

# RustHorn: CHC-based Verification for **Rust** Programs

## ESOP2020

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## Background

# CHCs for Automated Verification

- Reduction to **Constrained Horn Clauses (CHCs)** is a widely studied approach to **automated verification**

[Grebenshchikov+, 2012] [Björner+, 2015]

*Program &  
Verified Property*

```
int mc91(int n) {  
    if (n > 100) return n - 10;  
    else return mc91(mc91(n + 11));  
}
```

“for any  $n \leq 101$ ,  $mc91(n)$  returns  $91$  if it terminates”

↓ *reduction*

*CHC System &  
Satisfiability*

*input output*  
 $Mc91(n, r) \iff n > 100 \wedge r = n - 10$   
 $Mc91(n, r) \iff n \leq 100 \wedge Mc91(n + 11, r') \wedge Mc91(r', r)$   
 $r = 91 \iff n \leq 101 \wedge Mc91(n, r)$

“this CHC system is **satisfiable**”

A **CHC solver automatically finds out a solution** to the CHC system, e.g.:

$$Mc91(n, r) :\iff r = 91 \vee (n > 100 \wedge r = n - 10)$$

## Background

# Difficulties with Pointers

- Existing method: **Model the memory as an array** [Gurfinkel+, 2015]
  - Not very scalable**; *quantified invariants* are involved for even easy programs

*Pointer-Manipulating Program*

```
bool just_rec(int *ma) {  
    if (rand() >= 0) return true;  
    int old_a = *ma; int b = rand(); just_rec(&b);  
    return (old_a == *ma);  
}
```

“**just\_rec**(ma) always returns **true** if it terminates”

↓ *reduction by the existing method*

$JustRec(ma, h, sp, h', sp', r) \iff h' = h \wedge sp' = sp \wedge r = \text{true}$  *memory update*

$JustRec(ma, h, sp, h', sp', r) \iff mb = sp'' = sp + 1 \wedge h'' = h\{mb \leftarrow b\} \wedge$  *memory read*  
 $JustRec(mb, h'', sp'', h', sp', r) \wedge r = (h[ma] = h'[ma])$

$r = \text{true} \iff JustRec(ma, h, sp, h', sp', r) \wedge ma \leq sp$  *address constraint*

Solution:  $JustRec(ma, h, sp, h', sp', r) \iff r = \text{true} \wedge \forall i \leq sp. h[i] = h'[i]$

*quantified invariant* 3

# Our Work

Focusing on programs whose **pointer usages** are managed under **ownership** in the style of the **Rust programming language**,

- We propose a **novel translation** from programs to CHCs **clearing away pointers and heaps**.
- Also, we formalize and prove its correctness and confirm the effectiveness by experiments.

# Table of Contents

- Ownership and Borrow in Rust
- Our Method
- Formalization and Correctness Proof
- Experiments and Evaluation

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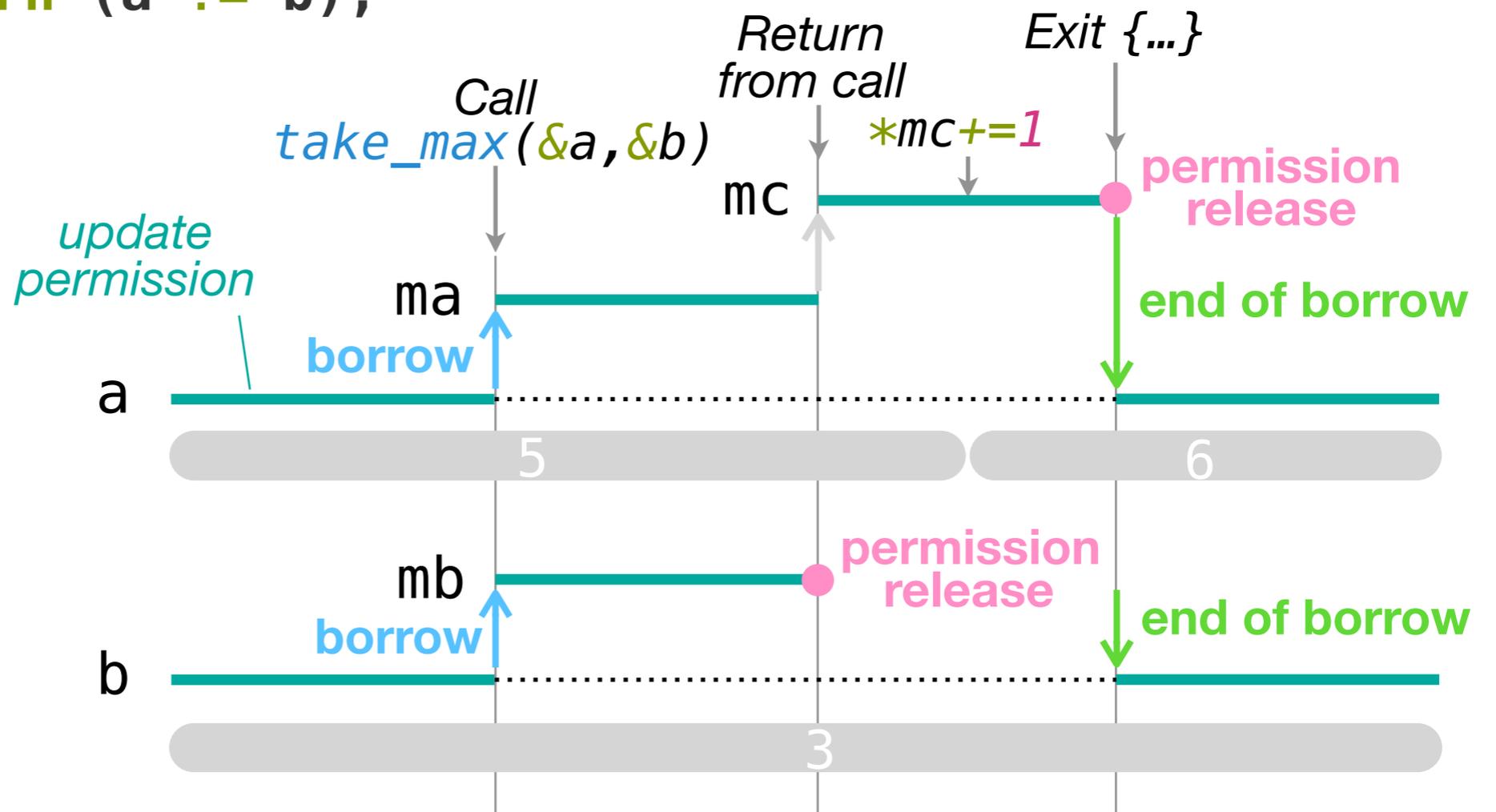
# Ownership and Borrow in Rust

