal{N} \vdash e^{\prime}: \star$, and (iii) for every $s \in U$, $T_{e}$ is accepted by $\mathcal{A}_{\mathcal{L}}$ from $q_{s}$ if and only if $T_{e^{\prime}}$ is accepted by $\mathcal{A}_{\mathcal{L}}$ from $q_{s}$.
- $e \sim_{\kappa_{1} \rightarrow \kappa_{2}}^{\prime} e^{\prime}$ if (i) $\vdash e: \kappa_{1} \rightarrow \kappa_{2}$, (ii) $\mathcal{N} \vdash e^{\prime}: \kappa_{1} \rightarrow \kappa_{2}$, and (iii) $e e_{1} \sim_{\kappa_{2}}^{\prime} e^{\prime} e_{1}^{\prime}$ holds for every $e_{1}, e_{1}^{\prime}$ such that $e_{1} \sim_{\eta_{1}}^{\prime} e_{1}^{\prime}$.

Below we write $i^{\#}$ for $\operatorname{Dec}^{\mathbf{m h}-i} \operatorname{Max}_{k}$. When $\beta=\left(\beta_{n}, \ldots, \beta_{j}\right)$, we also write $\beta^{\#}$ for the sequence $\beta_{n}{ }^{\#} \cdots \beta_{j}{ }^{\#}$. We show:

$$
e_{j}^{\left(\beta_{n}, \ldots, \beta_{j}\right)} \sim_{\eta_{j}^{\prime}}^{\prime} F_{j} \beta_{n}^{\#} \cdots \beta_{j}^{\#}
$$

by well founded induction on $\beta=\left(\beta_{n}, \ldots, \beta_{j}\right)$. We need to show

$$
e_{j}^{\left(\beta_{n}, \ldots, \beta_{j}\right)} e_{1} \cdots e_{\ell_{j}} \sim_{\star}^{\prime} F_{j} \beta_{n} \# \cdots \beta_{j}^{\#} e_{1}^{\prime} \cdots e_{\ell_{j}}^{\prime}
$$

for every $e_{1}, \ldots, e_{\ell_{j}}, e_{1}^{\prime}, \ldots, e_{\ell_{j}}^{\prime}$ such that $e_{i} \sim_{\eta_{j, i}}^{\prime} e_{i}^{\prime}$.

- Case $\beta_{j}=0$ :

By the definition of $e_{j}^{\left(\beta_{n}, \ldots, \beta_{j}\right)}, T_{e_{j}^{\left(\beta_{n}, \ldots, \beta_{j}\right)}{ }_{e_{1} \cdots e_{\ell_{j}}}}=\widehat{\alpha_{j}}$. By the definition of $\mathcal{G}_{\mathcal{E}, \mathcal{L}}$,

$$
T_{F_{j} \beta_{n} \# \cdots \beta_{j} \# e_{1}^{\prime} \cdots e_{\ell_{j}}^{\prime}}=\text { if } T_{\text {Iszero }_{k}\left(\beta_{j} \#\right)} \widehat{\alpha_{j}} \cdots .
$$

By the assumption $\beta_{j}=0$ and by Lemma 20, $T_{\text {IsZero }_{i}\left(\beta_{j} \#\right)}$ is accepted from $q_{1}$. Thus, the whole tree is accepted from $q_{s}$ if and only if $\widehat{\alpha_{j}}$ is. Thus, we have the required result.

- Case $\beta_{j}>0$ :
$e_{j}^{\left(\beta_{n}, \ldots, \beta_{j}\right)} e_{1} \cdots e_{\ell_{j}}$ is reduced to:

$$
\left[e_{0}^{\beta(0)} / F_{0}, \ldots, e_{n}^{\beta(n)} / F_{n}, e_{1} / x_{1}, \ldots, e_{\ell_{j}} / x_{\ell_{j}}\right] \psi_{j}^{!}
$$

On the other hand,

$$
F_{j} \beta_{n}^{\#} \cdots \beta_{j}^{\#} e_{1}^{\prime} \cdots e_{\ell_{j}}^{\prime}
$$

is reduced to:

$$
\begin{aligned}
& \text { if } \quad\left(\operatorname{IsZero}_{k}\left(\beta_{j}{ }^{\#}\right) \widehat{\alpha_{j}}\right. \\
& \quad\left(\left[e_{1}^{\prime} / x_{1}, \ldots, e_{\ell_{j}}^{\prime} / x_{\ell_{j}}\right] \llbracket \psi_{j} \rrbracket_{\beta_{n} \#, \ldots,\left(\beta_{j}-1\right) \#}\right)
\end{aligned}
$$