- The ownership system guarantees that:
  - For each memory cell and **at each moment**, we have
    - (i) **only one alias** with the **update permission** to the cell; or
    - (ii) **some aliases** with the **read permission** to the cell
  - *“If an alias can read data, any other alias cannot update it”*
- **Borrow**: *a temporary transfer of a permission*
  - This makes Rust really interesting!
  - The end of borrow is statically managed by *lifetimes*

# Example of Borrow

```
int *take_max(int *ma, int *mb) {  
    if (*ma >= *mb) return ma; else return mb;  
}  
  
bool inc_max(int a, int b) {  
    { int *mc = take_max(&a, &b); // borrow a & b  
      *mc += 1; } // end of borrow  
    return (a != b);  
}
```

When `inc_max(5, 3)`  
is called



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# Our Method

**mutable reference** (i.e. pointer with a **borrowed** update permission)

- Model a **pointer**  $ma$  simply as a **pair of values**  $\langle a, a_0 \rangle$ 
  - the **current value**  $a$  & the **value**  $a_0$  **at the end of borrow**
  - Access to the **future information** is related to **prophecy variables** [Abadi & Lamport, 1991] [Jung+, 2020]

# Our Method

Our model of pointer ma

$\langle a, a_0 \rangle$

How can this work?

# Example 1: take\_max/inc\_max

```

int *take_max(int *ma, int *mb) {
    if (*ma >= *mb) return ma; else return mb;
}

bool inc_max(int a, int b) {
    { int *mc = take_max(&a, &b); // borrow a & b
      *mc += 1; } // end of borrow
    return (a != b);
}

```

“for any **a** & **b**, **inc\_max(a, b)** returns **true**”

↓ reduction by our method

$$\begin{aligned}
 \text{TakeMax}(\langle a, a_{\circ} \rangle, \langle b, b_{\circ} \rangle, r) &\iff a \geq b \wedge b_{\circ} = b \wedge r = \langle a, a_{\circ} \rangle \\
 \text{TakeMax}(\langle a, a_{\circ} \rangle, \langle b, b_{\circ} \rangle, r) &\iff a < b \wedge a_{\circ} = a \wedge r = \langle b, b_{\circ} \rangle \\
 \text{IncMax}(a, b, r) &\iff \text{TakeMax}(\langle a, a_{\circ} \rangle, \langle b, b_{\circ} \rangle, \langle c, c_{\circ} \rangle) \wedge c' = c + 1 \wedge \\
 &\quad c_{\circ} = c' \wedge r = (a_{\circ} \neq b_{\circ}) \\
 r = \text{true} &\iff \text{IncMax}(a, b, r)
 \end{aligned}$$

*permission release* (pink arrow from  $b_{\circ} = b$  to  $a_{\circ} = a$ )  
*borrow* (blue arrow from  $\langle c, c_{\circ} \rangle$  to  $a_{\circ} \neq b_{\circ}$ )  
*permission release* (pink arrow from  $c_{\circ} = c'$  to  $r = (a_{\circ} \neq b_{\circ})$ )

**Key idea: set  $x_{\circ} = x$  when the permission of  $mx = \langle x, x_{\circ} \rangle$  is released**

# Example II: take\_some/inc\_some

- Our method works well with **recursive data types!**
  - This makes our method strong and interesting

```
enum List { Cons(i32, Box<List>), Nil } use List::*;
```

```
fn take_some(mxs: &mut List) -> &mut i32 {  
  match mxs {  
    Cons(mx, mxs2) => if rand() { mx } else { take_some(mxs2) }  
    Nil => take_some(mxs)  
  }  
}
```

*take\_some(mxs) takes a mutable reference to a randomly chosen element of \*mxs*

```
fn sum(xs:&List)->i32 { match xs {Cons(x,xs2)=>x+sum(xs2),Nil=>0} }
```

```
fn inc_some(mut xs: List) -> bool {  
  let n = sum(&xs); let my = take_some(&mut xs);  
  *my += 1; sum(&xs) == n + 1  
}
```

*inc\_some(xs) increments some element of xs and checks that the sum has increased by 1*

# Example II: take\_some/inc\_some

```
fn take_some(mx: &mut List) -> &mut i32 {
  match mx {
    Cons(mx, mxs2) => if rand() { mx } else { take_some(mxs2) }
    Nil => take_some(mx)
  }
}

fn inc_some(mut xs: List) -> bool {
  let n = sum(&xs); let my = take_some(&mut xs);
  *my += 1; sum(&xs) == n + 1
}
```

“for any  $xs$ ,  $inc\_some(xs)$  always returns **true** if it terminates”

↓ *reduction by our method*

$$TakeSome(\langle [x | xs'], xs_0 \rangle, r) \iff xs_0 = [x_0 | xs'_0] \wedge xs'_0 = xs' \wedge r = \langle x, x_0 \rangle$$

$$TakeSome(\langle [x | xs'], xs_0 \rangle, r) \iff xs_0 = [x_0 | xs'_0] \wedge x_0 = x \wedge TakeSome(\langle xs', xs'_0 \rangle, r)$$

$$TakeSome(\langle [], xs_0 \rangle, r) \iff TakeSome(\langle [], xs_0 \rangle, r)$$

$$IncSome(xs, r) \iff TakeSome(\langle xs, xs_0 \rangle, \langle y, y_0 \rangle) \wedge y_0 = y + 1 \wedge r = (\text{sum}(xs_0) = \text{sum}(xs) + 1)$$

$$r = \text{true} \iff IncSome(xs, r)$$

It has a **simple solution**:  $TakeSome(\langle xs, xs_0 \rangle, \langle y, y_0 \rangle) \iff y_0 - y = \text{sum}(xs_0) - \text{sum}(xs)$   
 $IncSome(xs, r) \iff r = \text{true}$

# Going Beyond CHCs

- Our method can be extended into **reduction from a Rust program to a functional program**
- By this view we can **apply various verification techniques to Rust** (e.g. model checking, Boogie, Coq)

```
int *take_max(int *ma, int *mb) {  
    if (*ma >= *mb) return ma; else return mb;  
}  
  
bool inc_max(int a, int b) {  
    { int *mc = take_max(&a, &b); // borrow a & b  
      *mc += 1; } // end of borrow  
    return (a != b);  
}
```

↓ *reduction to a functional program*

```
let take_max (a, a') (b, b') =  
    if a >= b then (assume (b' = b); (a, a'))  
    else (assume (a' = a); (b, b'))
```

```
let inc_max a b =  
    let a' = rand () in let b' = rand () in  
    let (c, c') = take_max (a, a') (b, b') in  
    assume (c' = c + 1); a' <> b'
```

*permission release*

# Advanced Features

- **Closure**
  - **Permission release** on the enclosed data is the twist
  - **FnMut** can be modeled as a closure that **generates a newer version of itself** after it is called
- **RefCell<T>** etc.
  - We need to deal with **real sharing of data**
  - Simple remedy: pass around a global array for `RefCell` values
    - **At the very time a mutable reference  $\langle a, a_0 \rangle$  is taken from a `RefCell`, the data at the array is updated into  $a_0$ .**

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# Formalization and Correctness Proof

- **Formalized the core of Rust**
  - Similar to  $\lambda_{\text{Rust}}$  of RustBelt [Jung+, 2018] but ours is simpler; **permission releases** and **lifetimes** are made explicit
- **Proved the correctness of the translation**
  - By techniques based on **bisimulations**
  - A concept strongly related to **prophecy variables** is used