The else part is actually equivalent to:

$$
\left[F_{0}(\beta(0))^{\#} / F_{0}, \ldots, F_{n}(\beta(n))^{\#} / F_{n}, e_{1}^{\prime} / x_{1}, \ldots, e_{\ell_{j}}^{\prime} / x_{\ell_{j}}\right] \psi_{j}^{\prime}
$$

By the induction hypothesis, $e_{i}^{\beta(i)} \sim_{\eta_{i}^{\prime}}^{\prime} F_{i}(\beta(i))^{\#}$. Thus, by the standard logical relation argument, we obtain

$$
\begin{aligned}
& {\left[e_{0}^{\beta(0)} / F_{0}, \ldots, e_{n}^{\beta(n)} / F_{n}, e_{1} / x_{1}, \ldots, e_{\ell_{j}} / x_{\ell_{j}}\right] \psi_{j}^{!}} \\
& \sim_{\eta_{j}^{\prime}}^{\prime} \\
& {\left[F_{0}(\beta(0))^{\#} / F_{0}, \ldots, F_{n}(\beta(n))^{\#} / F_{n}, e_{1}^{\prime} / x_{1}, \ldots, e_{\ell_{j}}^{\prime} / x_{\ell_{j}}\right] \psi_{j}^{\prime} .}
\end{aligned}
$$

By the condition $\beta_{j}>0$ and Lemma 20, $T_{\text {Iszero }_{k}\left(\beta_{j} \#\right)}$ is accepted from $q_{0}$. Thus, we have the required result.

Proof of Theorem 22. This follows immediately from Lemmas 21, 36, and 37.


[^0]:    ${ }^{1}$ It is necessarily so because the decidability of HORS model checking is non-trivial (and in fact, it has been the subject of many papers [6, 13, 24, 27]) whereas that of HFL model checking is straightforward; a proof of the correctness of the HORS-to-HFL translation would therefore serve as an alternative proof of the decidability of HORS model checking.

[^1]:    ${ }^{2}$ Following the usual convention, we write $x_{1}: \kappa_{1}, \ldots, x_{n}: \kappa_{n}$ instead of $\left\{x_{1} \mapsto \kappa_{1}, \ldots, x_{n} \mapsto \kappa_{n}\right\}$ for a type environment.

[^2]:    ${ }^{3}$ The least upper bound always exists, as $\longrightarrow$ is confluent.

[^3]:    ${ }^{4}$ For example, since the priority 0 does not occur, we can eliminate the first argument $g^{\sharp 0}$ of $F$. Similarly, we can also eliminate $\left\langle\mathrm{c}_{2}\right\rangle L_{0}$ from $\varphi_{F}$ because the $c_{2}$ transition cannot be taken at the end of a path labeled with $\left(\mathrm{a}_{0}+\mathrm{a}_{1}\right)(1+2+\text { and }+ \text { or })^{*}$.

[^4]:    ${ }^{5}$ Thus, for example, $T$ is actually annotated like $T^{\kappa}$. Without this assumption on the implicit annotation, Stype $(T)$ cannot be determined.

[^5]:    ${ }^{6}$ The type system presented in this section is actually a slight variation of the original one [15], but the proof in [15] can be easily adapted to this variation.

[^6]:    ${ }^{7}$ The full definition is given later in Section 6.3.

[^7]:    $\overline{{ }^{8}}$ The only dependence of $\mathcal{G}_{\mathcal{E}, \mathcal{L}}$ on $\mathcal{L}$ is via $r$.

[^8]:    ${ }^{9}$ Player's history-sensitive strategy $\mathcal{W}$ for a parity game is a partial map from $\left(V_{\forall} \cup V_{\exists}\right)^{*} V_{\exists}$ to $V_{\forall} \cup V_{\exists}$. It is winning if Player wins every play that conforms to $\mathcal{W}$, i.e., every play $v_{\text {init }} v_{1} v_{2} \cdots$ such that $\forall n . v_{n} \in V_{\exists} \Longrightarrow$ $v_{n+1}=\mathcal{W}\left(v_{\text {init }} \cdots v_{n}\right)$. It is known that if there is a history-sensitive winning strategy, there also exists a memoryless winning strategy [5].