# Formalization and Correctness Proof

$$\begin{aligned} \llbracket L: \text{let } y = \text{mutbor}_\alpha x; \text{goto } L' \rrbracket_{\Pi, f} & := \begin{cases} \left\{ \begin{array}{l} \forall (\Delta_{\Pi, f, L} + \{(x_\circ, \langle T \rangle)\}). \\ \tilde{\varphi}_{\Pi, f, L} \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle *x, x_\circ \rangle / y, \langle x_\circ \rangle / x] \end{array} \right\} & (\text{Ty}_{\Pi, f, L}(x) = \text{own } T) \\ \left\{ \begin{array}{l} \forall (\Delta_{\Pi, f, L} + \{(x_\circ, \langle T \rangle)\}). \\ \tilde{\varphi}_{\Pi, f, L} \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle *x, x_\circ \rangle / y, \langle x_\circ, \circ x \rangle / x] \end{array} \right\} & (\text{Ty}_{\Pi, f, L}(x) = \text{mut}_\alpha T) \end{cases} \\ \llbracket L: \text{drop } x; \text{goto } L' \rrbracket_{\Pi, f} & := \begin{cases} \left\{ \begin{array}{l} \forall (\Delta_{\Pi, f, L}). \tilde{\varphi}_{\Pi, f, L} \leftarrow \tilde{\varphi}_{\Pi, f, L'} \end{array} \right\} & (\text{Ty}_{\Pi, f, L}(x) = \check{P} T) \\ \left\{ \begin{array}{l} \forall (\Delta_{\Pi, f, L} - \{(x, \text{mut } \langle T \rangle)\} + \{(x_*, \langle T \rangle)\}). \\ \tilde{\varphi}_{\Pi, f, L}[\langle x_*, x_* \rangle / x] \leftarrow \tilde{\varphi}_{\Pi, f, L'} \end{array} \right\} & (\text{Ty}_{\Pi, f, L}(x) = \text{mut}_\alpha T) \end{cases} \\ \llbracket L: \text{immut } x; \text{goto } L' \rrbracket_{\Pi, f} & := \left\{ \begin{array}{l} \forall (\Delta_{\Pi, f, L} - \{(x, \text{mut } \langle T \rangle)\} + \{(x_*, \langle T \rangle)\}). \\ \tilde{\varphi}_{\Pi, f, L}[\langle x_*, x_* \rangle / x] \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle x_* \rangle / x] \end{array} \right\} \quad (\text{Ty}_{\Pi, f, L}(x) = \text{mut}_\alpha T) \end{aligned}$$

$$\begin{aligned} \llbracket L: \text{swap}(*x, *y); \text{goto } L' \rrbracket_{\Pi, f} & := \left\{ \begin{array}{l} \forall (\Delta_{\Pi, f, L}). \tilde{\varphi}_{\Pi, f, L} \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle *y, \circ x \rangle / x, \langle *x \rangle / y] \\ \forall (\Delta_{\Pi, f, L}). \tilde{\varphi}_{\Pi, f, L} \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle *y, \circ x \rangle / x, \langle *x, \circ y \rangle / y] \end{array} \right\} \\ & \quad (\text{Ty}_{\Pi, f, L}(y) = \text{own } T) \quad (\text{Ty}_{\Pi, f, L}(y) = \text{mut}_\alpha T) \\ \llbracket L: \text{let } *y = x; \text{goto } L' \rrbracket_{\Pi, f} & := \left\{ \forall (\Delta_{\Pi, f, L}). \tilde{\varphi}_{\Pi, f, L} \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle x \rangle / y] \right\} \end{aligned}$$

$$\begin{aligned} \llbracket L: \text{let } y = *x; \text{goto } L' \rrbracket_{\Pi, f} & := \begin{cases} \left\{ \begin{array}{l} \forall (\Delta_{\Pi, f, L}). \tilde{\varphi}_{\Pi, f, L} \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle *x / y \rangle] \\ \forall (\Delta_{\Pi, f, L}). \tilde{\varphi}_{\Pi, f, L} \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle **x \rangle / y] \\ \forall (\Delta_{\Pi, f, L}). \tilde{\varphi}_{\Pi, f, L} \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle **x, * \circ x \rangle / y] \end{array} \right\} & (\text{Ty}_{\Pi, f, L}(x) = \text{own } PT) \\ \left\{ \begin{array}{l} \forall (\Delta_{\Pi, f, L}). \tilde{\varphi}_{\Pi, f, L} \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle **x \rangle / y] \\ \forall (\Delta_{\Pi, f, L}). \tilde{\varphi}_{\Pi, f, L} \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle **x, * \circ x \rangle / y] \end{array} \right\} & (\text{Ty}_{\Pi, f, L}(x) = \text{immut}_\alpha PT) \\ \left\{ \begin{array}{l} \forall (\Delta_{\Pi, f, L}). \tilde{\varphi}_{\Pi, f, L} \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle **x, * \circ x \rangle / y] \\ \forall (\Delta_{\Pi, f, L} - \{(x, \text{mut box } \langle T \rangle)\} + \{(x_*, \text{box } \langle T \rangle)\}). \\ \tilde{\varphi}_{\Pi, f, L}[\langle x_*, x_* \rangle / x] \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle x_* / y \rangle] \end{array} \right\} & (\text{Ty}_{\Pi, f, L}(x) = \text{mut}_\alpha \text{immut}_\beta T) \\ \left\{ \begin{array}{l} \forall (\Delta_{\Pi, f, L} - \{(x, \text{mut mut } \langle T \rangle)\} \\ + \{(x_*, \text{mut } \langle T \rangle), (x_{* \circ}, \langle T \rangle)\}). \\ \tilde{\varphi}_{\Pi, f, L}[\langle x_*, \langle x_{* \circ}, \circ x_* \rangle \rangle / x] \\ \leftarrow \tilde{\varphi}_{\Pi, f, L'}[\langle *x_*, x_{* \circ} \rangle / y] \end{array} \right\} & (\text{Ty}_{\Pi, f, L}(x) = \text{mut}_\alpha \text{mut}_\beta T) \end{cases} \end{aligned}$$

$$\begin{aligned} S_{\Pi, f, L} = \text{let } y = \text{mutbor}_\alpha x; \text{goto } L' \quad x_\circ \text{ is fresh} & \frac{}{[f, L]_{\Theta} \mathcal{F} + \{(x, \langle \hat{v}_* \rangle)\}; \mathcal{S} \mid_{\mathbf{A}} \rightarrow_{\Pi} [f, L']_{\Theta} \mathcal{F} + \{(y, \langle \hat{v}_*, x_\circ \rangle), (x, \langle x_\circ \rangle)\}; \mathcal{S} \mid_{\mathbf{A}}} \\ S_{\Pi, f, L} = \text{let } y = \text{mutbor}_\alpha x; \text{goto } L' \quad x_\circ \text{ is fresh} & \frac{}{[f, L]_{\Theta} \mathcal{F} + \{(x, \langle \hat{v}_*, x'_\circ \rangle)\}; \mathcal{S} \mid_{\mathbf{A}} \rightarrow_{\Pi} [f, L']_{\Theta} \mathcal{F} + \{(y, \langle \hat{v}_*, x_\circ \rangle), (x, \langle x_\circ, x'_\circ \rangle)\}; \mathcal{S} \mid_{\mathbf{A}}} \\ S_{\Pi, f, L} = \text{drop } x; \text{goto } L' \quad \text{Ty}_{\Pi, f, L}(x) = \check{P} T & \frac{}{[f, L]_{\Theta} \mathcal{F} + \{(x, \hat{v})\}; \mathcal{S} \mid_{\mathbf{A}} \rightarrow_{\Pi} [f, L']_{\Theta} \mathcal{F}; \mathcal{S} \mid_{\mathbf{A}}} \\ S_{\Pi, f, L} = \text{drop } x; \text{goto } L' \quad \text{Ty}_{\Pi, f, L}(x) = \text{mut}_\alpha T & \frac{}{[f, L]_{\Theta} \mathcal{F} + \{(x, \langle \hat{v}_*, x_\circ \rangle)\}; \mathcal{S} \mid_{\mathbf{A}} \rightarrow_{\Pi} ([f, L']_{\Theta} \mathcal{F}; \mathcal{S} \mid_{\mathbf{A}}) [\hat{v}_* / x_\circ]} \\ S_{\Pi, f, L} = \text{immut } x; \text{goto } L' & \frac{}{[f, L]_{\Theta} \mathcal{F} + \{(x, \langle \hat{v}_*, x_\circ \rangle)\}; \mathcal{S} \mid_{\mathbf{A}} \rightarrow_{\Pi} ([f, L']_{\Theta} \mathcal{F} + \{(x, \langle \hat{v}_* \rangle)\}; \mathcal{S} \mid_{\mathbf{A}}) [\hat{v}_* / x_\circ]} \\ S_{\Pi, f, L} = \text{swap}(*x, *y); \text{goto } L' \quad \text{Ty}_{\Pi, f, L}(y) = \text{own } T & \frac{}{[f, L]_{\Theta} \mathcal{F} + \{(x, \langle \hat{v}_*, x_\circ \rangle), (y, \langle \hat{w}_* \rangle)\}; \mathcal{S} \mid_{\mathbf{A}} \rightarrow_{\Pi} [f, L']_{\Theta} \mathcal{F} + \{(x, \langle \hat{w}_*, x_\circ \rangle), (y, \langle \hat{v}_* \rangle)\}; \mathcal{S} \mid_{\mathbf{A}}} \\ S_{\Pi, f, L} = \text{swap}(*x, *y); \text{goto } L' \quad \text{Ty}_{\Pi, f, L}(y) = \text{mut}_\alpha T & \frac{}{[f, L]_{\Theta} \mathcal{F} + \{(x, \langle \hat{v}_*, x_\circ \rangle), (y, \langle \hat{w}_*, y_\circ \rangle)\}; \mathcal{S} \mid_{\mathbf{A}} \rightarrow_{\Pi} [f, L']_{\Theta} \mathcal{F} + \{(x, \langle \hat{w}_*, x_\circ \rangle), (y, \langle \hat{v}_*, y_\circ \rangle)\}; \mathcal{S} \mid_{\mathbf{A}}}\end{aligned}$$

$$\begin{aligned} \text{summary}_D^{\dagger \alpha}(\mathbf{x} :: T \mid \{\text{take}^{\dagger \alpha}(\mathbf{x} :: T)\}) & \frac{\text{summary}_D^{\dagger \alpha}(\hat{v} :: T \mid \mathcal{X})}{\text{summary}_D^{\dagger \alpha}(\langle \hat{v} \rangle :: \check{P} T \mid \mathcal{X})} \\ D \cdot \text{own} := D \quad D \cdot \text{immut}_\beta := \text{cold} & \\ \text{summary}_D^{\dagger \alpha}(\hat{v} :: T \mid \mathcal{X}) & \frac{\text{summary}_D^{\dagger \alpha}(\hat{v} :: T \mid \mathcal{X})}{\text{summary}_{\text{hot}}^{\dagger \alpha}(\langle \hat{v}, \mathbf{x} \rangle :: \text{mut}_\beta T \mid \mathcal{X} \oplus \{\text{give}_\beta(\mathbf{x} :: T)\})} \quad \frac{\text{summary}_D^{\dagger \alpha}(\hat{v} :: T \mid \mathcal{X})}{\text{summary}_{\text{cold}}^{\dagger \alpha}(\langle \hat{v}, \mathbf{x} \rangle :: \text{mut}_\beta T \mid \mathcal{X})} \\ \text{summary}_D^{\dagger \alpha}(\hat{v} :: T \mid \mathcal{X}) & \frac{\text{summary}_D^{\dagger \alpha}(\hat{v} :: T \mid \mathcal{X})}{\text{summary}_D^{\dagger \alpha}(\hat{v} :: \mu X.T/X \mid \mathcal{X})} \quad \frac{\text{summary}_D^{\dagger \alpha}(\text{const} :: T \mid \emptyset)}{\text{summary}_D^{\dagger \alpha}(\hat{v} :: \mu X.T/X \mid \mathcal{X})} \\ \text{summary}_D^{\dagger \alpha}(\hat{v} :: T_i \mid \mathcal{X}) & \frac{\text{summary}_D^{\dagger \alpha}(\hat{v}_0 :: T_0 \mid \mathcal{X}_0) \quad \text{summary}_D^{\dagger \alpha}(\hat{v}_1 :: T_1 \mid \mathcal{X}_1)}{\text{summary}_D^{\dagger \alpha}(\text{inj}_i \hat{v} :: T_0 + T_1 \mid \mathcal{X})} \quad \frac{\text{summary}_D^{\dagger \alpha}(\hat{v}_0 :: T_0 \mid \mathcal{X}_0) \quad \text{summary}_D^{\dagger \alpha}(\hat{v}_1 :: T_1 \mid \mathcal{X}_1)}{\text{summary}_D^{\dagger \alpha}((\hat{v}_0, \hat{v}_1) :: T_0 \times T_1 \mid \mathcal{X}_0 \oplus \mathcal{X}_1)} \end{aligned}$$

$$\begin{aligned} \text{readout}_{\mathbf{H}, D, \hat{P}}^{\dagger \alpha}(*a :: T \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}}) & \frac{\text{readout}_{\mathbf{H}, D, \hat{P}}^{\dagger \alpha}(*a :: T \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}})}{\text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(a :: \check{P} T \mid \langle \hat{v} \rangle; \hat{\mathcal{X}}, \hat{\mathcal{M}})} \\ \hat{D} \circ \text{own} := \hat{D} \quad \text{hot} \circ \text{immut}_\beta := \text{cold}_\beta \quad \text{cold}_\alpha \circ \text{immut}_\beta := \text{cold}_\alpha & \\ \text{readout}_{\mathbf{H}, \text{hot}}^{\dagger \alpha}(*a :: T \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}}) & \frac{\text{readout}_{\mathbf{H}, \text{hot}}^{\dagger \alpha}(*a :: T \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}})}{\text{readout}_{\mathbf{H}, \text{hot}}^{\dagger \alpha}(a :: \text{mut}_\beta T \mid \langle \hat{v}, \mathbf{x} \rangle; \hat{\mathcal{X}} \oplus \{\text{give}_\beta(*a; \mathbf{x} :: T)\}, \hat{\mathcal{M}})} \\ \text{readout}_{\mathbf{H}, \text{cold}_\beta}^{\dagger \alpha}(*a :: T \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}}) & \frac{\text{readout}_{\mathbf{H}, \text{cold}_\beta}^{\dagger \alpha}(*a :: T \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}})}{\text{readout}_{\mathbf{H}, \text{cold}_\beta}^{\dagger \alpha}(a :: \text{mut}_{\beta'} T \mid \langle \hat{v}, \mathbf{x} \rangle; \hat{\mathcal{X}}, \hat{\mathcal{M}})} \\ \text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: T \mid \mathbf{x}; \{\text{take}^{\dagger \alpha}(*a; \mathbf{x} :: T)\}, \emptyset) & \frac{\text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: T \mid \mathbf{x}; \{\text{take}^{\dagger \alpha}(*a; \mathbf{x} :: T)\}, \emptyset)}{\mathbf{H}(a) = a' \quad \text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(a' :: PT \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}})} \\ \text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: PT \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}} \oplus \{\hat{D}^{\dagger \alpha}(a)\}) & \frac{\text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: PT \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}} \oplus \{\hat{D}^{\dagger \alpha}(a)\})}{\hat{D}^{\dagger \alpha}(a) := \begin{cases} \text{hot}^{\dagger \alpha}(a) & (\hat{D} = \text{hot}) \\ \text{cold}_\beta^{\dagger \alpha}(a) & (\hat{D} = \text{cold}_\beta) \end{cases}} \\ \text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: T[\mu X.T/X] \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}}) & \frac{\text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: T[\mu X.T/X] \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}})}{\text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: \mu X.T \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}})} \\ \mathbf{H}(a) = n & \frac{\mathbf{H}(a) = n}{\text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: \text{int} \mid n; \emptyset, \{\hat{D}^{\dagger \alpha}(a)\})} \quad \text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: \text{unit} \mid (); \emptyset, \emptyset) \\ \mathbf{H}(a) = i \in [2] \quad \text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a+1 :: T_i \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}}) \quad n_0 = (\#T_{1-i} - \#T_i)_{\geq 0} & \frac{\mathbf{H}(a) = i \in [2] \quad \text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a+1 :: T_i \mid \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}}) \quad n_0 = (\#T_{1-i} - \#T_i)_{\geq 0}}{\text{for any } k \in [n_0], \mathbf{H}(a+1 + \#T_i + k) = 0 \quad \hat{\mathcal{M}}_0 = \{\hat{D}^{\dagger \alpha}(a+1 + \#T_i + k) \mid k \in [n_0]\}} \\ \text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: T_0 + T_1 \mid \text{inj}_i \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}} \oplus \{\hat{D}^{\dagger \alpha}(a)\} \oplus \hat{\mathcal{M}}_0) & \frac{\text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: T_0 + T_1 \mid \text{inj}_i \hat{v}; \hat{\mathcal{X}}, \hat{\mathcal{M}} \oplus \{\hat{D}^{\dagger \alpha}(a)\} \oplus \hat{\mathcal{M}}_0)}{\text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: T_0 \mid \hat{v}_0; \hat{\mathcal{X}}_0, \hat{\mathcal{M}}_0) \quad \text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a + \#T_0 :: T_1 \mid \hat{v}_1; \hat{\mathcal{X}}_1, \hat{\mathcal{M}}_1)} \\ \text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: T_0 \times T_1 \mid (\hat{v}_0, \hat{v}_1); \hat{\mathcal{X}}_0 \oplus \hat{\mathcal{X}}_1, \hat{\mathcal{M}}_0 \oplus \hat{\mathcal{M}}_1) & \frac{\text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: T_0 \times T_1 \mid (\hat{v}_0, \hat{v}_1); \hat{\mathcal{X}}_0 \oplus \hat{\mathcal{X}}_1, \hat{\mathcal{M}}_0 \oplus \hat{\mathcal{M}}_1)}{\text{readout}_{\mathbf{H}, D}^{\dagger \alpha}(*a :: T_0 \times T_1 \mid (\hat{v}_0, \hat{v}_1); \hat{\mathcal{X}}_0 \oplus \hat{\mathcal{X}}_1, \hat{\mathcal{M}}_0 \oplus \hat{\mathcal{M}}_1)} \end{aligned}$$

$$\frac{\mathcal{X}(x) = \{\text{give}_\alpha(\mathbf{x} :: T), \text{take}^{\dagger \beta}(\mathbf{x} :: T')\} \quad T \sim_{\mathbf{A}} T' \quad \alpha \leq_{\mathbf{A}} \beta \quad \mathcal{X}(\mathbf{x}) = \emptyset}{\text{safe}_{\mathbf{A}}(\mathbf{x}, \mathcal{X})} \quad \frac{\mathcal{X}(\mathbf{x}) = \emptyset}{\text{safe}_{\mathbf{A}}(\mathbf{x}, \mathcal{X})}$$

$\mathcal{X}(\mathbf{x})$ : the multiset of the items of form 'give $_\gamma(\mathbf{x} :: U)$ '/'take $^\gamma(\mathbf{x} :: U)$ ' in  $\mathcal{X}$

# Table of Contents

- Ownership and Borrow in Rust
- Our Method
- Formalization and Correctness Proof
- **Experiments and Evaluation**

# Implementation and Experiments

- Implemented a **prototype verifier** **RustHorn**
  - Uses **MIR** (mid-level intermediate representation) of the Rust compiler
  - Generates CHCs with a **simple algorithm** based on **our method**
- Conducted **experiments** on benchmarks
  - Tested **RustHorn** and **SeaHorn** [Gurfinkel+, 2015]
    - SeaHorn is a standard CHC-based verifier for C programs
  - Made **benchmark** verification problems in **Rust & C**
    - Took ones from SeaHorn and also wrote ones featuring pointers
  - Used **Z3/Spacer** [Komuravelli+, 2014] and **Holce** [Champion+, 2018] as a backend CHC solver

check out [github.com/hopv/rust-horn](https://github.com/hopv/rust-horn)

# Experimental Results

Group	Instance	Property	RustHorn		SeaHorn <i>w/Spacer</i>	
			<i>w/Spacer</i>	<i>w/HoIce</i>	<i>as is</i>	<i>modified</i>
simple	01	safe	<0.1	<0.1	<0.1	
	04-recursive	safe	0.5	timeout	0.8	
	05-recursive	unsafe	<0.1	<0.1	<0.1	
	06-loop	safe	timeout	0.1	timeout	
	hhk2008	safe	timeout	40.5	<0.1	
	unique-scalar	unsafe	<0.1	<0.1	<0.1	
bmc	1	safe	0.2	<0.1	<0.1	
		unsafe	0.2	<0.1	<0.1	
	2	safe	timeout	0.1	<0.1	
		unsafe	<0.1	<0.1	<0.1	
	3	safe	<0.1	<0.1	<0.1	
		unsafe	<0.1	<0.1	<0.1	
	diamond-1	safe	0.1	<0.1	<0.1	
	diamond-2	unsafe	<0.1	<0.1	<0.1	
inc-max	base	safe	<0.1	<0.1	false alarm	<0.1
		unsafe	<0.1	<0.1	<0.1	<0.1
	base/3	safe	<0.1	<0.1	false alarm	
		unsafe	0.1	<0.1	<0.1	
	repeat	safe	0.1	timeout	false alarm	0.1
		unsafe	<0.1	0.4	<0.1	<0.1
swap-dec	base	safe	<0.1	<0.1	false alarm	<0.1
		unsafe	0.1	timeout	<0.1	<0.1
	base/3	safe	0.2	timeout	false alarm	<0.1
		unsafe	0.4	0.9	<0.1	0.1
	exact	safe	0.1	0.5	false alarm	timeout
		unsafe	<0.1	26.0	<0.1	<0.1
	exact/3	safe	timeout	timeout	false alarm	false alarm
		unsafe	<0.1	0.4	<0.1	<0.1

just-rec	base	safe	<0.1	<0.1	<0.1
		unsafe	<0.1	0.1	<0.1
linger-dec	base	safe	<0.1	<0.1	false alarm
		unsafe	<0.1	0.1	<0.1
	base/3	safe	<0.1	<0.1	false alarm
		unsafe	<0.1	7.0	<0.1
	exact	safe	<0.1	<0.1	false alarm
		unsafe	<0.1	0.2	<0.1
exact/3	safe	<0.1	<0.1	false alarm	
	unsafe	<0.1	0.6	<0.1	
lists	append	safe	tool error	<0.1	false alarm
		unsafe	tool error	0.2	0.1
	inc-all	safe	tool error	<0.1	false alarm
		unsafe	tool error	0.3	<0.1
	inc-some	safe	tool error	<0.1	false alarm
		unsafe	tool error	0.3	0.1
inc-some/2	safe	tool error	timeout	false alarm	
	unsafe	tool error	0.3	0.4	
trees	append-t	safe	tool error	<0.1	timeout
		unsafe	tool error	0.3	0.1
	inc-all-t	safe	tool error	timeout	timeout
		unsafe	tool error	0.1	<0.1
	inc-some-t	safe	tool error	timeout	timeout
		unsafe	tool error	0.3	0.1
inc-some/2-t	safe	tool error	timeout	false alarm	
	unsafe	tool error	0.4	0.1	

**Table 1.** Benchmarks and experimental results on RustHorn and SeaHorn, with Spacer/Z3 and HoIce. “timeout” denotes timeout of 180 seconds; “false alarm” means reporting ‘unsafe’ for a safe program; “tool error” is a tool error of Spacer, which currently does not deal with recursive types well.

- RustHorn+Holce handles **recursive data types** quite well
- The output of RustHorn is **very reliable**
- RustHorn is well **comparable** to SeaHorn in performance

# Conclusion

- **Novel translation** from **Rust** programs to CHCs
  - Models a **mutable reference** as a pair of the current value and the **future value**, reminiscent of a **prophecy variable**
  - **Applicable to a wide class** of Rust programs
  - We formalized and proved its correctness and confirmed the effectiveness by experiments

We believe that this work establishes the foundation of **verification leveraging borrow-based ownership**.